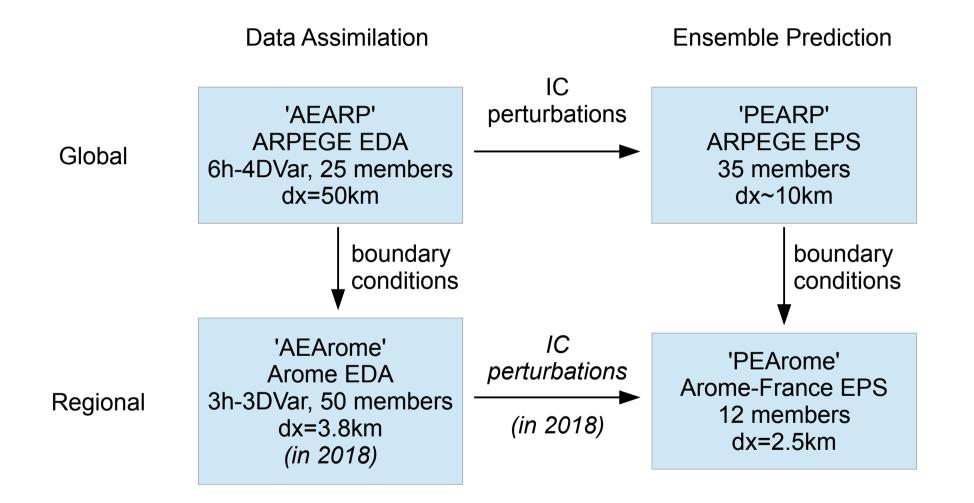
Ensemble model error at Météo-France

François Bouttier and many colleagues - Sept 2017

- Ensemble Data Assimilations
- Global Arpege-EPS (PEARP)
- Regional Arome-France-EPS
- Diagnosing model error



Ensembles at MF

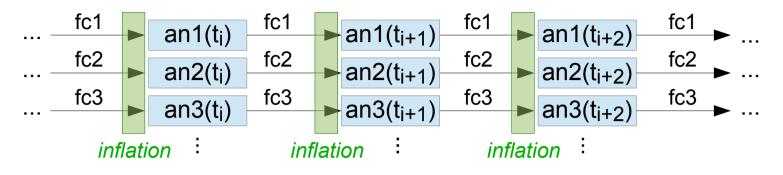




EC seminar 2/23

I. EDAs at MF (global and regional)

(see also talk by L. Raynaud)



Principle :

- n instances of same full fledged data assimilation system
- each one leads its (nearly) own life = full nonlinear error cycling

Perturbations :

- random noise on observations
- surface (through surface obs perturbations to be replaced by direct perts.)

Model error scheme : *adaptive inflation*

- on each cycle, diagnose ensemble spread-skill consistency
- multiplicative inflation of first-guess perturbations :

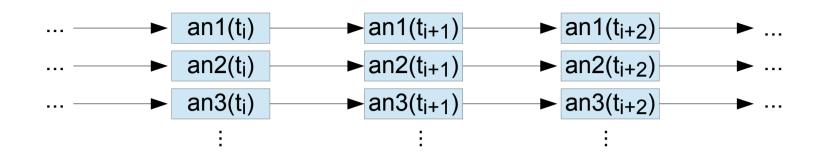
 $x_i = \overline{x} + \alpha (x_i - \overline{x})$ (i = member index)



EC seminar

3/23

EDAs at MF : model error by inflation



In practice, the inflation compensates EDA lack of spread :

- AEARP : 6-hourly inflation factor ~20%
- AEArome : 3-hourly inflation factor ~10%

Why do we need inflation ?

- forecasts lack model error spread
- analysis steps lack representation of *analysis error* sources :
 - not all analysis errors come from obs errors
 - obs errors likely contain correlated errors e.g. uncorrected forward operator biases
 - unresolved analysis scales
- likely mechanisms :
 - too smooth background structure functions \rightarrow lack of small-scale errors
 - multivariate J_b cross-correlations are regressions → need to add the unexplained variance

EC seminar 5/23

II. global ARPEGE EPS configuration 'PEARP' = Prévision d'Ensemble modèle ARPÈGE

(see also MF poster)

Principle :

- 4.5-day range issued at 6 & 18utc (to avoid overloading computer around 00/12utc)
- 34 undistinguishable perturbed members
- 1 'control member' (= operational deterministic model except resolution : 10kmL90 instead of 7.5kmL105)

Perturbations : (ref : Descamps et al, QJRMS 2015)

- initial : combination of EDA & Singular Vector perturbations
- SVs are tuned for short ranges (18-h optimisation), some target cyclonic areas
- surface : not yet perturbed

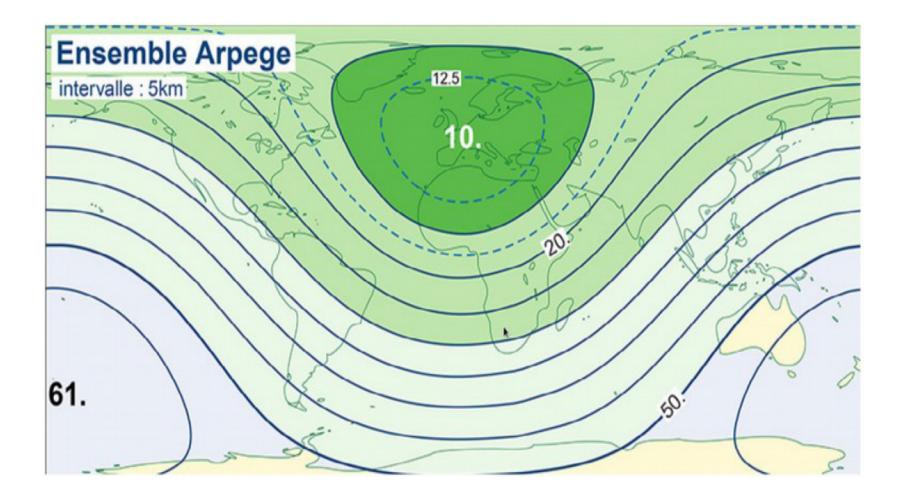
Model error scheme : *multiphysics*

- one single dynamical core
- random draws from 10 different physical parametrisation packages
- packages include current deterministic model and its previous versions
- adds significant spread, mainly through varying systematic errors



ARPEGE-EPS model geometry

Variable horizontal resolution, so conceptually both a global and regional ensemble.





EC seminar 6/23

FRANCE

ARPEGE EPS model error : multiphysics

The 35 member physics are drawn from 10 possible physics combinations. *Differences* with respect to operational physics :

physics index	turbulence	convection	other
0	-	-	-
1	Louis	-	ECUME sea flux
2	Louis	KFB	-
3	Louis	KFB + CAPE closure	-
4	non-advective TKE	PCMT	-
5	-	EDKF	-
6	-	PCMT + EDKF	-
7	-	PCMT + KFB	-
8	-	PCMT	-
9	-	-	modified GWD

KFB = shallow Kain-Fritsch-BechtoldEDKF = eddy-diffusivity Kain-FritschPCMT = Prognostic Convection/Microphysics/TurbulenceTKE=Turbulent Kinetic EnergyGWD = gravity wave drag

(+ multiple radiation & cloud schemes in 2018)

Comparing global model error schemes with other centres

(info not necessarily up to date ; ensemble DAs are not mentioned)

- BMRC (Australia until 2010), CMA, CPTEC : no model error
- ECMWF : SPPT + SKEB (stochastic error backscatter) in atmosphere only
- JMA (Japan): SPPT
- UKMO, KMA (S Korea): random parameters + SCV (stochastic convective vorticity, similar to SKEB)
- MF (France): multiphysics
- MSC (Canada) : multiphysics + SPPT + SKEB
- NCEP (USA): STTP (stochastic total perturbation scheme, similar to SPPT)



FC seminar

8/23



ARPEGE EPS model error : tests and plans

EC seminar 9/23

SKEB :

• tested, not much improvement

SPPT :

- tested, not much improvement
- frequent model crashes with strong SPPT tunings = touchy MF physics

plans :

- use ECMWF's SPP for ARPEGE-physics-specific parameters
- get rid of multiphysics (tedious maintenance work)



III. Regional AROME-France-EPS

in operational production since Oct 2016

2017 operational setup :

- model : AROME-France, dx=2.5km (dx=1.3km in AROME-F déterministic) grid=750x800, 90 levels
- base : 9/21utc (coupling is 3h older)
- production : 12 members up to 45h range
- (no lagged product generation)

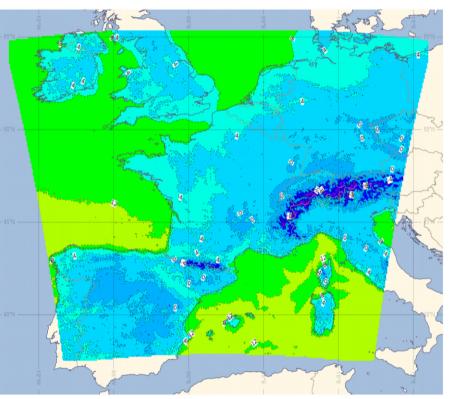
Perturbations :

- lateral boundaries: clustered global PEARP ensemble
- initial: global PEARP ensemble + centering on 3DVar analysis of AROME-France (dx=1.3km)
- surface: initial & constant perturbations
- model: stochastic perturbations of physics tendencies (SPPT)

Plans (2018):

- 6-hourly productions
- ensemble data analysis (EDA) initial perturbations

AROME-France-EPS domain







EC seminar 10/23

AROME static surface-model perturbations

'Static' model error scheme : Random space-correlated error patterns are added/multiplied to surface fields at initial time :

Initial perturbations, short-lived : (t ~1 day)

- top soil T and water content
- snow depth

Initial perturbations, long-lived : (t ~several days)

• deep soil T and water content

Initial perturbations, constant :

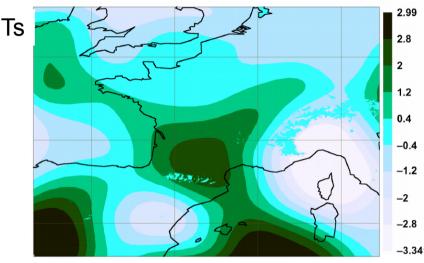
- SST
- sea surface fluxes
- vegetation index, heat coeff, leaf area index
- land albedo, roughness length

Persistent surface perturbations are equivalent to a multiphysics (multiparameter) scheme.

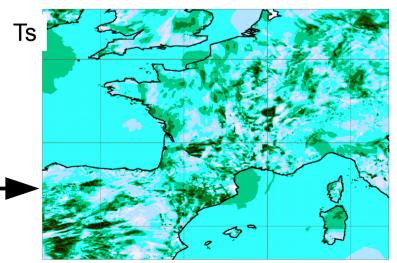
Results :

- improves low-level spread of T, HU, wind)
- Most of the impact comes from SST, soil water & temperature.

Future : mix with EDA-generated perturbations



(Bouttier et al 2015)



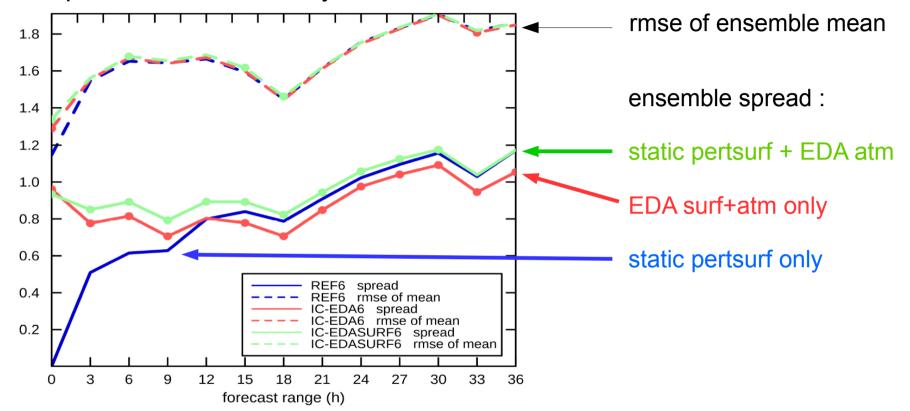


EC seminar 11/23

AROME surface-model perturbations : static vs EDA

EC seminar 12/23

Impact on spread-skill consistency :



EDA ICs good at short ranges, but miss long-lived surface errors.

Static surface-model perturbations alone take time to influence the atmosphere.

The best is a mix of both.

(Ideally, EDA needs a surface perturbation scheme, but long-term surface stability is an issue)

AROME-EPS : atmospheric SPPT

Model error scheme adapted from ECMWF SPPT : (Palmer et al 2009)

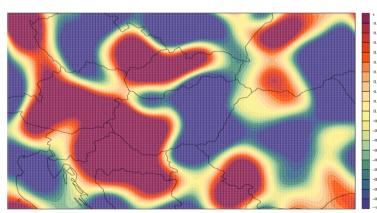
 $dx_i / dt = DYN(x_i) + (1 + \alpha r_i) PHY(x_i)$

where :

- is the model state, member i
- DYN = dynamical tendencies
- PHY = physical tendencies
- α = static vertical profile (damping at bottom & top of troposphere)
- r_i = 2D random error pattern
 - correlated in space & time (separable, prescribed correlations)
 - truncated Gaussian PDF at each point (prescribed std.dev and limiter)
 - same for model variables (U, V, T, Qv) (TKE and condensed water are not perturbed)

Main differences with ECMWF :

- quasi-Gaussian horizontal correlations (2D bi-Fourier spectral pattern generator)
- only 1 pattern (3 at ECMWF)
- no supersaturation limiter



EC seminar 13/23

(M. Szucs, Hungarian Met Service)

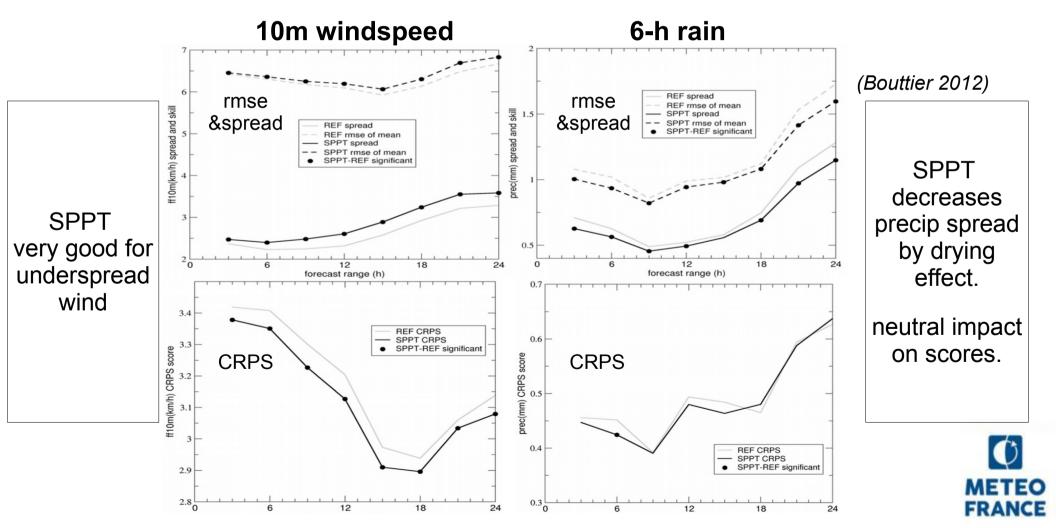
CLSTEMPERATURE 2015/08/18 z18:00 Initialized

AROME-EPS SPPT impact

EC seminar 14/23

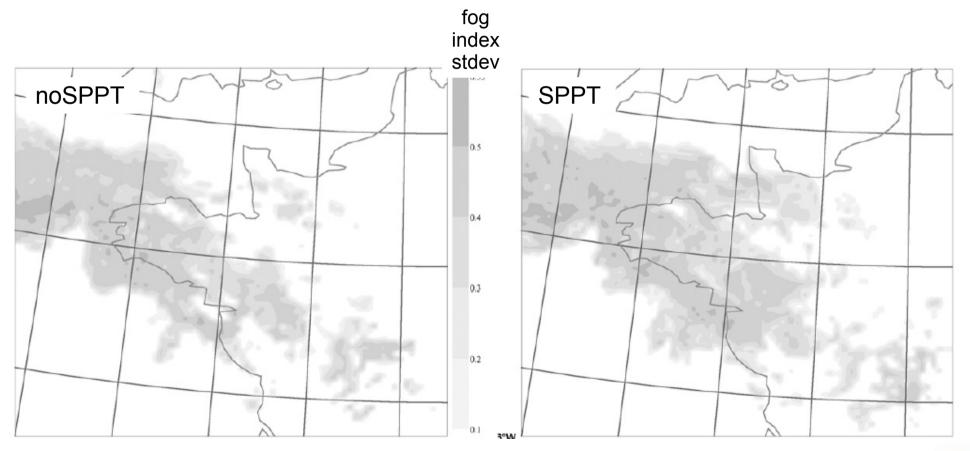
- adds beneficial spread to low-level T, HU, wind, cloudiness
- small but robust improvement of performance measures (Brier, ROC, etc)
- mostly neutral impact on precip, undesirable drying effect

caveat : 'in an underdispersive ensemble, anything that adds spread will improve scores'



AROME-EPS SPPT impact

- the SPPT-induced spread propagates to non-perturbed parameters like cloud and fog
- discourages on/off behaviour : we put the model into states not necessarily allowed by its original design.



In this case, SPPT 'spreads out' nonzero fog probabilities over a wider area.



AROME-EPS SPPT comments

Experimental results : (by L. Raynaud, M. Szucs, ALADIN/HIRLAM/SRNWP partners)

- weak sensitivity to choice of correlations
- the drying effect :
 - is poorly understood
 - is an issue for the detection of high precip events
 - can be partly alleviated by a better supersaturation treatment
- iSPPT (zero or partial correlations between U V T Qv variables perts.) improves the results
- the model can sometimes **crash** if SPPT is too strong :
 - in thunderstorm situations, blow-ups at low model levels
 - alleviated by reducing the SPPT amplitude and disabling it in the PBL (boundary layer)

Current formulation fails to generate enough spread for some processes :

- rain/snow transition
- fog location & timing
- low-level windspeed is much underdispersive



EC seminar 16/23

AROME-EPS SPPT future directions

- extend SPPT to PBL dynamics and microphysical aspects
- improve diagnostics of model error (to avoid confusing it with lack of IC / LBC perturbations)



IV. Diagnosing model error

What do we call 'model error' ?

- 1) errors in the existing model processes
- 2) subgrid-scale errors we know about
- 3) errors we do not know about

Physics perturbations may account for types 1 & 2, but probably not 3 because they restrict themselves to a predefined model architecture.

How can we design perturbations relating to type-3 errors ? We need to **characterize 'missing' ensemble spread** using observations.

Naive method : boost already implemented perturbation sources, until spread is consistent (on average) with skill.

e.g. var(model error) = var(ens. mean error) - spread

Problem : we may produce unphysical spread by boosting the wrong kind of perturbation (e.g. spread of initial conditions)



EC seminar 18/23

Diagnosing model error : scale dependency

EC seminar 19/23

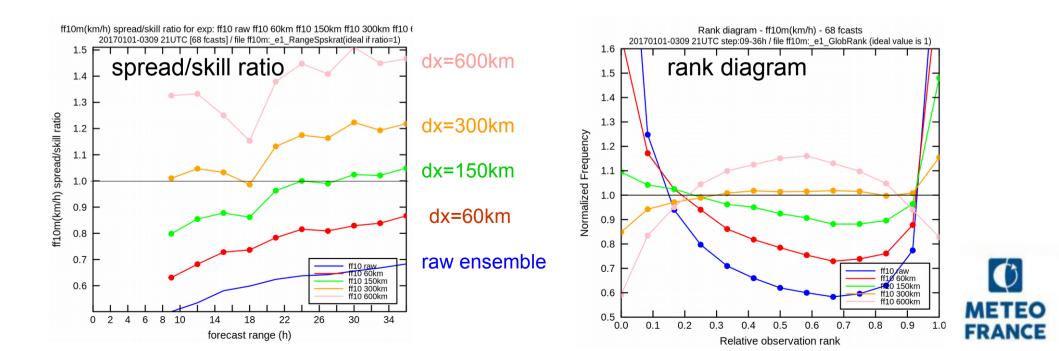
Example : 10m windspeed in Arome-France-EPS wrt in-situ obs :

- · conventional spread/skill diags indicate the ensemble lacks spread
- not a trivial model bias or obs error problem

Let us **upscale the verification** by smoothing both obs and model output : the obs network geometry allows smoothing at scales dx=30 to 600km

Probabilistic scores are computed on increasingly large scales (see also the Fractions Skill Score by Roberts & Lean 2008 etc.) over 68 winter days

The ensemble is overdispersive at scales >200km : spread is lost in the local adaptation of synoptic features

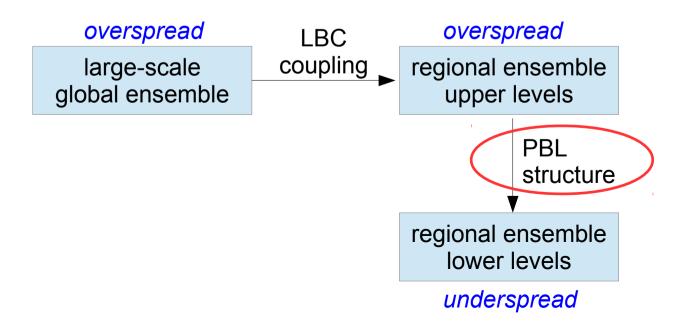


Diagnosing model error : scale dependency

Tentative physical interpretation :

- large-scale LAM upper-level wind is tightly driven by a global ensemble (PEARP) that is similarly overdispersive.
- small-scale, low-level wind lacks spread because some wind error sources are missing
 - in the large-scale -> small-scale energy cascade (unlikely : model dynamics are fairly good at these scales)
 - or, in the high -> low level wind transition : missing model error representation in the PBL ? (not solved by simple perturbations of physics parameters)

In this situation, increasing synoptic-scale ensemble spread would improve SYNOPbased point probabilistic scores for the wrong reasons.





Diagnosing model error in 'easy' conditions

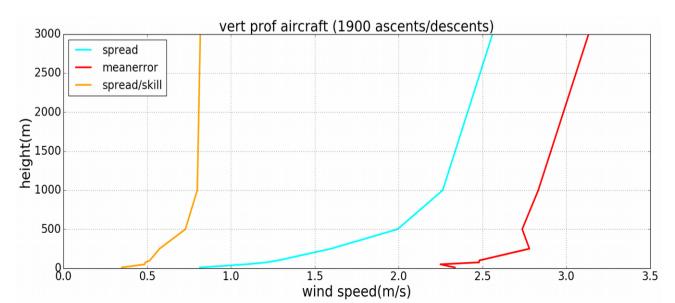
Can we locate missing ensemble perturbations by locating *sinks of spread*? assuming a simple chain of events : obs



Study : windspeed in neutral PBLs, using aircraft ascents/descents

- model & obs biases are small
- wind is driven by current upper-level conditions
- spread/skill ratio collapses near the surface, suggesting the ensemble lacks representation of a specific uncertainty source in the PBL.

Usually, several sources of spread interact, making it difficult to tune model error schemes.



(see also Berner et al 2016, MWR 143-1295)



EC seminar 21/23



Summary & Outlook

- diversity of model error strategies in interconnected systems (EDAs, largescale and fine-scale ensemble)
- each one is clearly beneficial, but they could be made more consistent to ease maintenance (e.g. SPP / SPPT in all systems) and reduce risks of overcompensating some error sources by others

Future priorities :

- **develop** clearly missing model perturbations (surface pert. in EDA, perturbed parametrisations in ARPEGE & AROME models)
- minimise complexity : identify & treat the most uncertain processes (rain/snow transition, cloudiness, fog extent, dynamics...)
- **improve model tolerance to perturbations :** numerical blow-ups and ensemble-specific biases (eg SPPT drying)



EC seminar 22/23



EC seminar 23/23

Thanks for your attention

Questions ?

