Stochastic methods for representing atmospheric model uncertainties in ECMWF's IFS model

Sarah-Jane Lock

Model Uncertainty, Research Department, ECMWF

With thanks to Martin Leutbecher, Simon Lang, Pirkka Ollinaho



© ECMWF September 12, 2017

Some background: ensemble reliability

• In a reliable ensemble, ensemble spread is a predictor of ensemble error



- Ensemble member
- Ensemble mean
- Observation

i.e. averaged over many ensemble forecasts,

$$e(\bar{x}) \approx \sigma(x)$$

CECMWF

Some background: ensemble reliability

• In an over-dispersive ensemble,

 $e(\bar{x}) \ll \sigma(x)$



- Ensemble member
- Ensemble mean
- Observation

and ensemble spread does not provide a good estimate of error.

The relatively large spread implies large uncertainty and hence, likely large error:

an "under-confident forecast"



Some background: ensemble reliability

• In an under-dispersive ensemble,

 $e(\bar{x}) \gg \sigma(x)$



- Ensemble member
- Ensemble mean
- Observation

The small spread implies low uncertainty and hence, small errors:

an "over-confident forecast"

What happens when there is no representation of model uncertainty in our ensemble?



Ensemble forecasts with only initial conditions perturbations

Ensemble mean RMSE ("Error") & standard deviation ("Spread")



When only initial uncertainty is represented in the forecast ...







Uncertainties arise due to:

- Inability to resolve sub-grid scales
 - Surface drag (orography/waves)
 - Convection rates (occurrence / en-/detrainment)
 - Phase transitions
 - Radiation transfer in cloudy skies
- Poorly constrained parameters or processes
 - cloud-water distribution (radiation)
 - Composition
 - Non-orographic drag



Parametrisation schemes:

- developed & operate together
- highly tuned for best performance

Seek a description of uncertainty that retains consistencies of the representation of the physical processes.









CECMWF

When the forecast also includes a representation of model uncertainty ...



Recall: Ensemble forecasts: with initial conditions perturbations (IP) only

Ensemble mean RMSE ("Error") & standard deviation ("Spread")



Ensemble forecasts: with grid-scale model uncertainty perturbations (SPPT)

Ensemble mean RMSE ("Error") & standard deviation ("Spread")



Ensemble forecasts: with static model uncertainty perturbations (SPPT)

Ensemble mean RMSE ("Error") & standard deviation ("Spread")



Stochastically Perturbed Parametrisation Tendencies (SPPT) scheme

- Used in IFS ensemble forecasts and ensemble of data assimilations
- Initially implemented in IFS, 1998 (Buizza et al., 1999; Palmer et al., 2009; Shutts et al., 2011)





- Column of net tendencies from parametrised atmospheric physical processes multiplied with a 2D random field
- Multi-scale pattern: largest/slowest scale with least variance
- Perturbations are tapered (μ) to zero in the stratosphere and near the lower boundary

Ensemble forecasts: with multi-scale model uncertainty perturbations (SPPT)

Ensemble mean RMSE ("Error") & standard deviation ("Spread")



Include model uncertainty perturbations via SPPT: X' = (1 + r)X

where the noise term

$$r = r(x,t)$$

- 1. Includes only shortestscale correlations
- 2. Includes multi-scale correlations

Some additional spread from SPPT3



Ensemble forecasts: with multi-scale model uncertainty perturbations (SPPT)

Probabilistic skill (CRPS) – difference from **SPPT3** with respect to **SPPT1**



Include model uncertainty perturbations via SPPT: X' = (1 + r)X

where the noise term

$$r = r(x,t)$$

- 1. Includes only shortestscale correlations
- 2. Includes multi-scale correlations

Some additional probabilistic skill from SPPT3



Experiment details:

CY43R1

TCo399, dt=900s,

23 dates (2015),

20 perturbed fcs

Stochastic representations of model uncertainty in IFS

IFS ensemble forecasts (ENS and SEAS) include 2 model uncertainty schemes:

- 1. Stochastically perturbed parametrisation tendencies (SPPT) scheme
 - SPPT scheme: simulates model uncertainty due to sub-grid parametrisations
- 2. Stochastic kinetic energy backscatter (SKEB) scheme
 - real world: upscale propagation of kinetic energy (KE) at all scales
 - SKEB simulates upscale propagation from unresolved scales to resolved scales
 - streamfunction is perturbed with noise from a 3D random field, modulated by an estimate of local dissipation rate (Berner et al., 2009; Palmer et al., 2009; Shutts et al., 2011)
 - recent revisions to dissipation rate estimate: now only depends on that due to deep convection

Ensemble forecasts: SPPT & SKEB

Ensemble standard deviation ("Spread") – 200hPa zonal wind (ms⁻¹)



46 dates (2013-2014),

20 perturbed fcs

Ensemble forecasts: SPPT & SKEB

Continuous Ranked Probability Score – 200hPa zonal wind (ms⁻¹)



20 perturbed fcs

Stochastic representations of model uncertainty: looking ahead

EUROPEAN CENTRE FOR MEDIUM-RANGE WEATHER FORECASTS

Towards process-level model uncertainty representation



ECE

- **Aim**: to improve the physical consistency
- Remove ad hoc tapering in boundary layer and stratosphere
- Preserve local energy/moisture budgets through consistent flux perturbations at the upper and lower boundaries
- Represent uncertainty close to assumed sources of errors
- Include multi-variate aspects of uncertainties



Stochastic physics in the IFS: looking ahead

Towards process-level model uncertainty representation



Stochastically Perturbed Parametrisations (SPP)

(Ollinaho et al., 2017, QJRMS)

Parameters/variables within parametrisation schemes are multiplied with noise from a 2D random pattern: $\xi = r\hat{\xi}$

correlated in space (2000 km) and time (72 h).

e.g. convection scheme parameters are perturbed with numbers drawn from distributions shown

Currently: 20 independent perturbations in

parametrisations of sub-grid orography and vertical mixing, radiation, cloud and large-scale precipitation and convection

Stochastically Perturbed Parametrisations (SPP) scheme

Ensemble mean RMSE ("Error") & standard deviation ("Spread")



Include model uncertainty perturbations via

i) SPPT:

$$X' = (1+r)X$$

acting on physics tendencies

ii) SPP:

 $\xi = r\hat{\xi}$

acting on 20 parameters/variables

| Currently, SPP generates less spread (& skill) than SPPT => Some model uncertainty sources missing from SPP |
|---|
|---|

More work to do!

IP only
IP + SPPT
IP + SPP

Experiment details: CY43R1 TCo399, dt=900s, 23 dates (2015), 20 perturbed fcs

A look at the physical tendencies and processes

Ensemble mean of tendencies, 21-24h

Net physics temperature (T) tendencies (K/3h) @ model level 64 (~500 hPa)



From a 20-member ensemble forecast: starting 00:00,10-01-2015





And a look at the tendency perturbations

T tendencies, 21-24h @ model level 64 (~500 hPa)







And a look at the tendency perturbations

T tendencies, 21-24h @ model level 64 (~500 hPa)



From a 20-member ensemble forecast: starting 00:00,10-01-2015 with identical initial conditions





Ensemble mean convective precipitation (mm/3h)

And a look at the tendency perturbations

T tendencies, 21-24h @ model level 64 (~500 hPa)







A look at the physical tendencies and processes (II)

U tendencies, 0-3h @ model level 49 (~200 hPa)







And a look at the tendency perturbations (II)

U tendencies, 0-3h @ model level 49 (~200 hPa)









Stochastic methods for representing atmospheric model uncertainties in ECMWF's IFS model

Present and future – much greater detail and discussion in:

Leutbecher et al., 2017: Stochastic representations of model uncertainties at ECMWF: State of the art and future vision, QJRMS, DOI: 10.1002/qj.3094

Take a look ...

&

thanks for your attention!



© ECMWF September 12, 2017