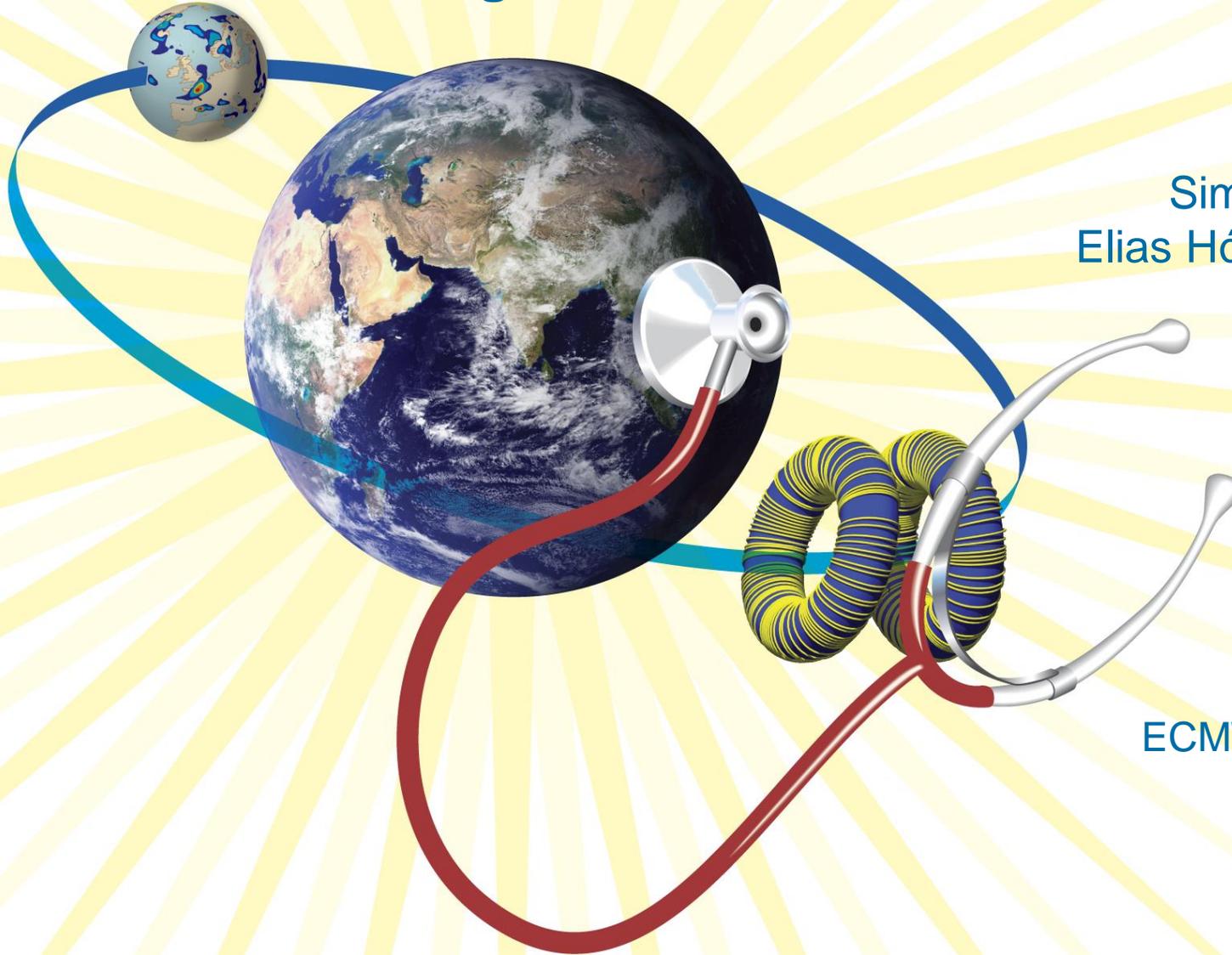


# Using ensemble data assimilation to diagnose model uncertainty



Mark Rodwell

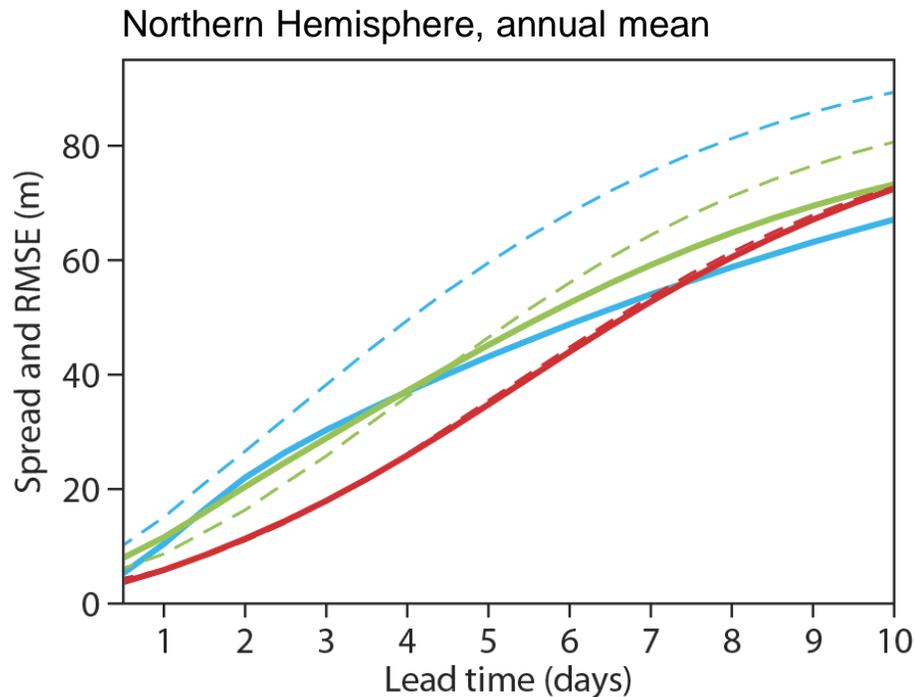
Simon Lang, Bruce Ingleby, Niels Bormann  
Elias Hólm, Florence Rabier, David Richardson,  
Munehiko Yamaguchi

ECMWF/WWRP Workshop on Model Uncertainty

12 April 2016, ECMWF Reading

# Ensemble spread and error

Z500



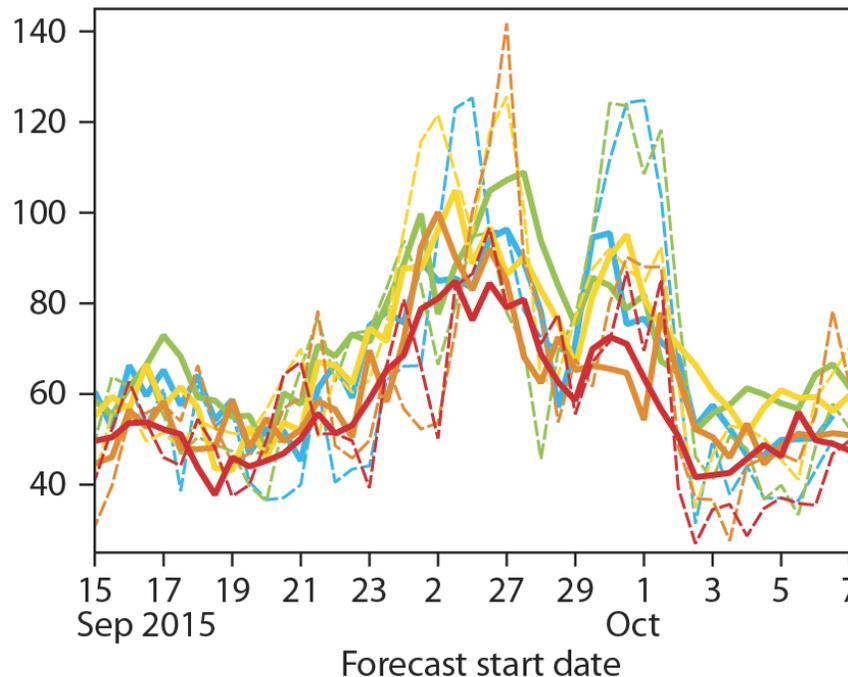
	1996	2005	2014
Spread	<span style="color: blue;">—</span>	<span style="color: green;">—</span>	<span style="color: red;">—</span>
RMSE	<span style="color: blue;">- - -</span>	<span style="color: green;">- - -</span>	<span style="color: red;">- - -</span>

Improvements in sharpness and reliability. Due to:

- Ensemble of data assimilations
- Stochastic physics
- Observations and modelling of observation error

Europe, day 6

Rodwell 2016, ECMWF Newsletter



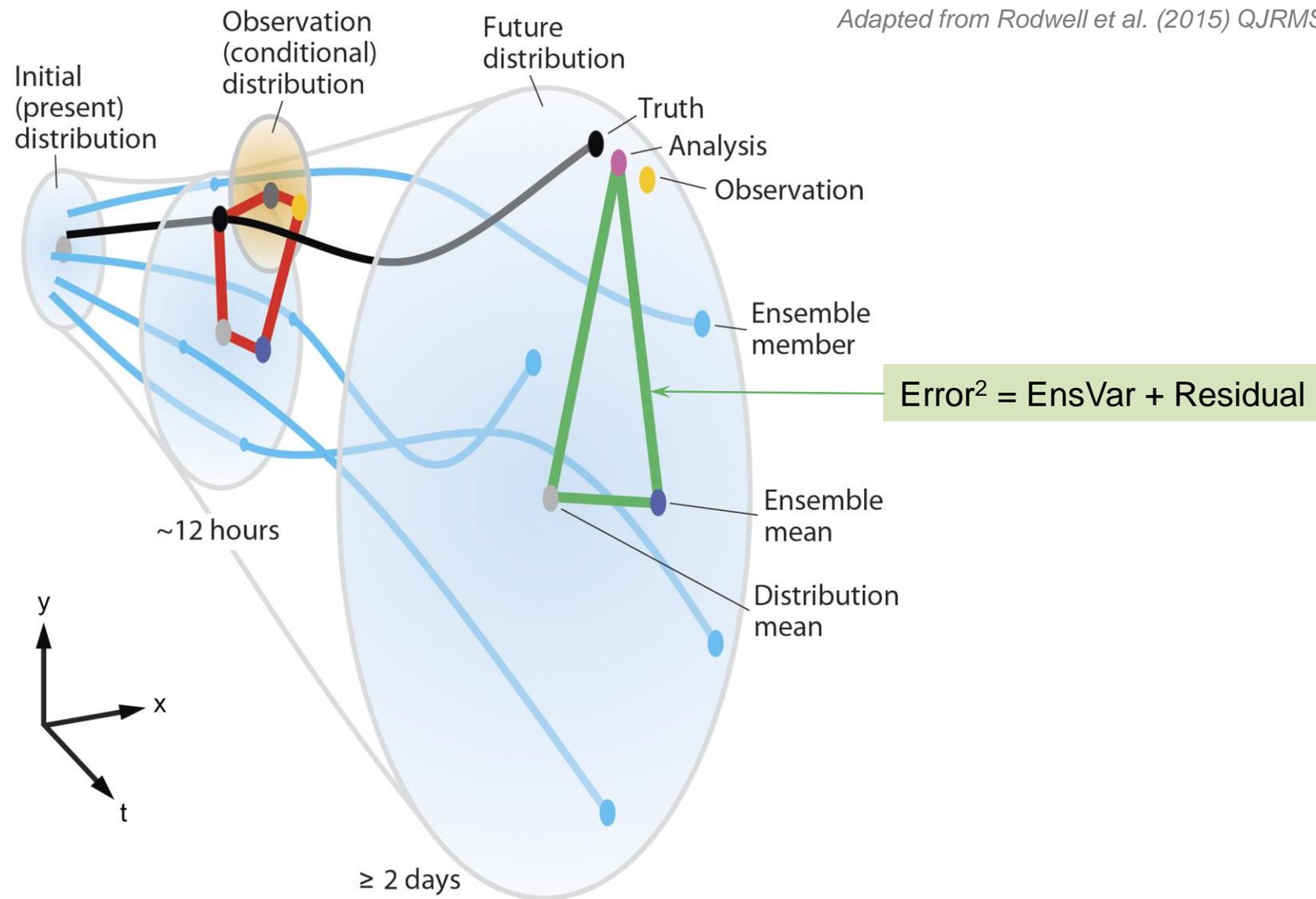
	ECMWF	UKMO	JMA	CMC	NCEP
Spread	<span style="color: red;">—</span>	<span style="color: orange;">—</span>	<span style="color: yellow;">—</span>	<span style="color: green;">—</span>	<span style="color: blue;">—</span>
RMSE	<span style="color: red;">- - -</span>	<span style="color: orange;">- - -</span>	<span style="color: yellow;">- - -</span>	<span style="color: green;">- - -</span>	<span style="color: blue;">- - -</span>

- Spread agreement between centres indicates flow-dependent fluctuations in underlying predictability (reason for ensemble forecasting!)
- Need to assess flow-dependent reliability

500 hPa geopotential height (Z500). RMSE is of ensemble-mean error. Spread = ensemble standard deviation (scaled to take account of finite ensemble size).

# Reliability in ensemble forecasting

Adapted from Rodwell et al. (2015) QJRMS

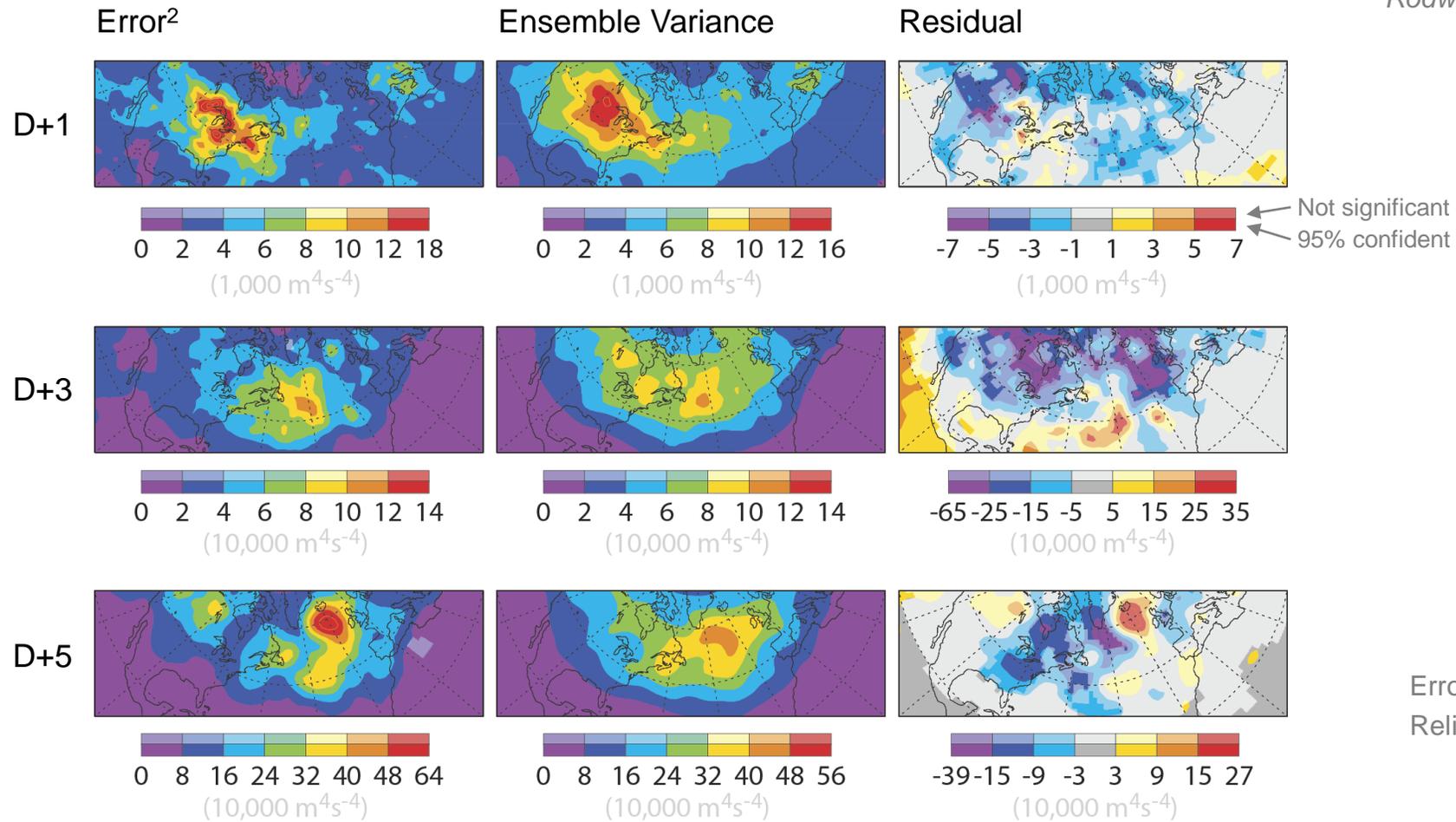


(Cross-terms on squaring have zero expectation. EnsVar is scaled variance to account for finite ensemble-size)

# Composite with North American trough & CAPE ( $\Rightarrow$ Mesoscale convective systems)

Z200, 54 cases

Rodwell 2016, ECMWF Newsletter

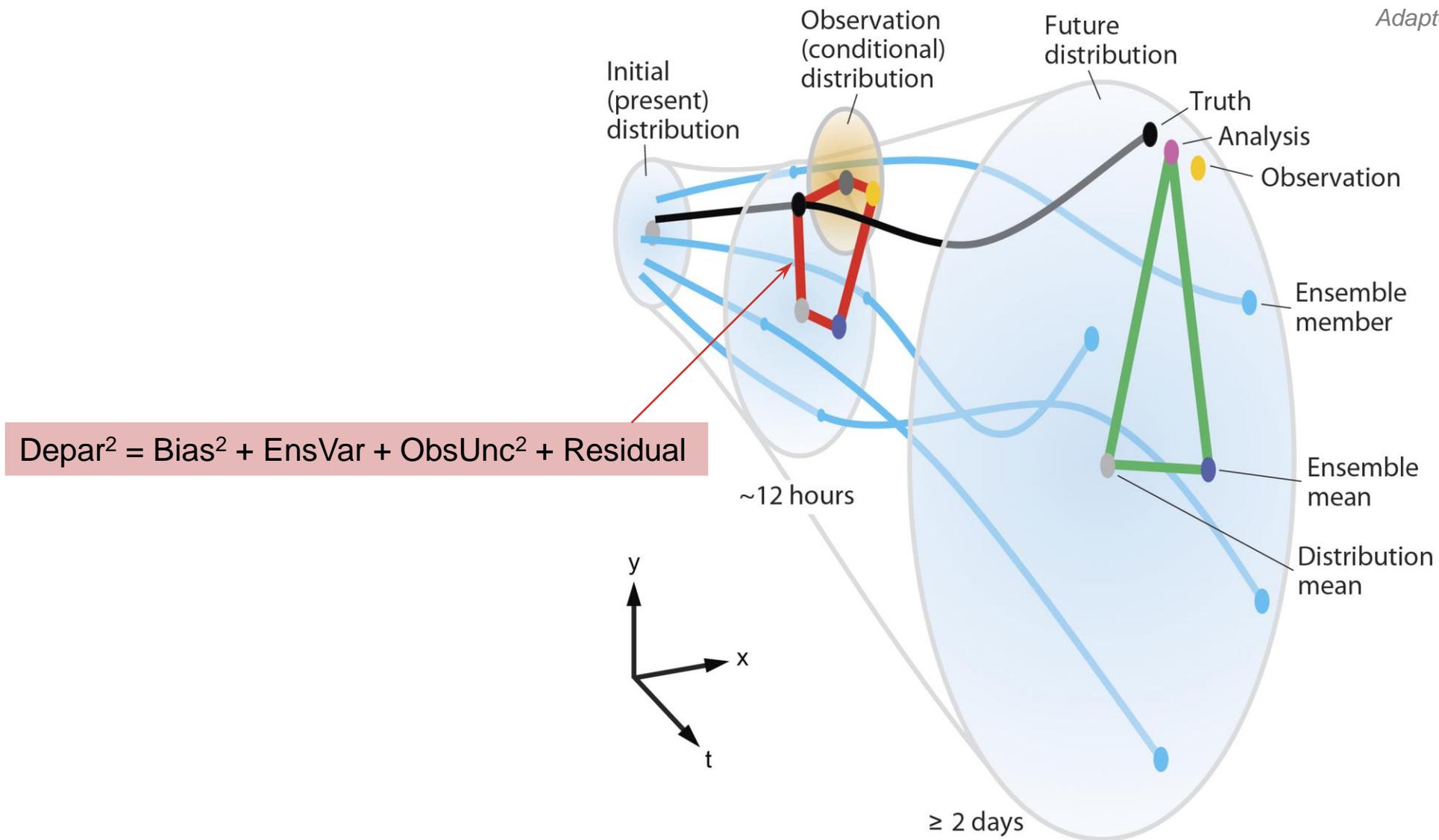


Error<sup>2</sup> = EnsVar + Residual  
Reliability  $\Rightarrow$  E[Residual]=0

- Following conditions conducive to MCS development, enhanced errors and spread propagate east towards Europe  $\rightarrow$  'Busts' ✓
- Note: -ve residuals occur in non-trough/CAPE situation too.
- +ve residual at D+5 is not significant (Chaos?  $\rightarrow$  use bigger sample or shorter leadtime? But analysis uncertainty at D+1?) ✗

# Reliability in ensemble data assimilation

Adapted from Rodwell et al. (2015) QJRMS



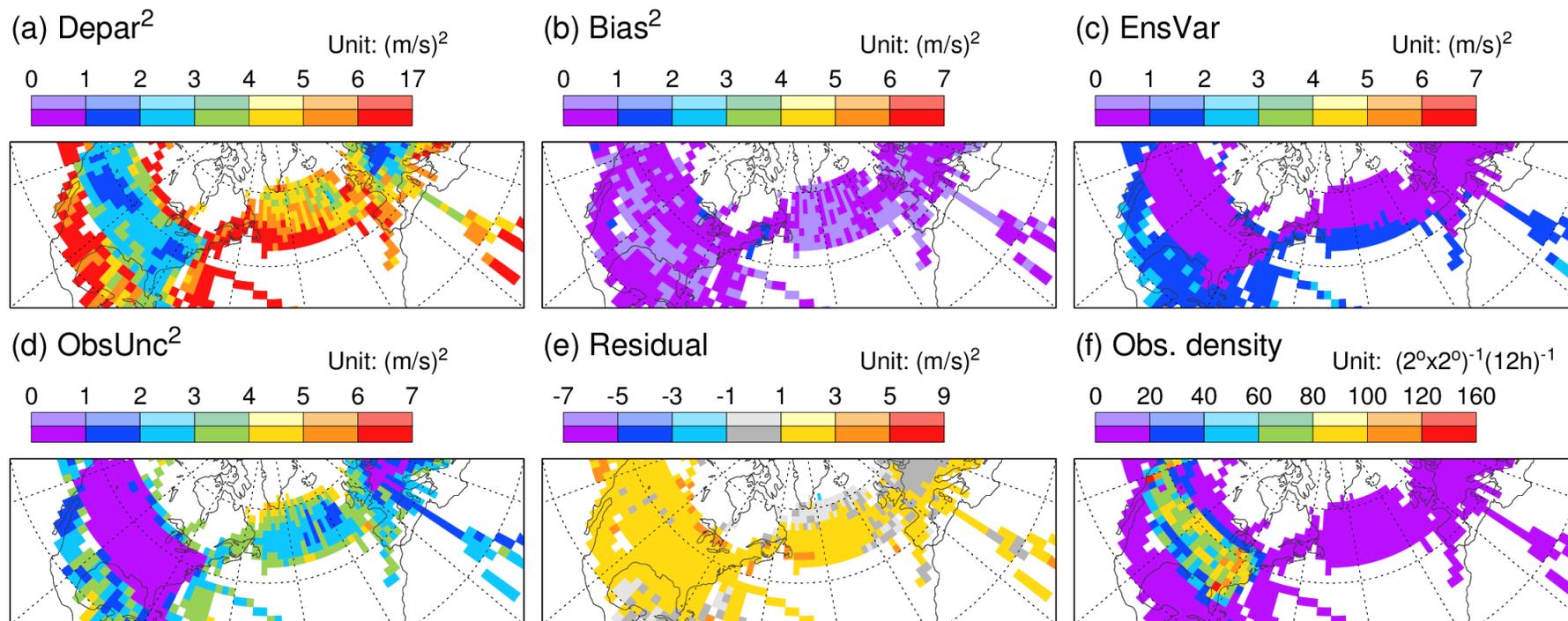
(Cross-terms on squaring have zero expectation. EnsVar is scaled variance to account for finite ensemble-size)

# EDA reliability budget: Non-trough/CAPE comp.

u200, ~1000 cases

Rodwell 2016, ECMWF Newsletter

Relative to aircraft observations of zonal wind 200hPa ( $\pm 15$ )



$$\text{Depar}^2 = \text{Bias}^2 + \text{EnsVar} + \text{ObsUnc}^2 + \text{Residual}$$

Reliability  $\Rightarrow E[\text{Residual}]=0$

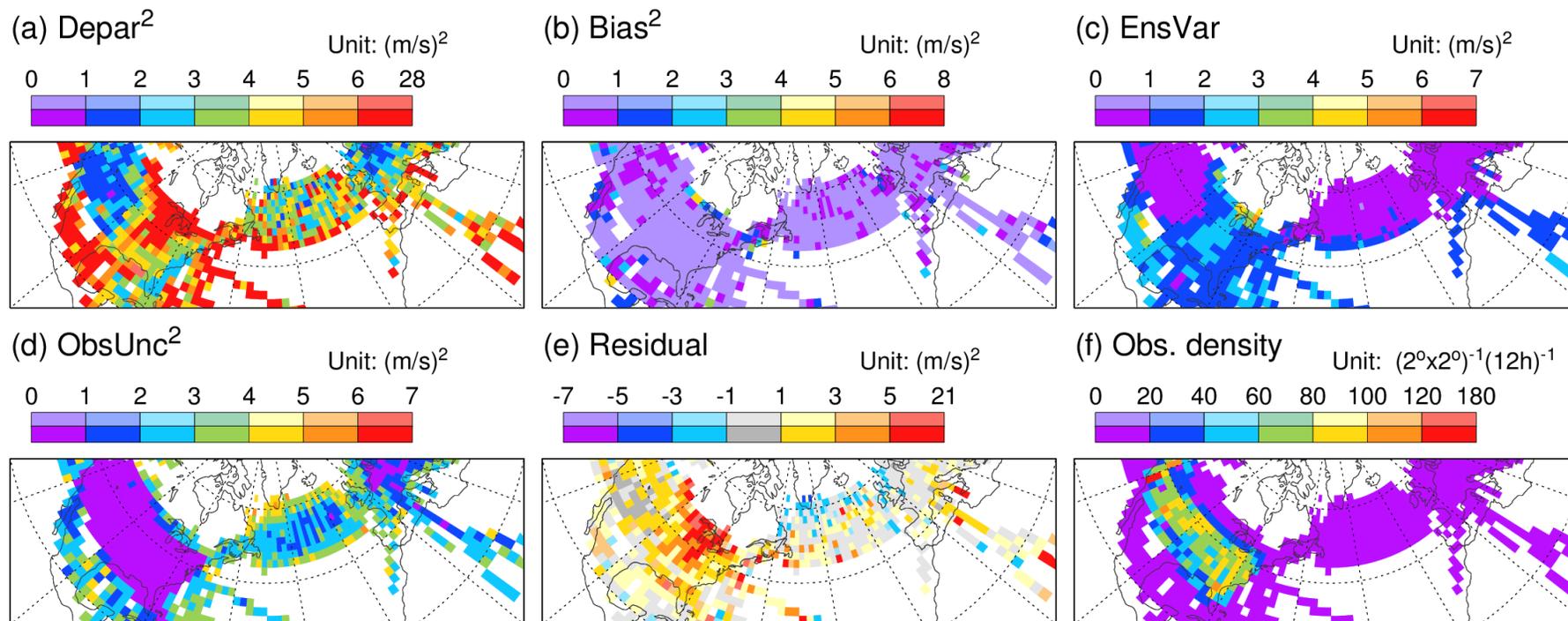
- Residual suggests general underestimation of background variance or observation uncertainty
- Not interested in this here as we are interested in flow-dependent reliability

# EDA reliability budget: Trough/CAPE comp.

u200, 54 cases

Rodwell 2016, ECMWF Newsletter

Relative to aircraft observations of zonal wind 200hPa ( $\pm 15$ )



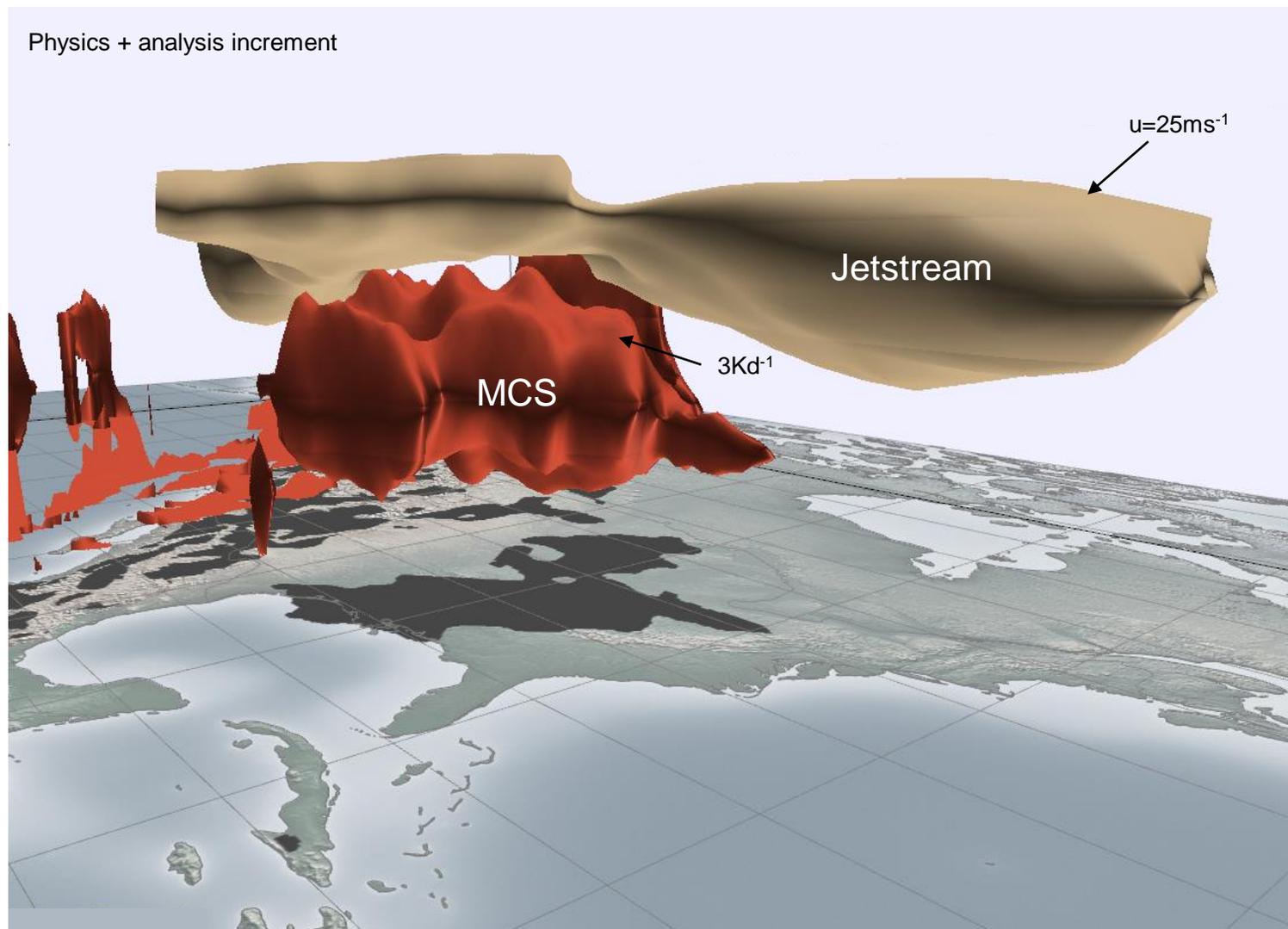
$\text{Depar}^2 = \text{Bias}^2 + \text{EnsVar} + \text{ObsUnc}^2 + \text{Residual}$   
Reliability  $\Rightarrow E[\text{Residual}] = 0$

- **Key result: Residual in trough/CAPE regime highlights MCS, and suggests lack of background variance**
- (Observation uncertainty changes should be a second-order effect for this large-scale wind field)
- One interpretation: The inherent un-predictability of the existence, intensity and location of MCS events is not adequately reflected in Jetstream uncertainty (with downstream consequences)

# A role for systematic model error?

54 cases

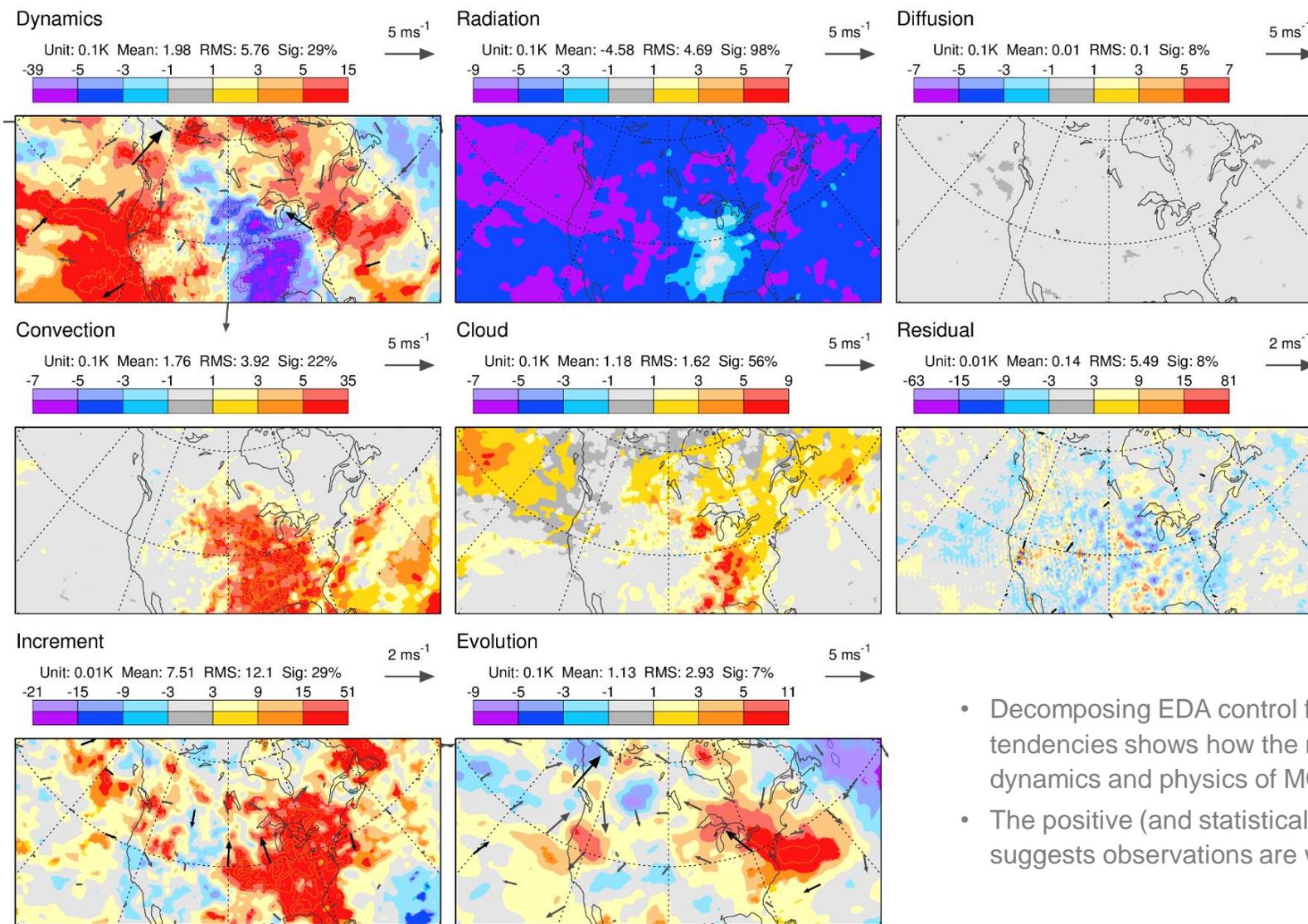
Met3D: Marc Rautenhaus



- Increments highlight a role for model systematic error: MCS does not interact enough with Jetstream
- Also need to strengthen stochastic physics to increase background variance?

# Initial tendency budget from control forecast: Trough/CAPE comp.

T300, 54 cases



- Decomposing EDA control forecast into process tendencies shows how the model represents dynamics and physics of MCS
- The positive (and statistically significant) increment suggests observations are warmer than the model

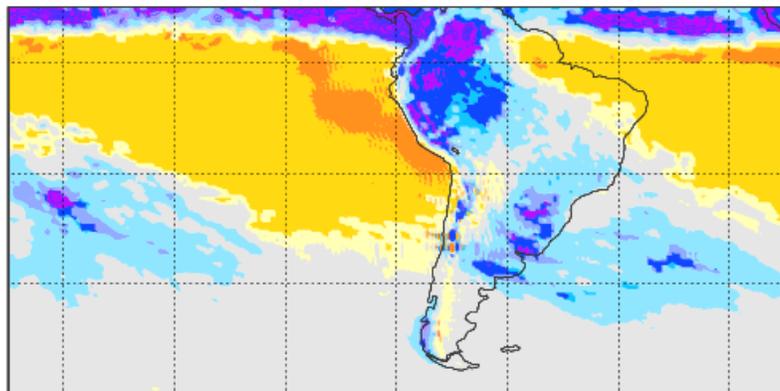
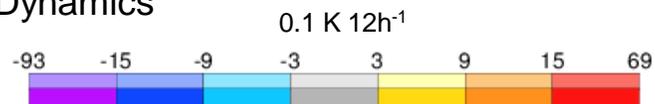
Process tendencies accumulated over 12hr background, the analysis increment, and evolution of the flow



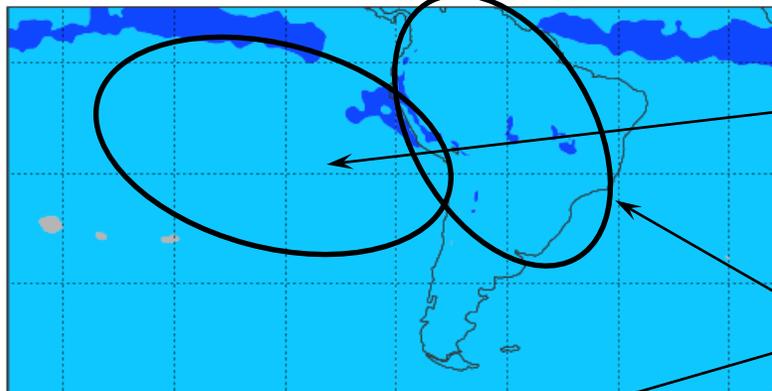
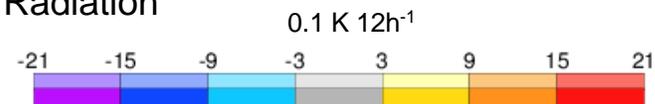
# Initial tendencies from control forecast: SON 2014

T500, SON 2014

Dynamics



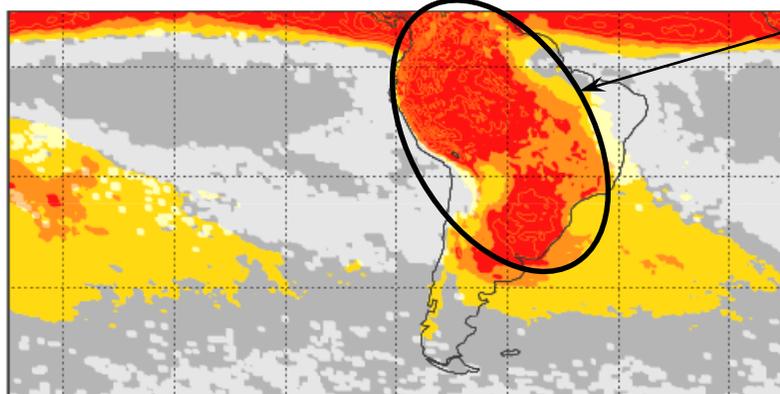
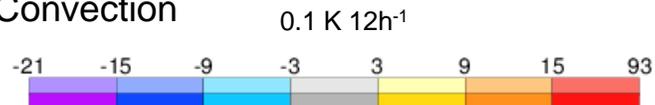
Radiation



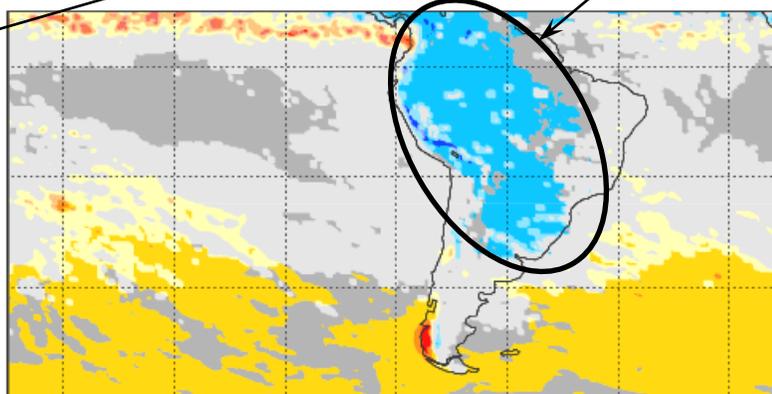
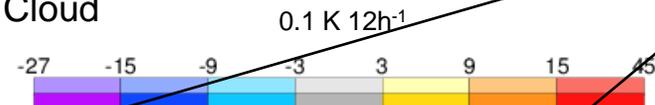
Stoch.Phys.  $\approx \alpha$ Radiation

Stoch.Phys.  $\approx \alpha$ (Radiation + Convection + Cloud)

Convection

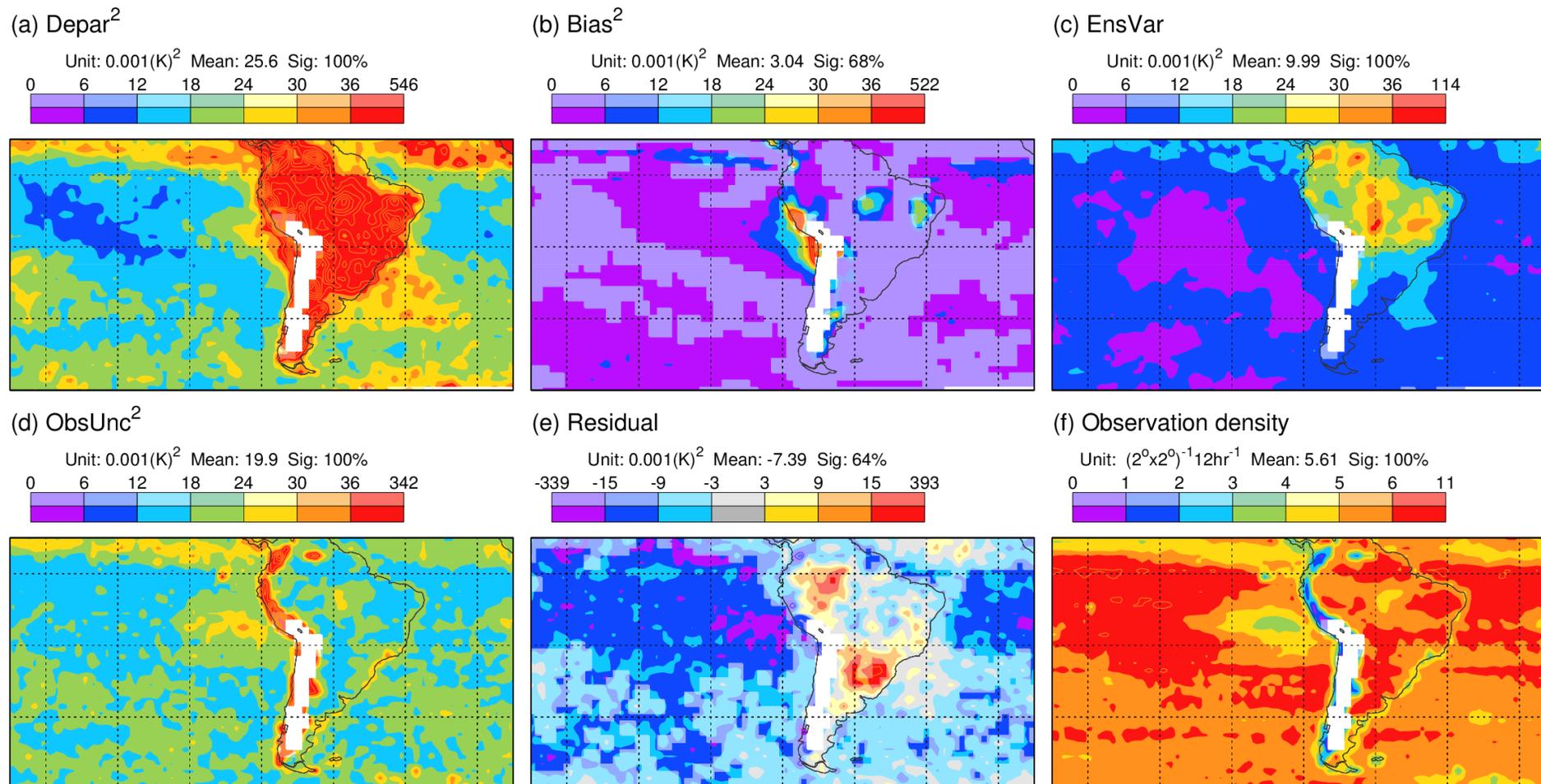


Cloud



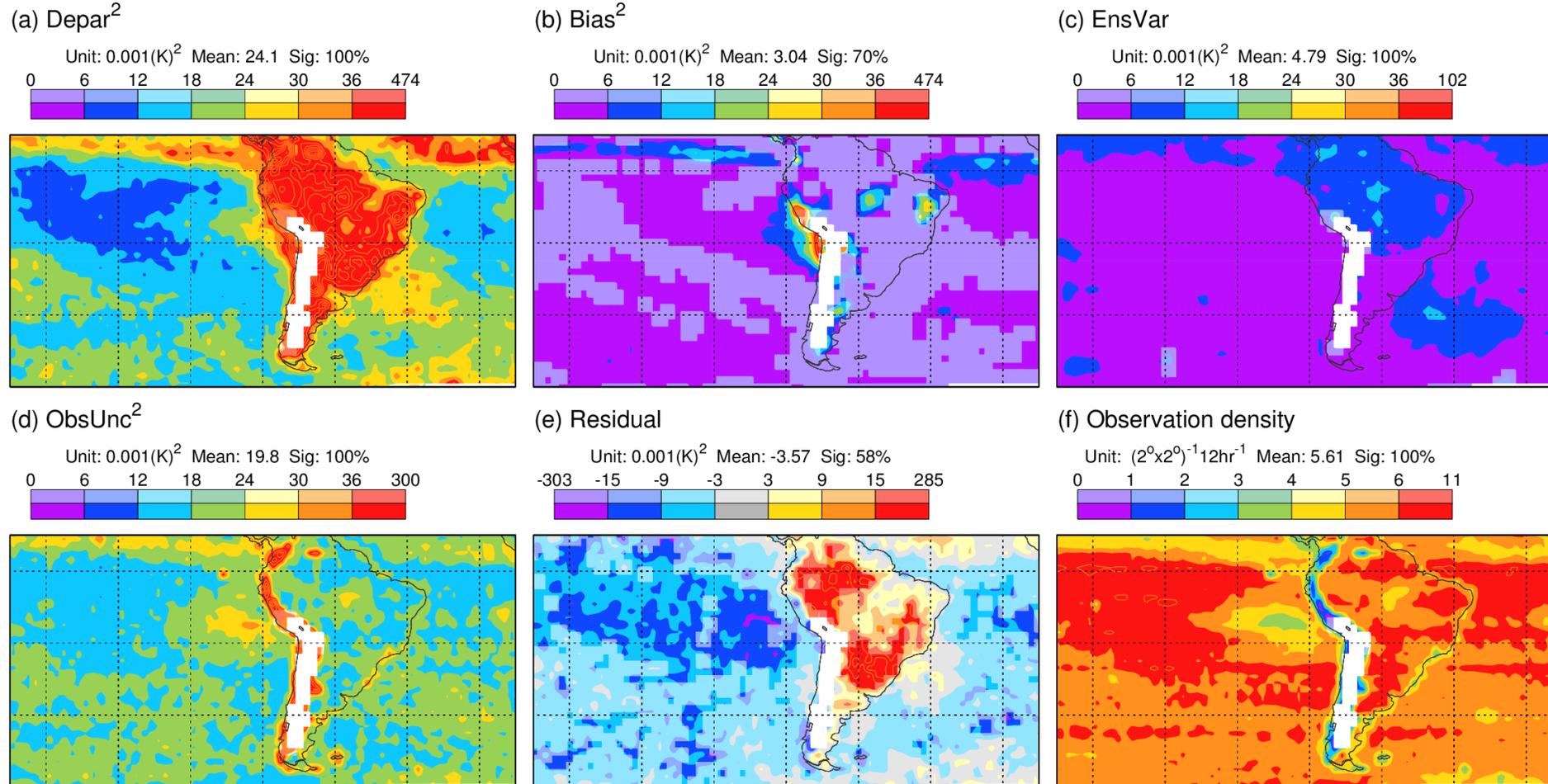
- At ECMWF stochastic physics is largely a multiplicative scaling of the total physics tendency
- Is physics in subtropical anticyclones as uncertain as Stochastic Physics treats it?

Relative to AMSUA channel 5 microwave brightness observations of mid-tropospheric temperature



- Largest departures and ensemble variance in convective regions
- Large bias off west coast (associated with errors in cloud detection?)
- $\text{ObsUnc}^2$  is sometimes larger than  $\text{Depar}^2$  off west coast
- Residual consistent with too much stochastic physics in subtropical anticyclones, too little in convective regions

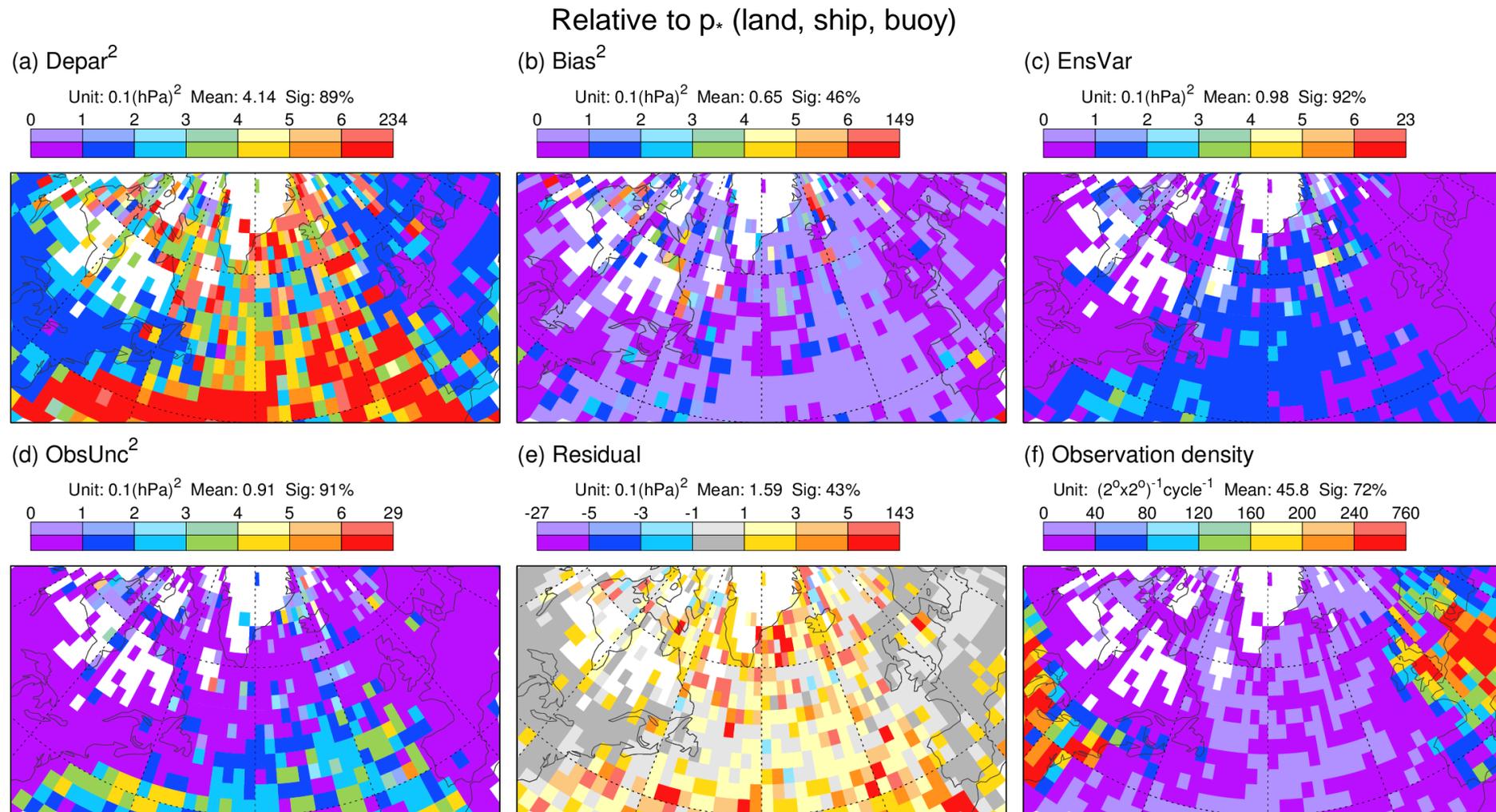
Relative to AMSUA channel 5 microwave brightness observations of mid-tropospheric temperature



- Reduction in ensemble variance
- Improved diagnosed reliability within subtropical anticyclones, but convective regions worse
- **Key result: EDA reliability budget is sensitive to local changes in Stochastic Physics**
- Should help development of stochastically-formulated process parametrizations
- Note that Obs Error assignment also likely to be an issue in this budget

# A role for errors in the modelling of observation uncertainty? (Different situation)

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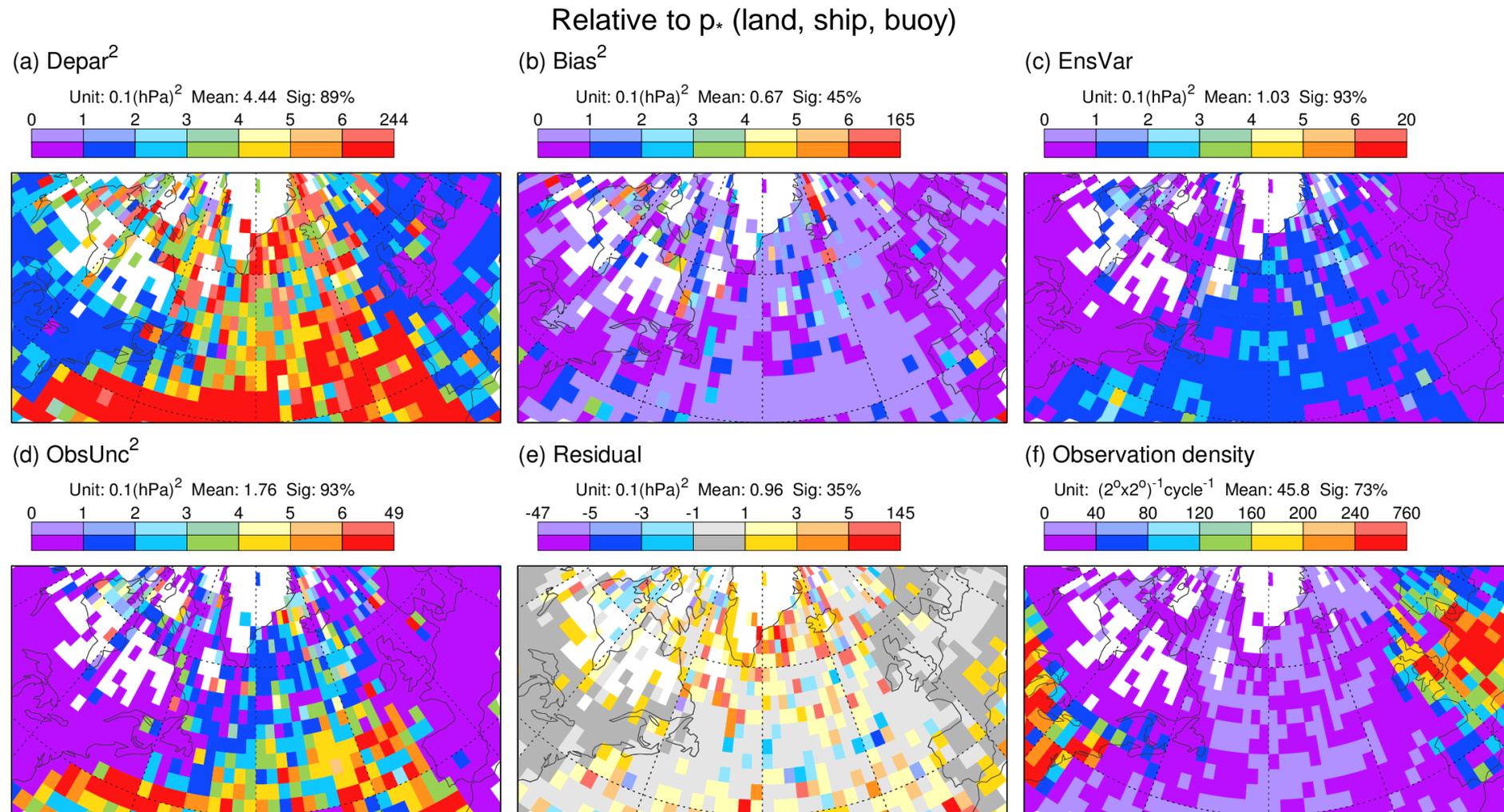


- Marine observation errors not large enough?

Reference experiment (3 members, 20140901-20141130)

# EDA reliability budget: Larger marine Observation Uncertainties

Rodwell et al. (2015) QJRMS



- Larger marine observation errors consistent with better reliability
- Modelling of observation uncertainty and representation of model uncertainty are key to reliability

Perturbed experiment (3 members, 20140901-20141130)

- Difficult to assess flow-dependent reliability in the medium-range
  - Error propagation and interaction means we cannot highlight specific issues
  - Chaos means that large samples are required
- Approach here is to look at short timescales
  - Need to include uncertainty in our knowledge of the truth
  - “EDA reliability budget” (focuses on reliability, not sharpness)
  - **Can assess local and flow-dependent sensitivity to model uncertainty representation**
- Ambiguities with (e.g.) observation error a “mixed blessing”
  - Reliable ensemble initiation requires good modelling of observation error
  - “Desroziers statistics” (etc) can inform on observation errors
  - Initial tendency budget can inform on systematic model errors
- Tool can now be readily applied by developers to the IFS