



# *The impact and importance of GPS - RO in NWP*

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National Centers for Environmental Prediction*

*ECMWF/ EUMETSAT ROM - SAF workshop on  
Applications of GPS radio occultation measurements  
16 to 18 June 2014*



# Outline

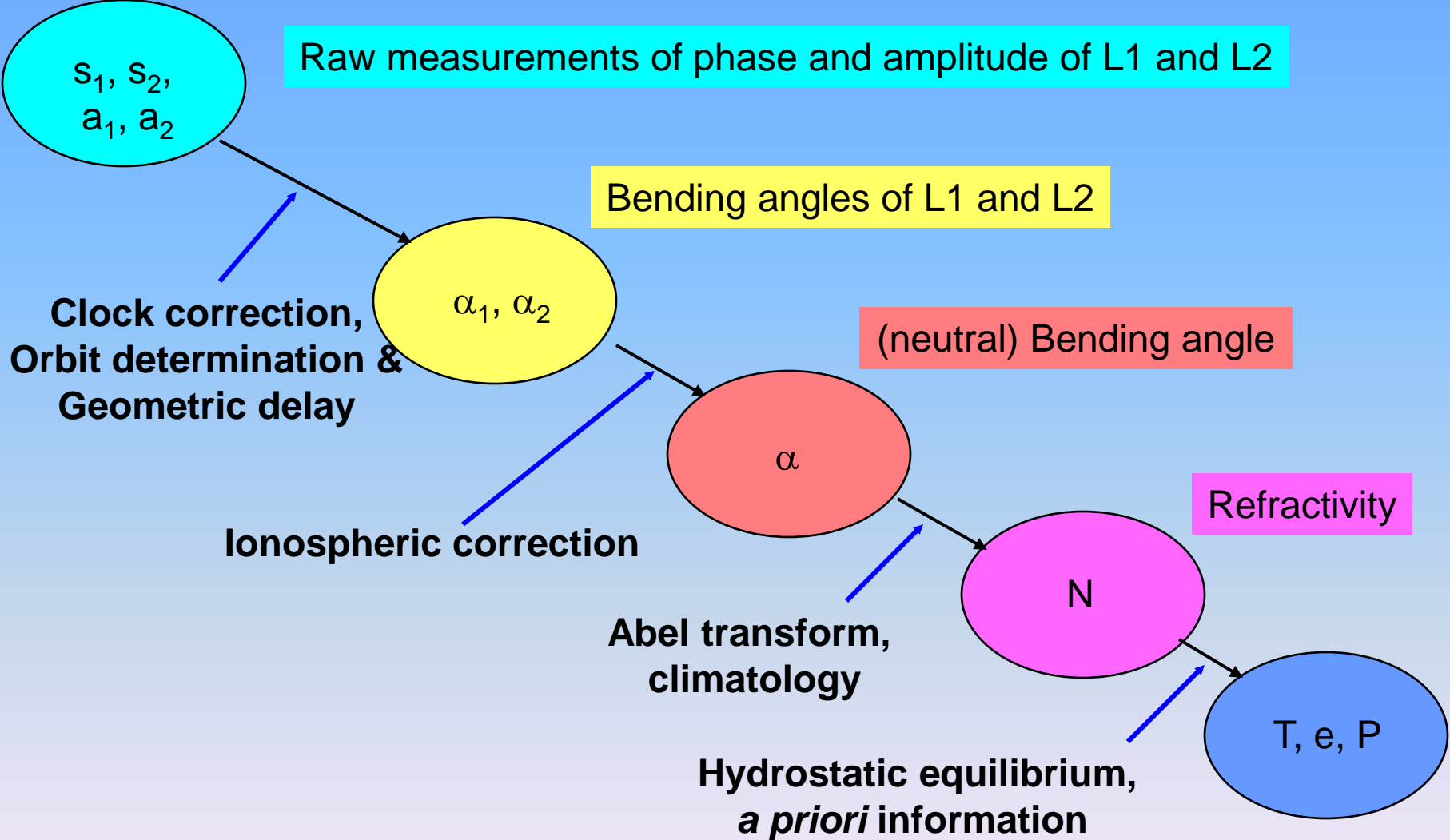
- **GPS-RO data in atmospheric data assimilation**
- Uses of GPS-RO data
  - Data and System monitoring
  - Reference observations
  - Density information in GPS-RO observations
- Impact of GPS-RO observations
  - Forecast sensitivity to observations
  - OSE experiments



# GPS-RO data in atmospheric data assimilation

- Data must be used carefully. Improperly used or bad data can produce large negative impacts. Important to be aware of instrument characteristics before attempting to use data.
- Raw observations vs. pre-processed observations.
- No current component of observing system is used “perfectly” or “as well as possible”.
- Computational expense plays important role in design of system.

# GPS radio occultation measurements & processing





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# Atmospheric Analysis Problem

$$\mathbf{J} = \mathbf{J}_b + \mathbf{J}_o + \dots$$

$$\mathbf{J} = (\mathbf{x} - \mathbf{x}_b)^T \mathbf{B}_x^{-1} (\mathbf{x} - \mathbf{x}_b) + (\mathbf{K}(\mathbf{x}) - \mathbf{O})^T (\mathbf{E} + \mathbf{F})^{-1} (\mathbf{K}(\mathbf{x}) - \mathbf{O}) + \dots$$

**$\mathbf{J}$  = Fit to background + Fit to observations + other small terms**

**$\mathbf{x}$  = Analysis**

**$\mathbf{x}_b$  = Background**

**$\mathbf{B}_x$  = Background error covariance**

**$\mathbf{K}$  = Forward model (nonlinear)**

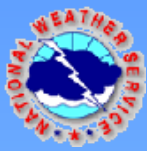
**$\mathbf{O}$  = Observations**

**$\mathbf{E} + \mathbf{F} = \mathbf{R}$  = Instrument error + Representativeness error**



# Important aspects of variational DA problem

- All data used at same time.
- Forward operator ( $K$ ) – transforms control variables ( $x$ ) into simulated observations.
  - Can include forecast model (4-D).
  - Generally more accurate implies more useful information extracted
  - Choice of forward model determines what observations to use (computational cost important)
  - If variables impacting forward model are not a part of  $x$ , then forward model error can be introduced.



# Important aspects of variational DA problem

- Instrument + Representativeness error determines weight given observation
  - Off diagonal terms allows correlated instrument or representativeness error
- Choice of which data to use is important.
  - Quality control
  - Thinning or superobing
  - Availability of data
- Background error determines weight given to short term forecast
  - Background error determines how information is distributed spatially and between variables
  - Analysis variable (x) definition enters into background error and forward model
  - Background can be as good or better than observations (in terms of variance), but will have different error structure





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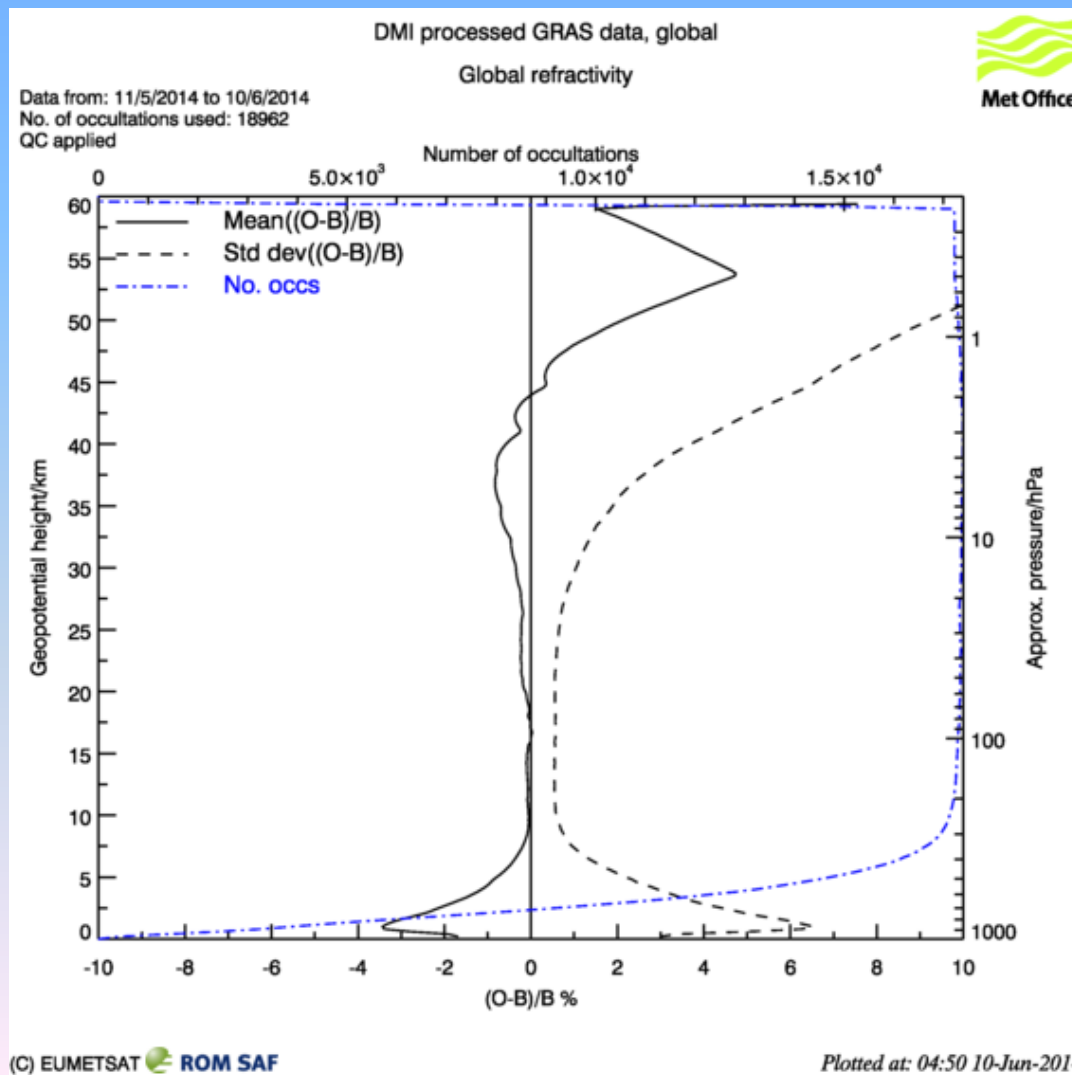


# Data and System Monitoring

- Operational centres use the short term model forecasts compared to the observations to monitor the observations and the forecast system.
- Often the NWP centres see problems with instruments prior to notification by provider (Met Office especially).
- The data monitoring can also show problems with assimilation and forecast systems.
- Needs to be ongoing/real time.



# Data and system monitoring

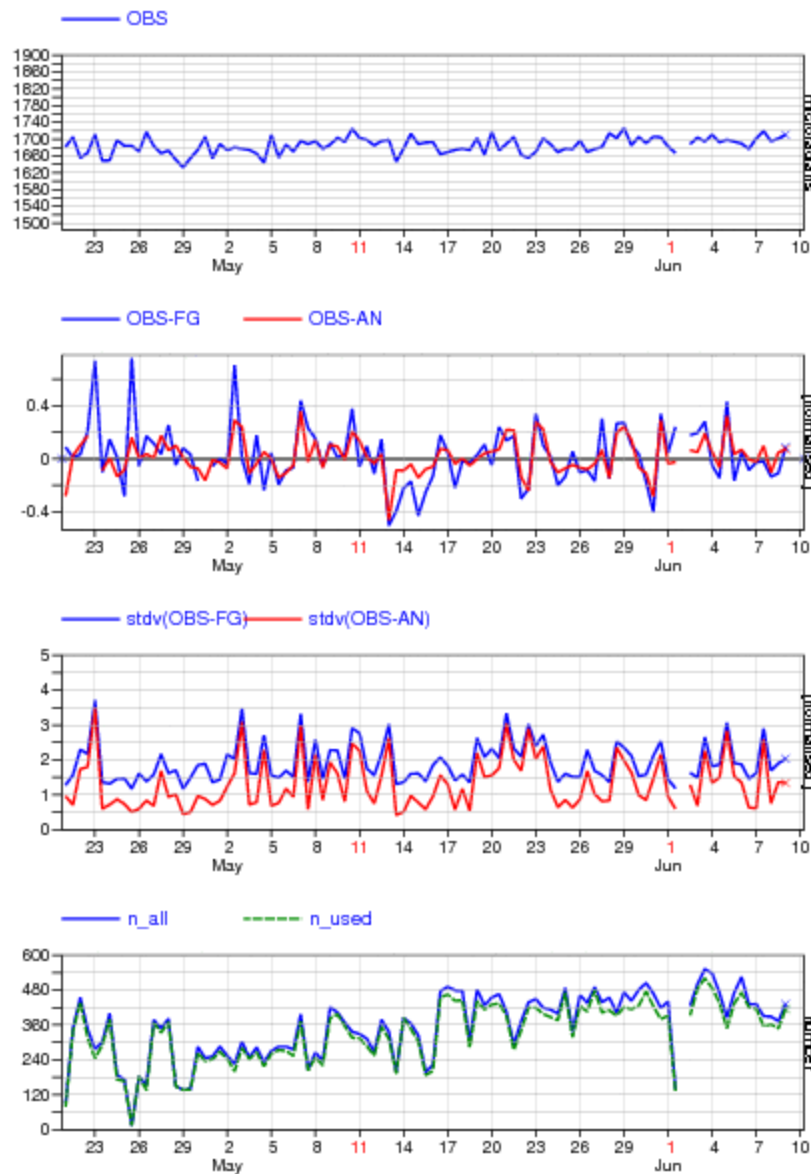




STATISTICS FOR RISING RO FROM COSMIC-1/GPSRO  
IMPACT HEIGHT = 20 KM, ALL DATA [ TIME STEP = 12 HOURS ]  
Area: lon\_w= 0.0, lon\_e= 360.0, lat\_s= -90.0, lat\_n= 90.0 (over All\_surfaces)  
EXP = 0001 (LAST TIME WINDOW: 2014060821)

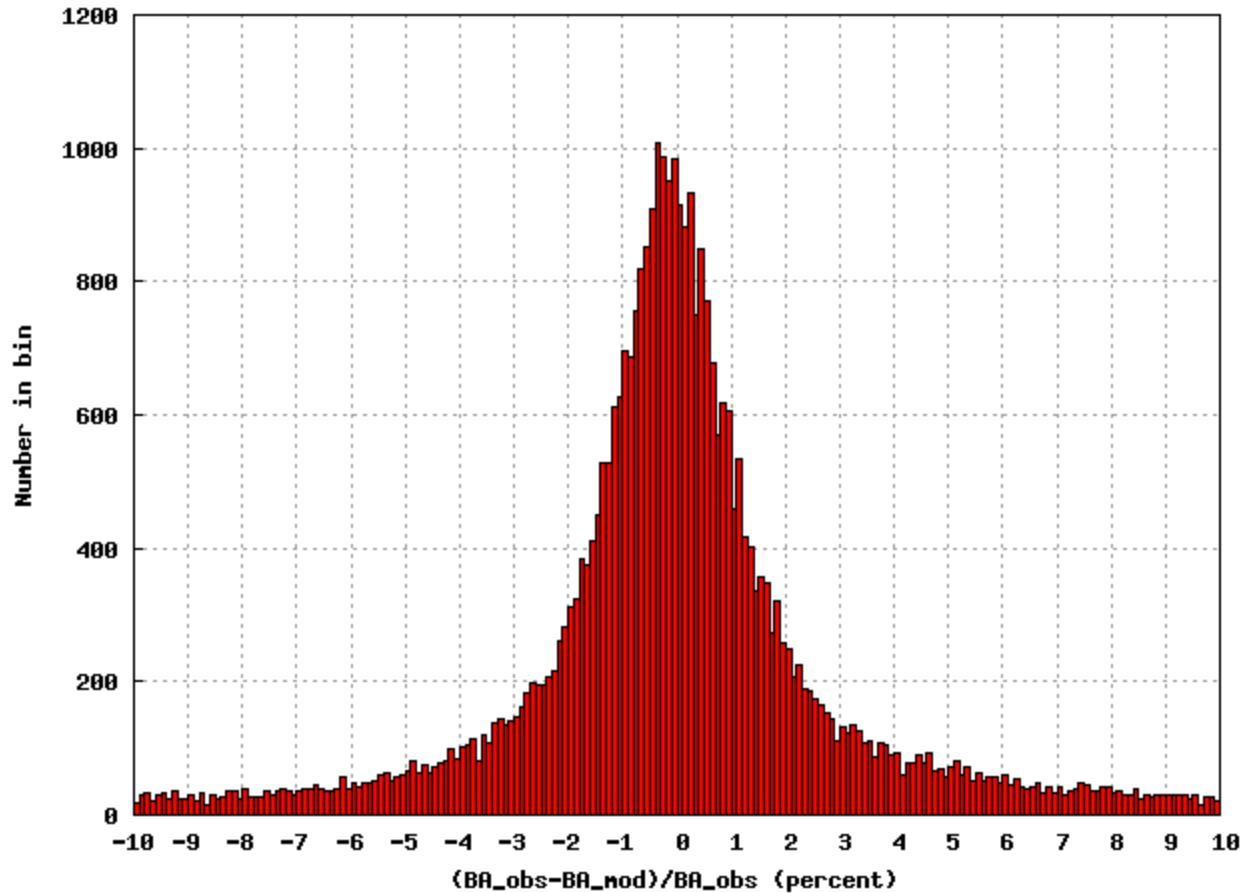


ECMWF





FM1 nheni allobs ninc histogram: 2014060800 to 2014060818



NCEP

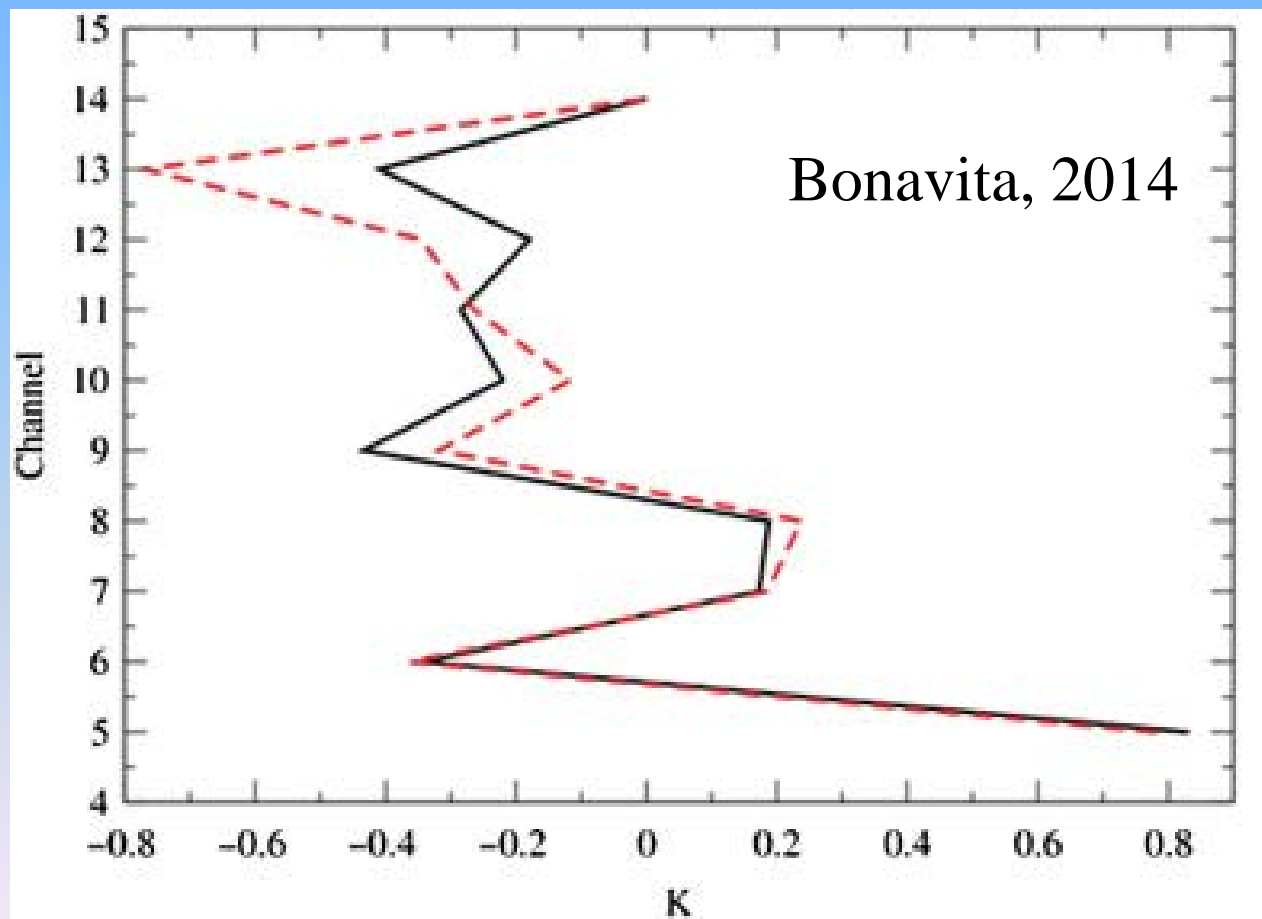


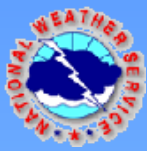
# Reference observations

- GPS-RO observations are high quality, reliable, and not very instrument dependent
- Other data (e.g., Satellite radiances, radiosondes) often require bias correction due to errors in instrument characterization and forward modelling.
- Since there is not much other reliable data available high in the atmosphere, the GPS-RO data can serve as reference observations (see prior presentation by J. Eyre)



# Reference observations





# Density information in GPS-RO observations

- Distribution to temperature and moisture determined by background error covariances and forward model
- Impact discussed below





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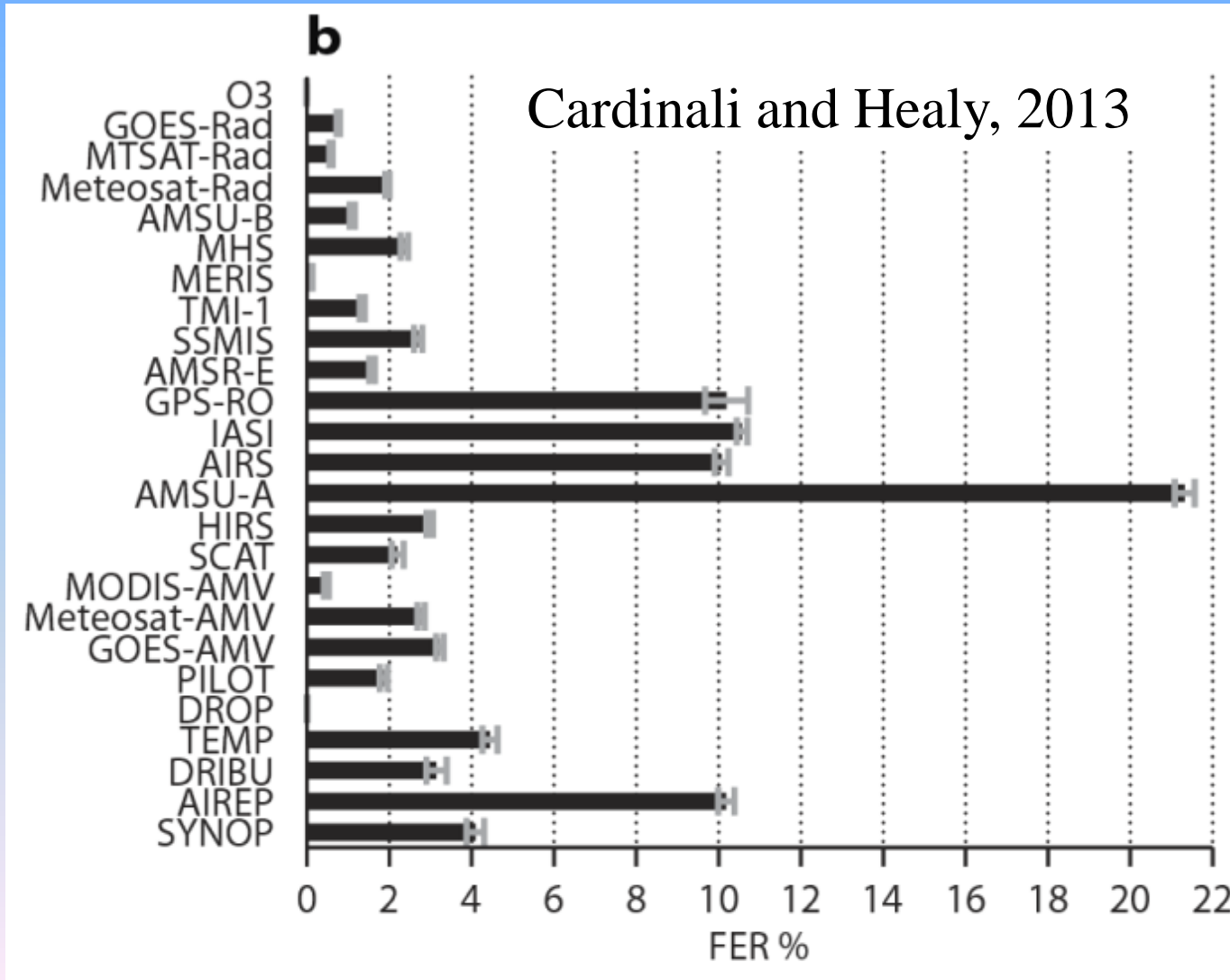


# Impact of GPS-RO observations

- Includes both density information and reference observation signal (not monitoring)
- Analysis/forecast diagnostics (e.g. DFS, FER)
  - Impact of redundancies in observing system
- Observing System Experiments
  - All impacts dependent on assimilation system
  - Similar results from most operational systems

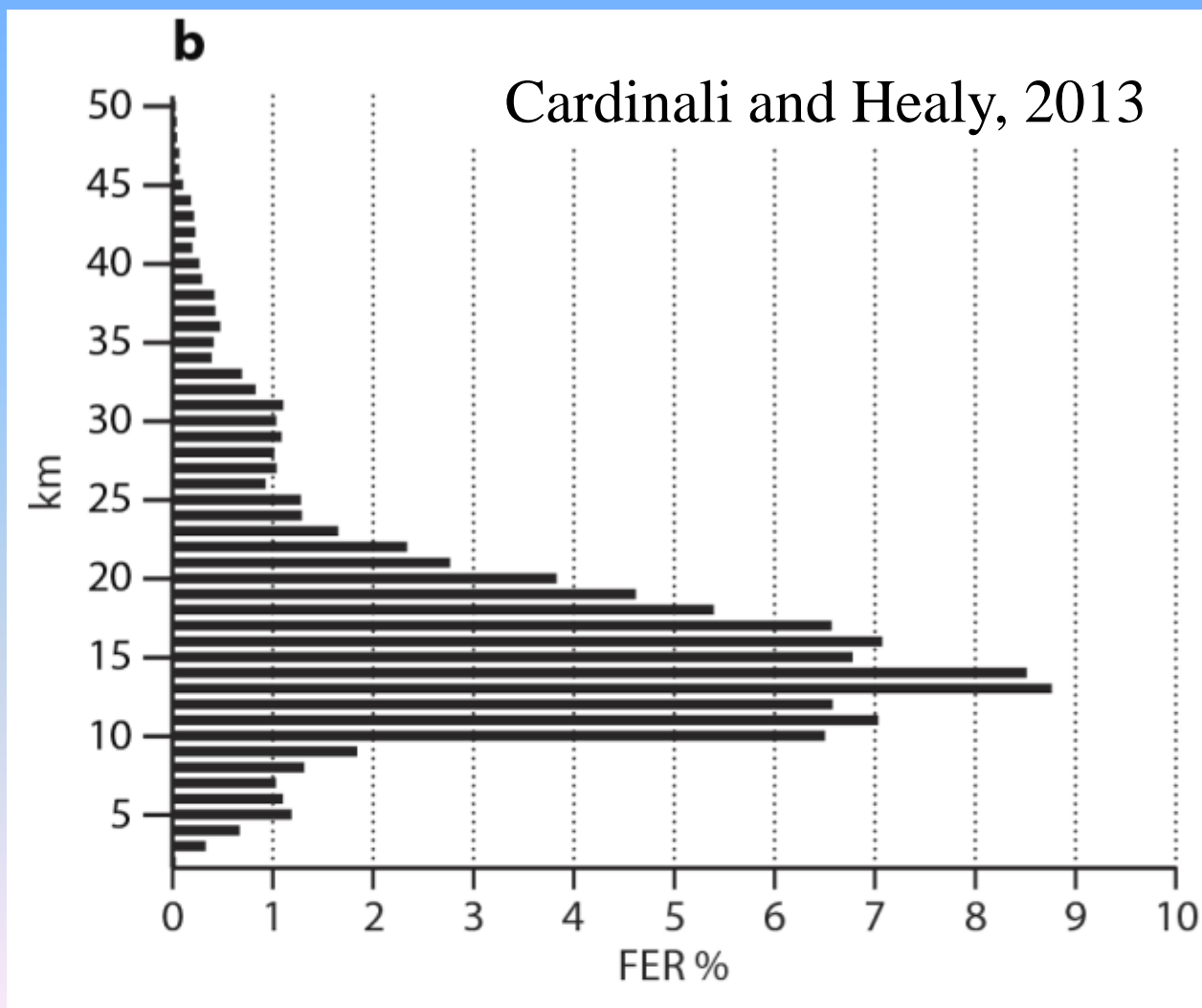


# Forecast Error Reduction



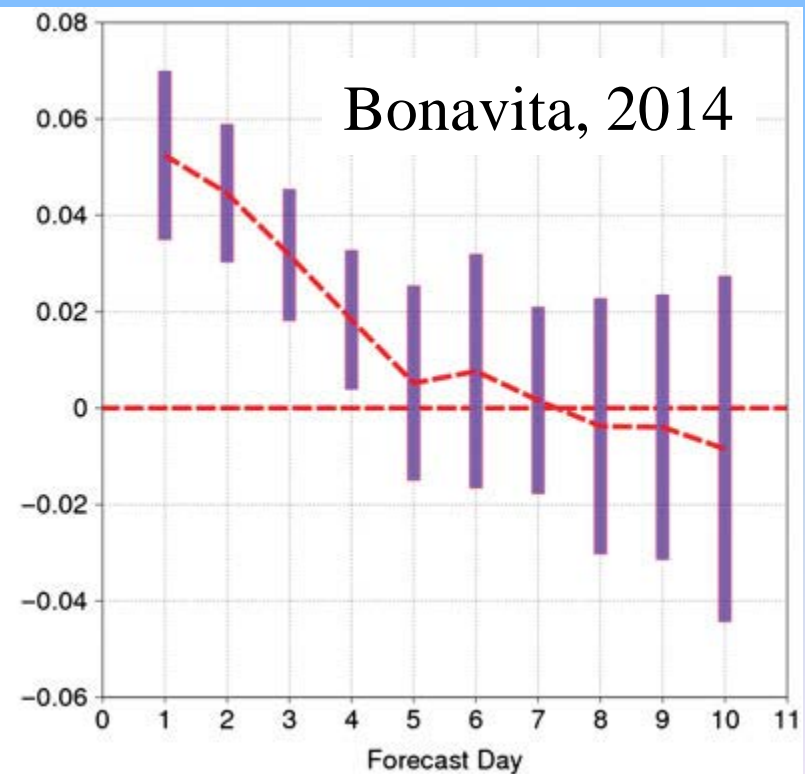
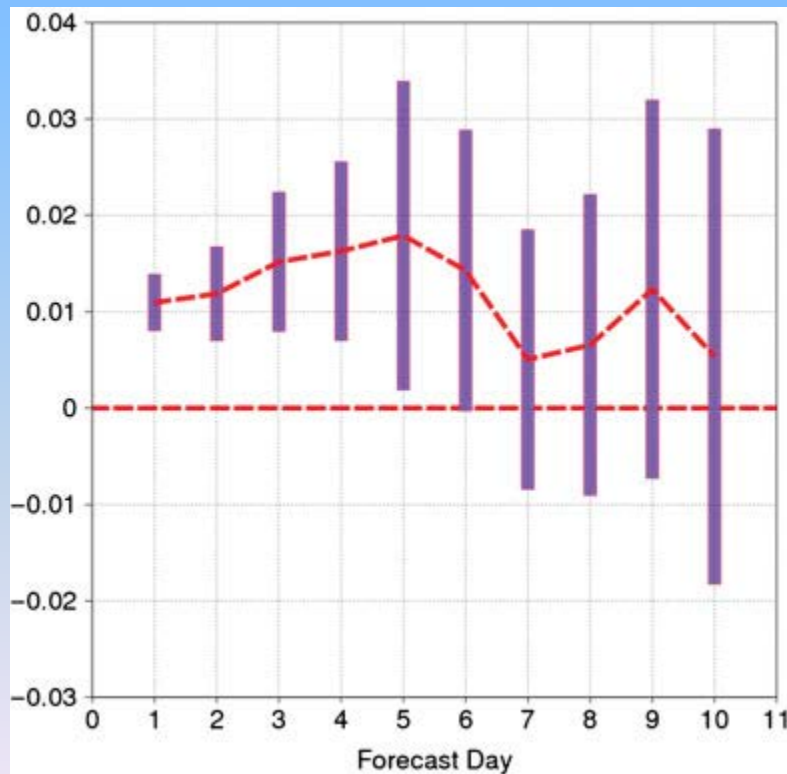


# Forecast Error Reduction





# OSE – anomaly correlation

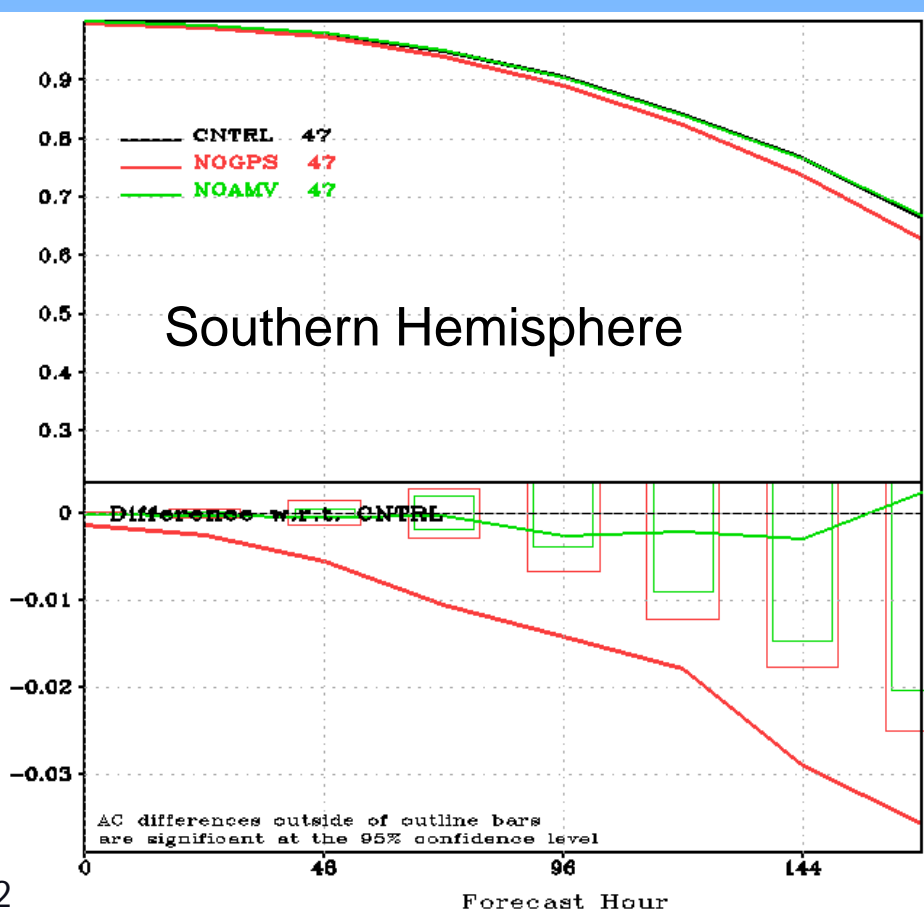
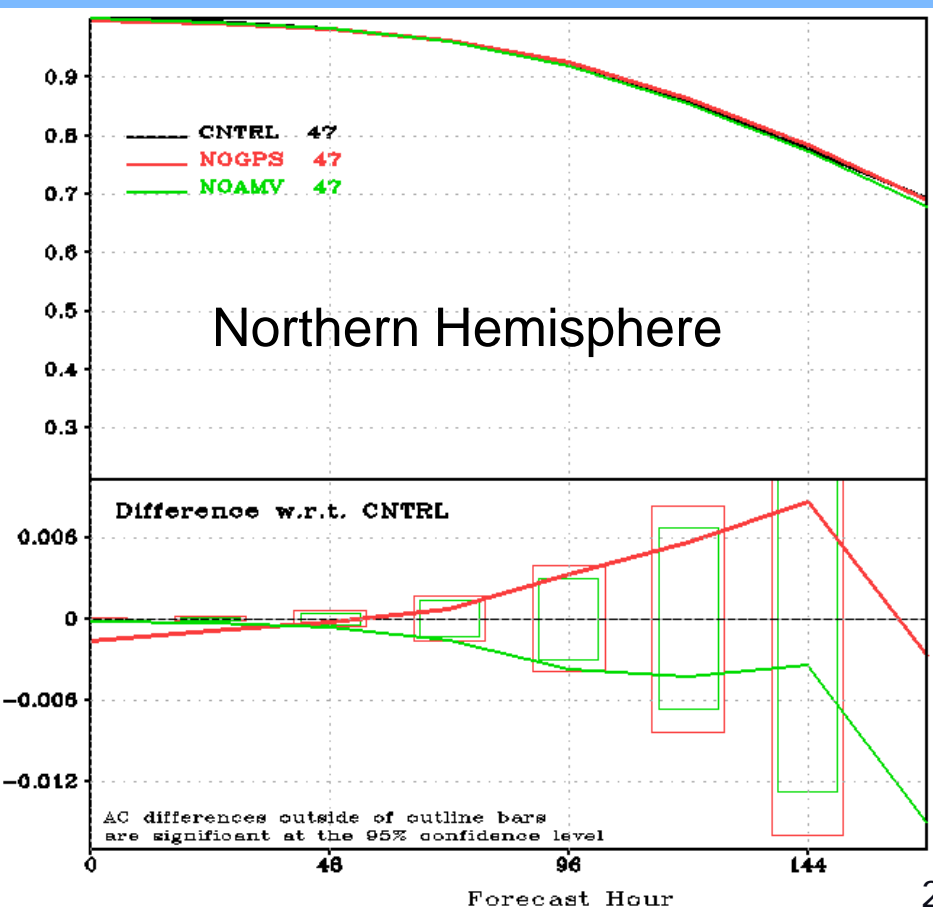




# 500 hPa Anomaly Correlations

## 15 Aug – 30 Sep 2010

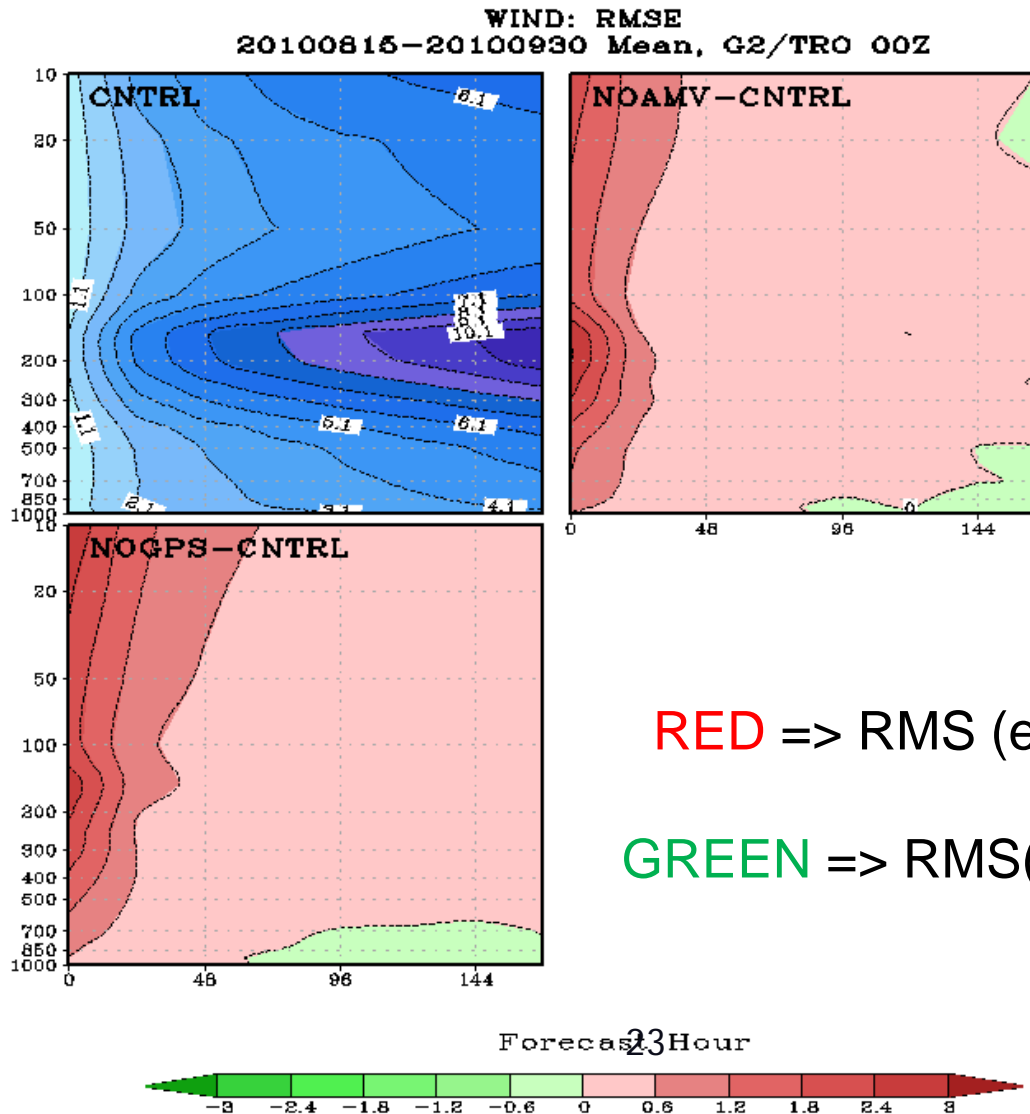
### Jung and Riishojgaard

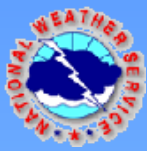


# No GPS-RO / No AMV

## 15 Aug -30 Sep 2010

### Jung and Riishojgaard





# Final Comments

- GPS-RO observations do have a positive impact on NWP, but not overwhelming
- The data is important for its direct impact on model skill, as a reference data set for bias correction and for monitoring purposes
- Largest impact is in upper troposphere and lower stratosphere
- Through improved data assimilation techniques more information can be extracted from the observations