

# Spatial filtering of assimilation ensemble statistics: increase of sample size by local spatial averaging

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# Introduction and Plan

Importance of sample size:

- amplitude of sampling noise in the estimated covariances.
- the ensemble size influences the ensemble cost.

1 - Increase of sample size by local spatial averaging

2 - Spatial filtering of standard deviations

3 - Spatial filtering of correlations

# 1 - Increase of sample size by local spatial averaging

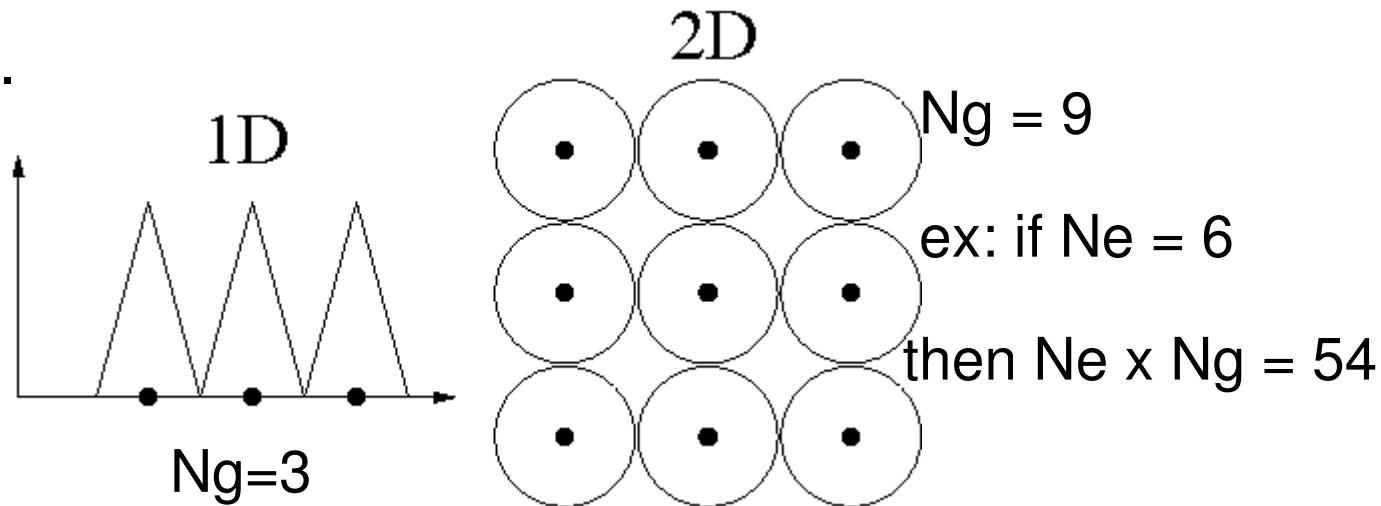


# Strategies for ensemble size and cost reduction (assimilation ensemble at Météo France)

- Experiments: a small number of members (e.g. 3 to 10) already provides a lot of information !
- Use ergodic properties: increase sample size by spatial averaging.
- The full assimilation system may be approximated in the error simulation (e.g. resolution or/and 4D-Var vs 3D-Fgat).
- Six global members T359 L46 with 3D-Fgat are running in nearly real time (Arpège).

# Increase of statistical sample size through spatial sampling/averaging

Basic idea: MULTIPLY(!) the statistical sample size by a number  $Ng$  of gridpoint samples.

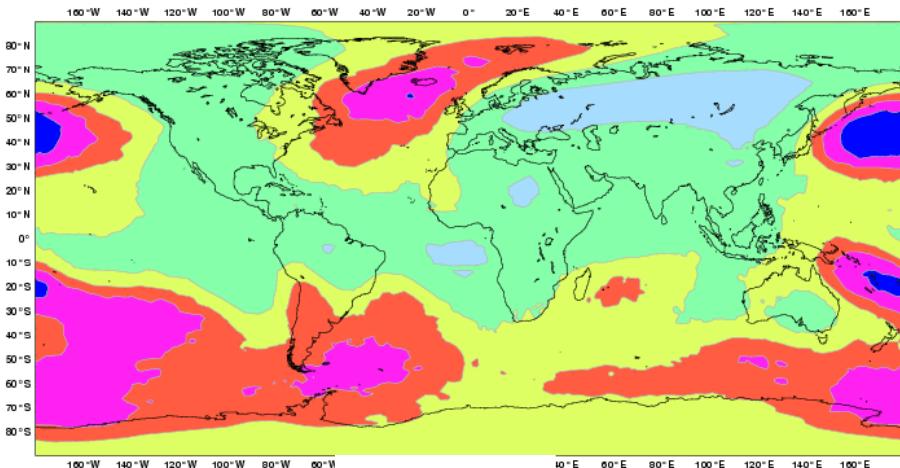


- An "ideal" case: local homogeneity of covariances and (relatively) short correlation length-scales.
- Another way to justify spatial filtering: sampling noise  $\sim$  small scale.

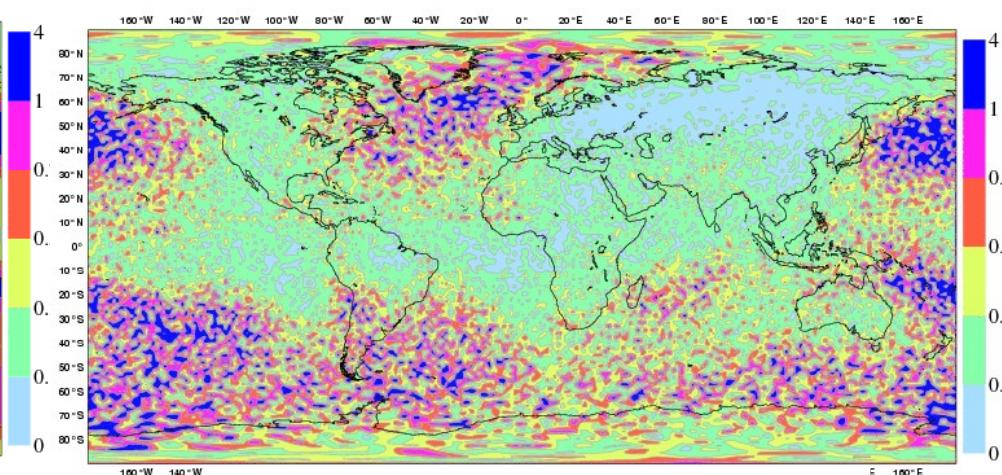
## 2 - Spatial filtering of standard deviations



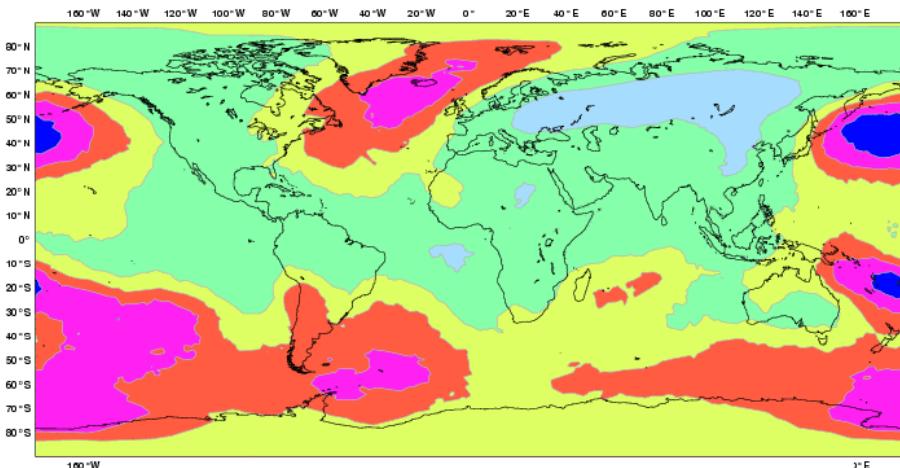
# Illustration in a simulated framework



True  $\sigma_b$



RAW 6-member estimated  $\sigma_b$



FILTERED 6-member estimated  $\sigma_b$

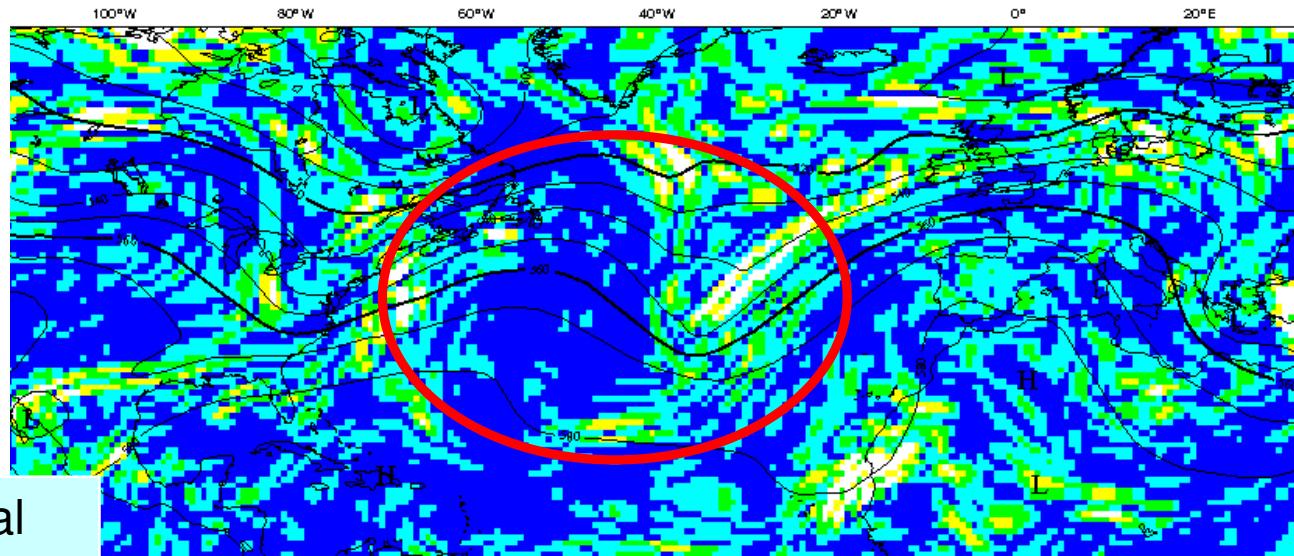
Workshop on Flow-dependent aspects of data assimilation 11 - 13 June 2007



**METEO FRANCE**  
Toujours un temps d'avance

# The spatial structure of signal and noise from two independent 3-member ensembles

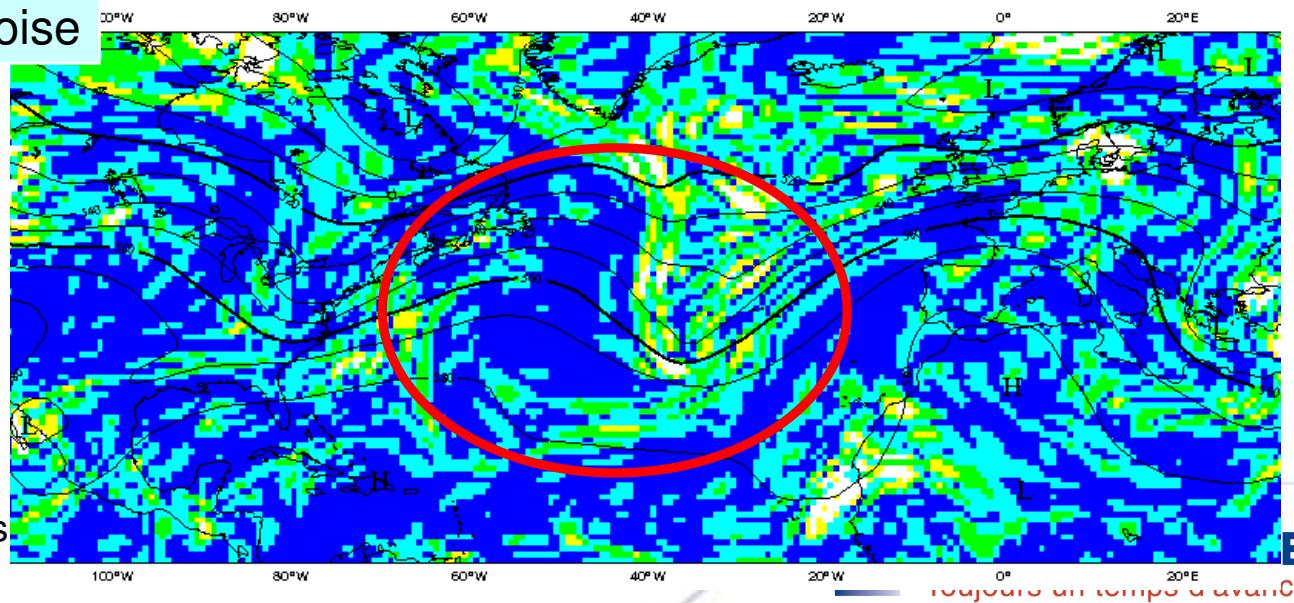
"RAW"  $\sigma b$  ENS 1



Common features ~ signal

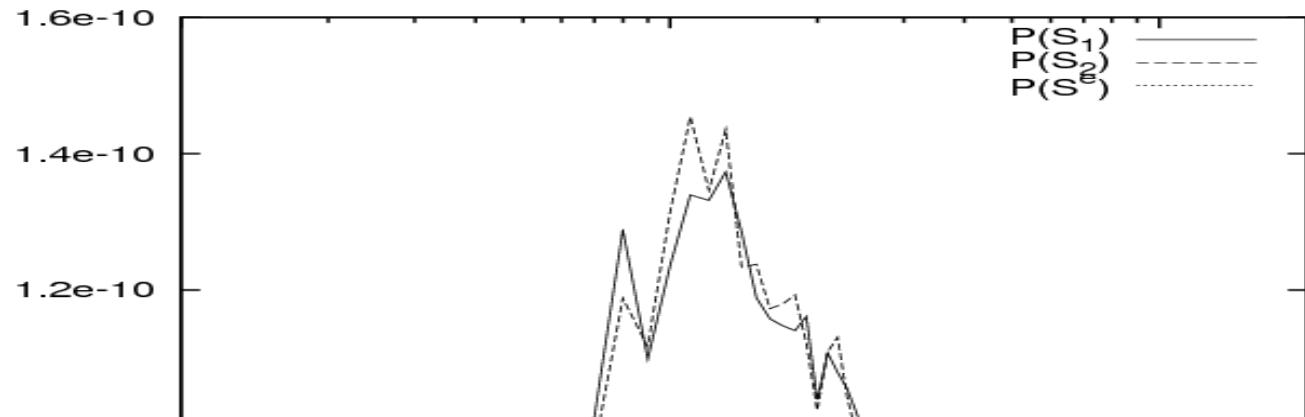
Differences ~ sampling noise

"RAW"  $\sigma b$  ENS 2

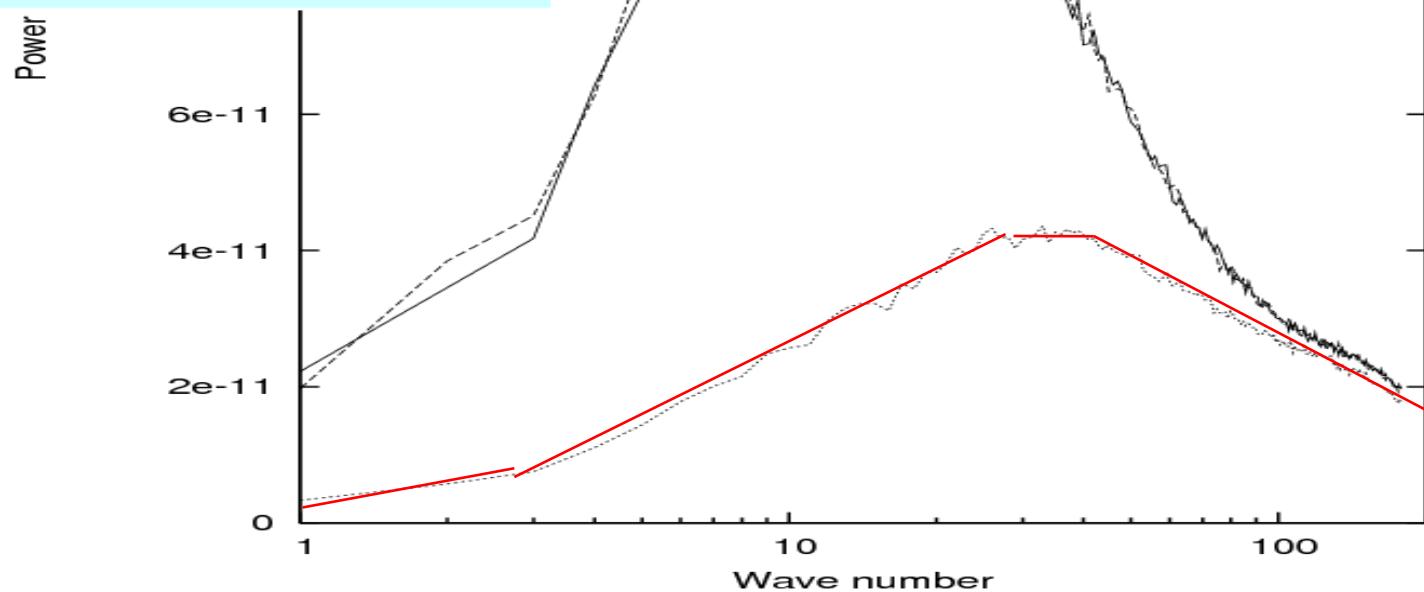


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# Spectra of sigmab maps and of sampling noise

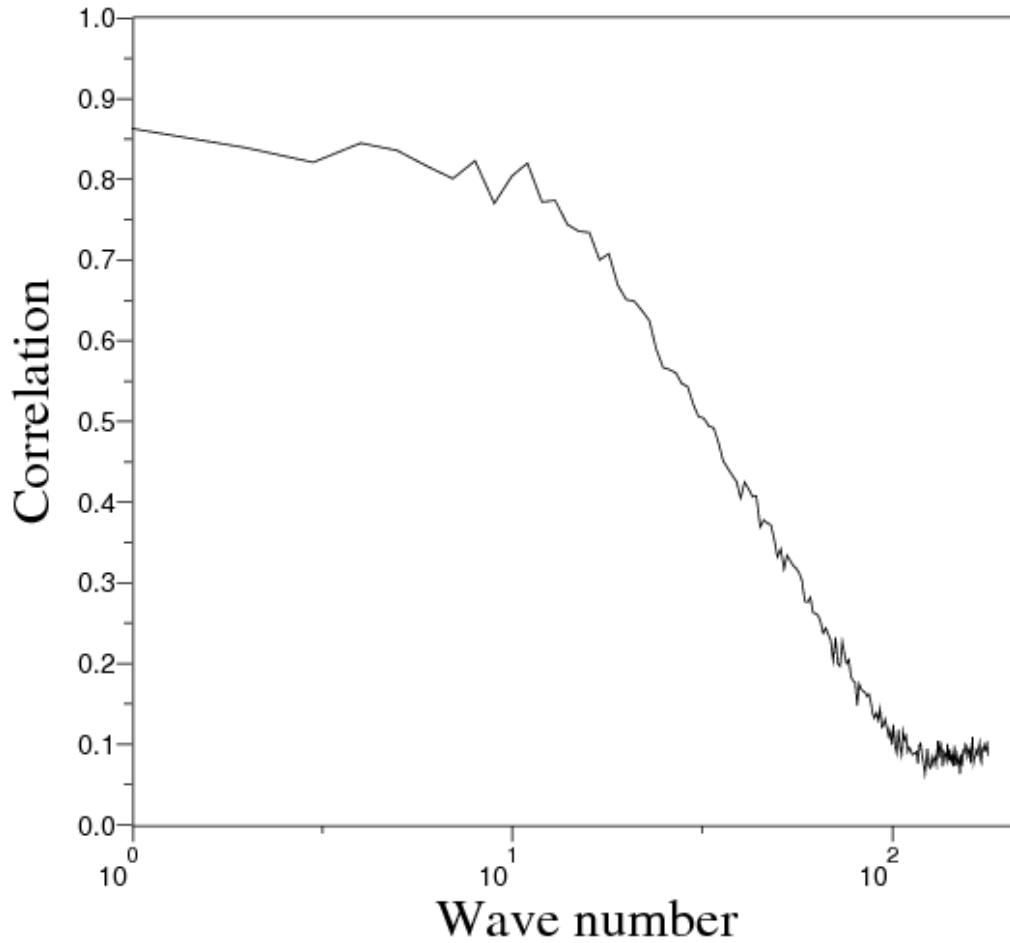


=> The **sampling noise** is relatively small scale, which justifies the application of spatial filtering.



# Can we design an objective and optimal filter ?

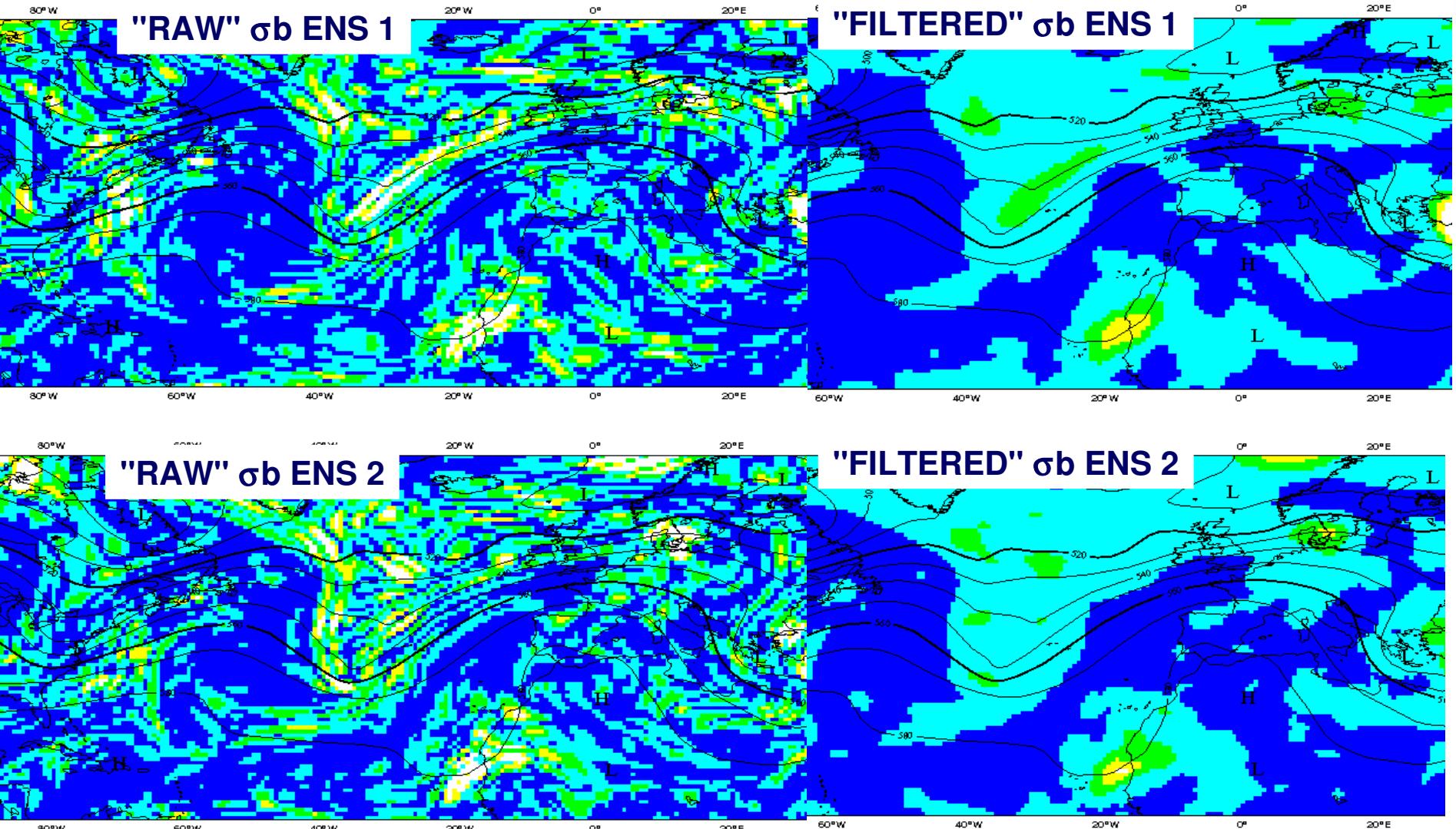
$$\rho = \text{cor}(\mathbf{S}_1, \mathbf{S}_2)$$



⇒ The two  $\sigma_b$  fields are more coherent  
in the large scales than  
in the small scales.

⇒ It can be shown that this spectral  
correlation can be used as an objective  
and optimal filtering coefficient !

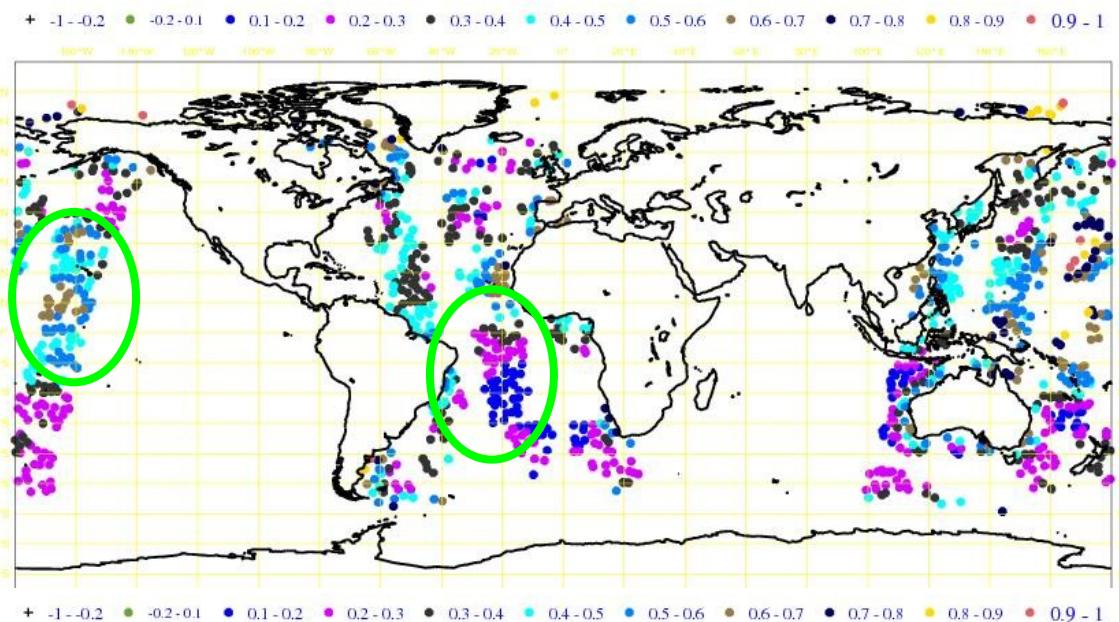
# Spatial filtering of standard deviations



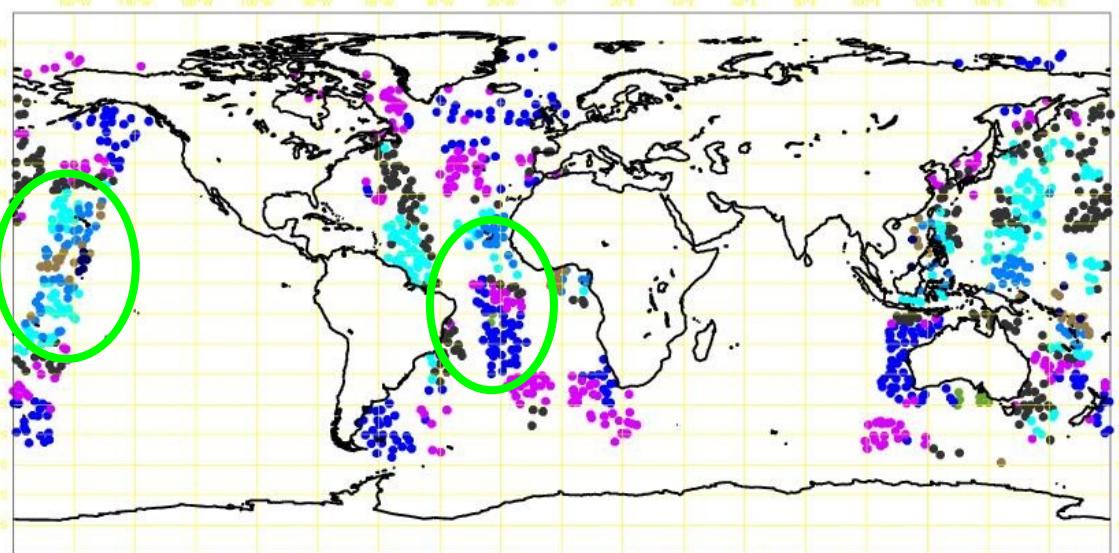
# Validation with innovation diagnostics

## ( for one specific day and for HIRS-7 )

Ensemble  
sigmab's



"Observed"  
sigmab's

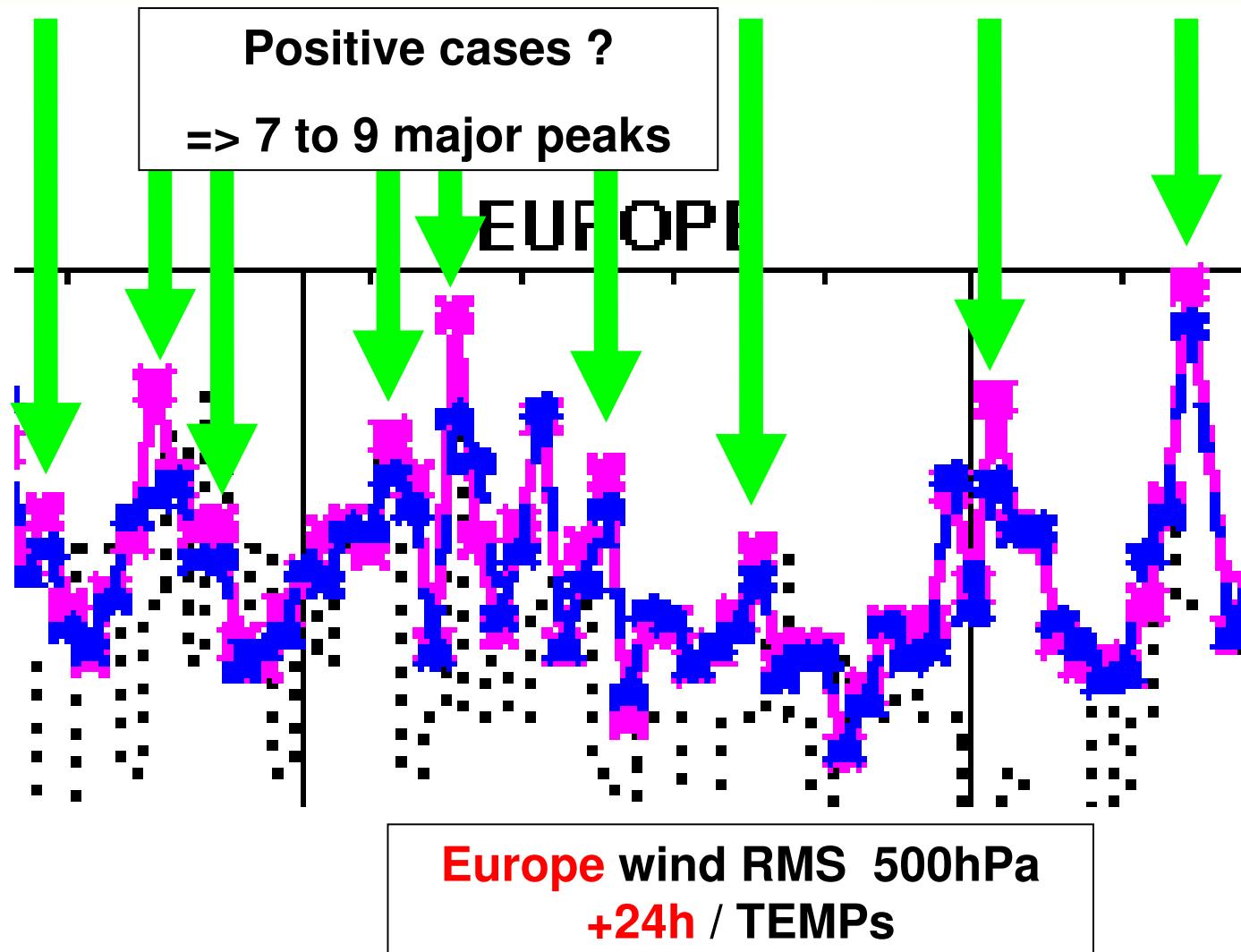


$$\text{cov}( \mathbf{H} \mathbf{d}x, \mathbf{d}y ) \sim \mathbf{H} \mathbf{B} \mathbf{H}^T$$

(Desroziers et al 2005)

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# Impact of sigmab's of the day in the Arpège 4D-Var (~over two months ; versus “climatological” sigmab's)



## 3 - Spatial filtering of correlations

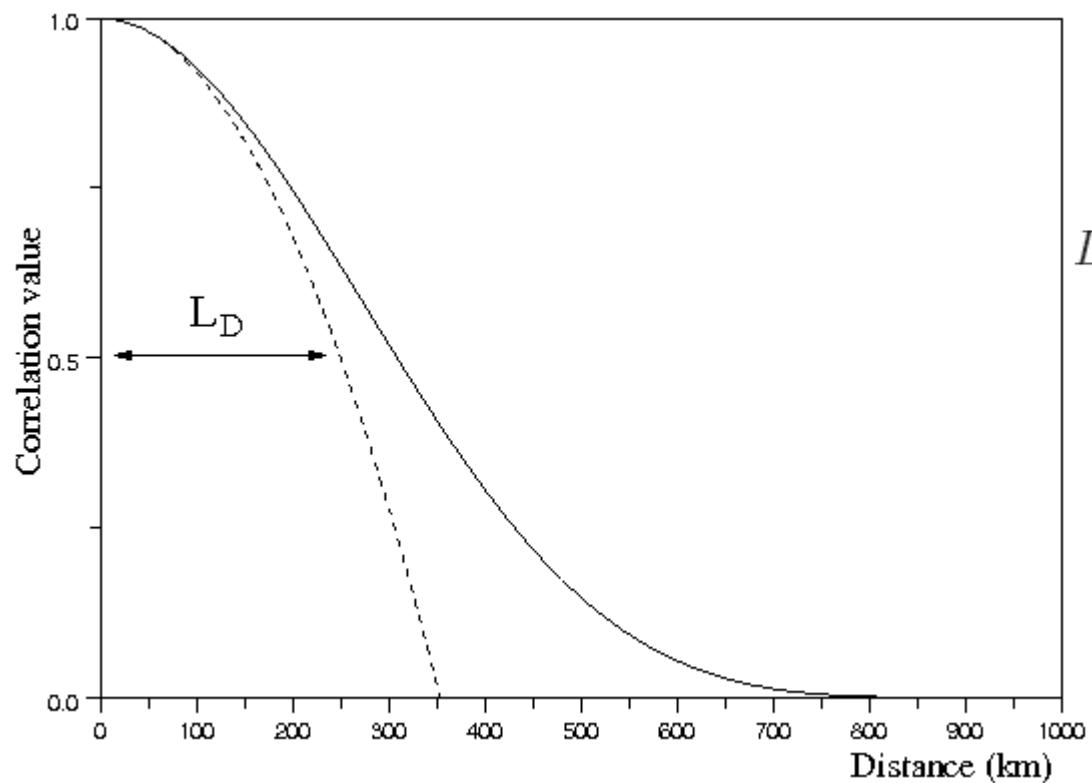


# Local averaging of correlations via wavelets

Two extreme approaches in correlation modeling:

- Ens KF: **local** correlation functions are calculated for each gridpoint. => heterogeneity, but it needs a large ensemble.
- Var: a **global average** of correlation functions, via a spectral diagonal approach. => large (spatial) sample, but homogeneity.  
=> An attractive compromise is to use wavelets, to calculate a **local average** of correlations.

# Diagnosis of length-scale



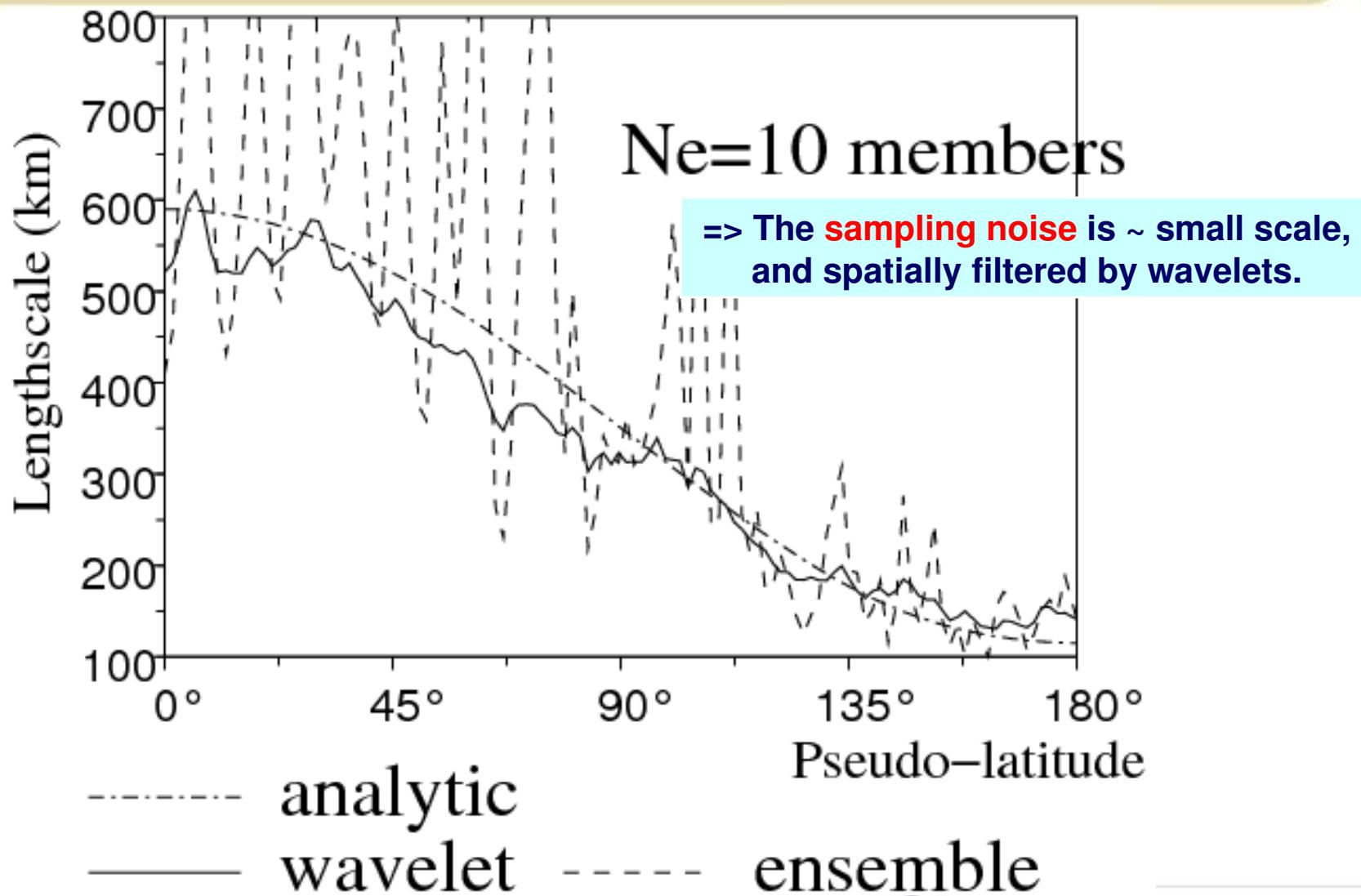
$$L_D = \sqrt{-\frac{1}{\Delta\rho(0)}}$$

$$L_{B\&B} = \sqrt{\frac{\sigma(\varepsilon_b(x))^2}{\sigma(\partial_x \varepsilon_b(x))^2 - (\partial_x \sigma(\varepsilon_b(x)))^2}}$$

$$L_{Pb} = \frac{|\delta x|}{\sqrt{2(1 - \rho(\delta x))}}$$

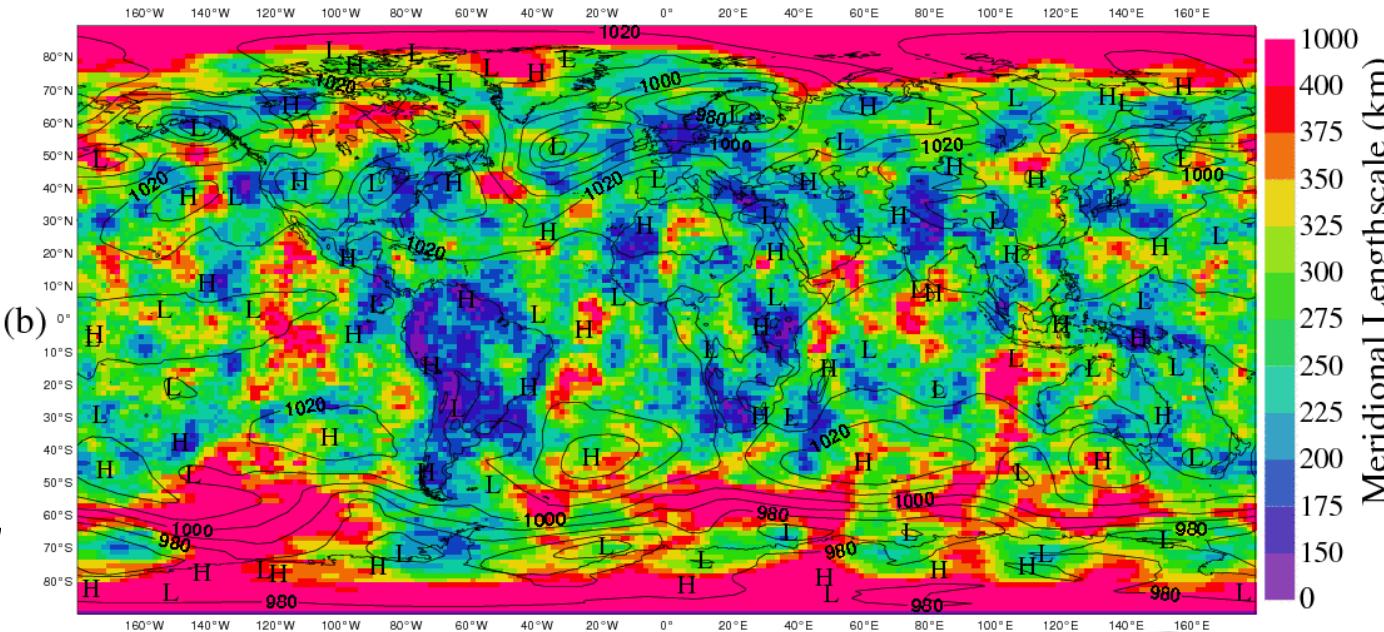
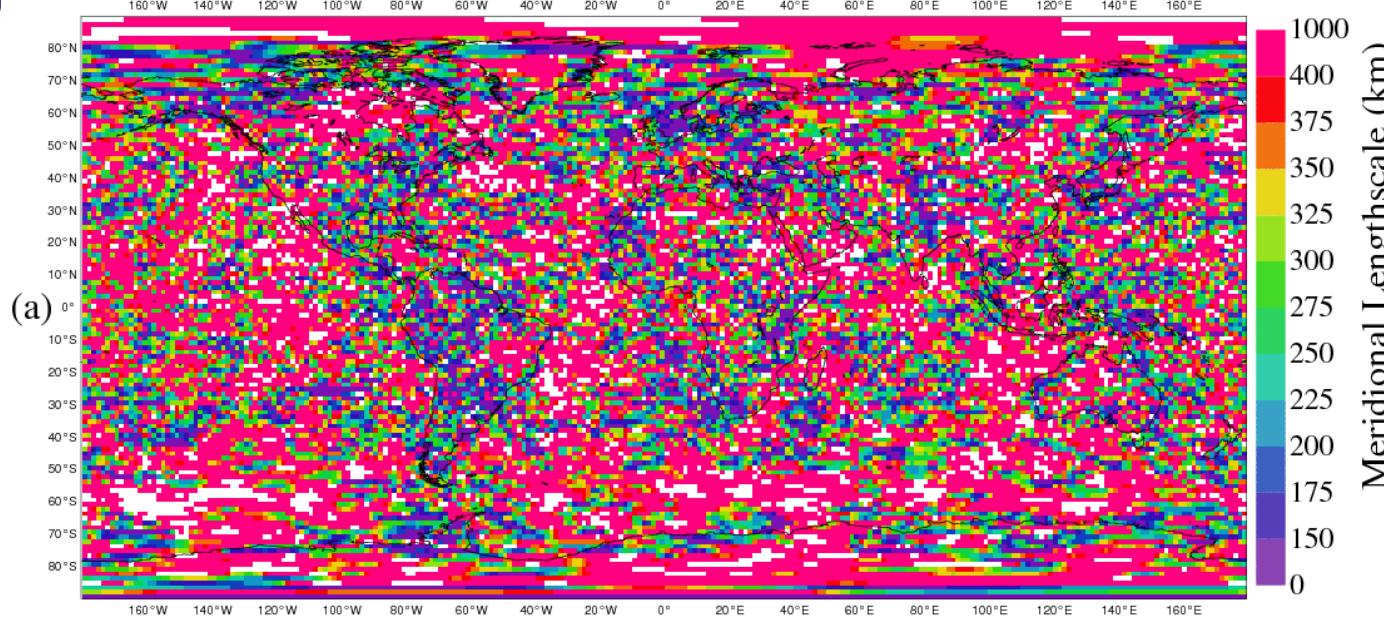
$$L_{Gb} = \frac{|\delta x|}{\sqrt{-2 \ln \rho(\delta x)}}$$

# Sampling noise reduction

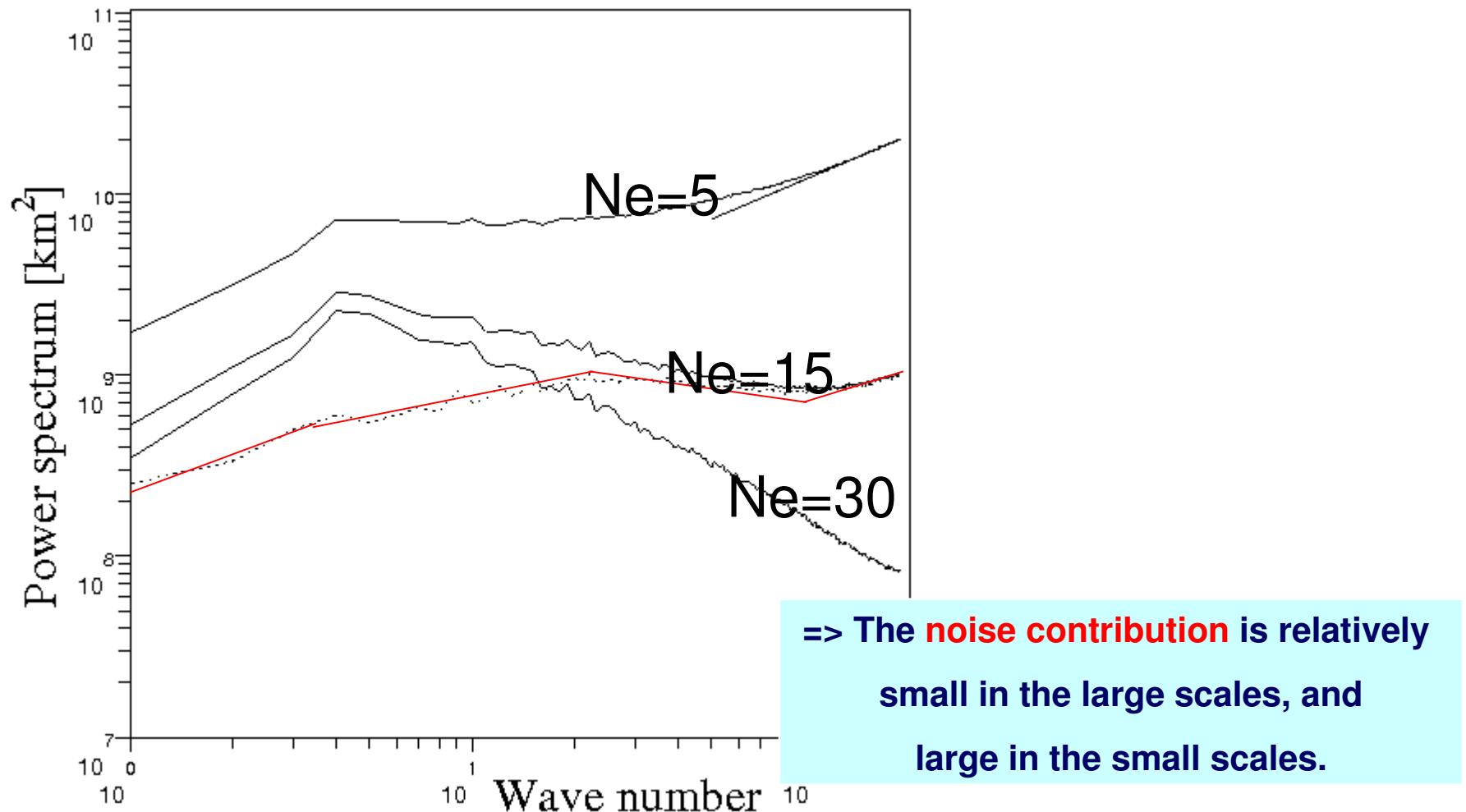


# Correlation length-scales of the day

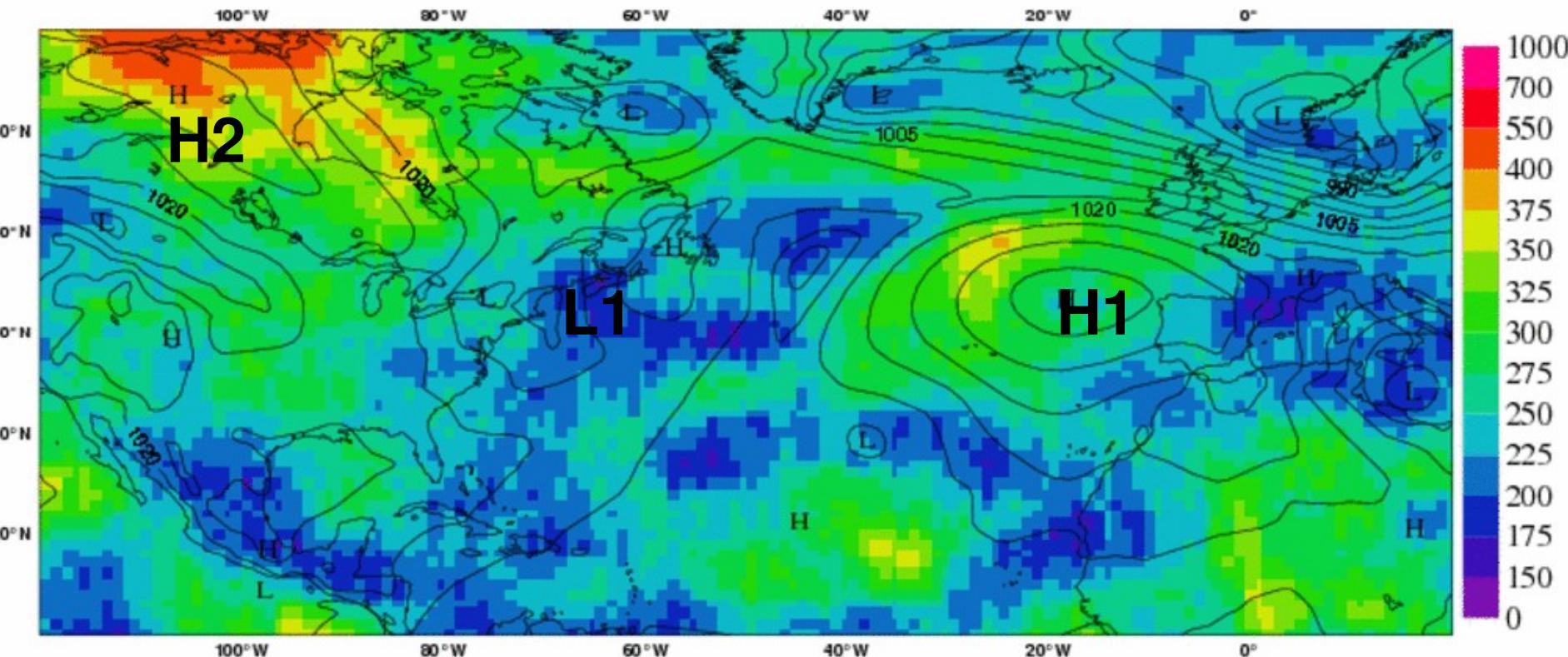
(from a 6-member assimilation ensemble; Pannekoucke et al 2007)



# Spectrum of unfiltered length-scale map versus ensemble size

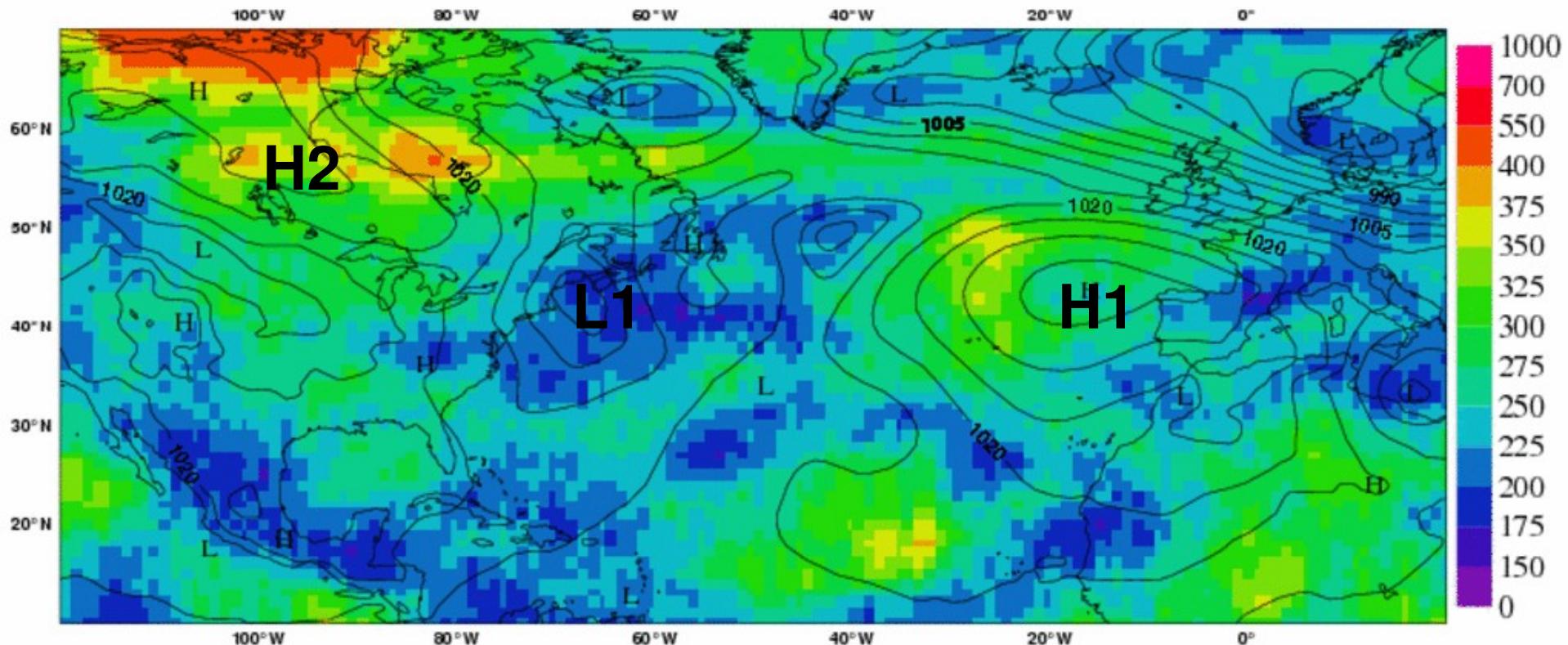


# Length-scales of the day



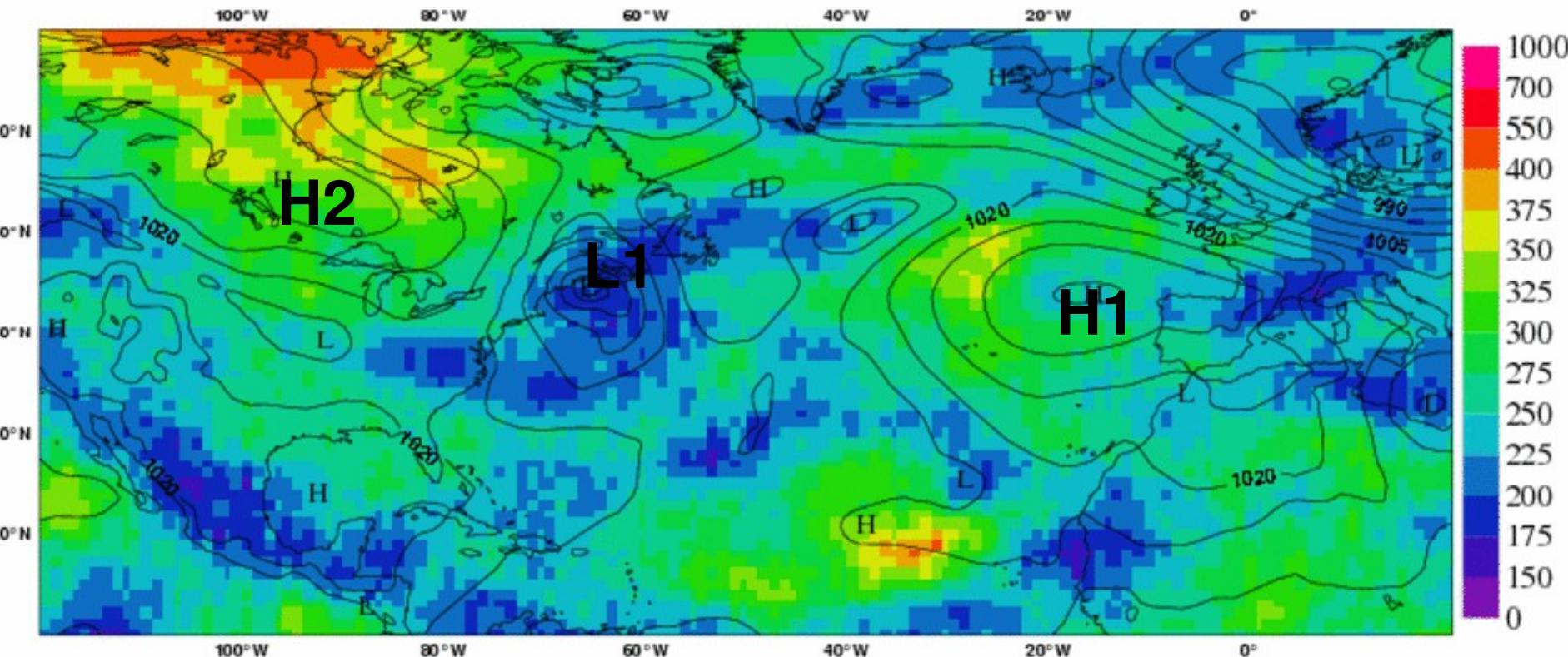
20/01/2005 06UTC ( 1/12)

# Length-scales of the day



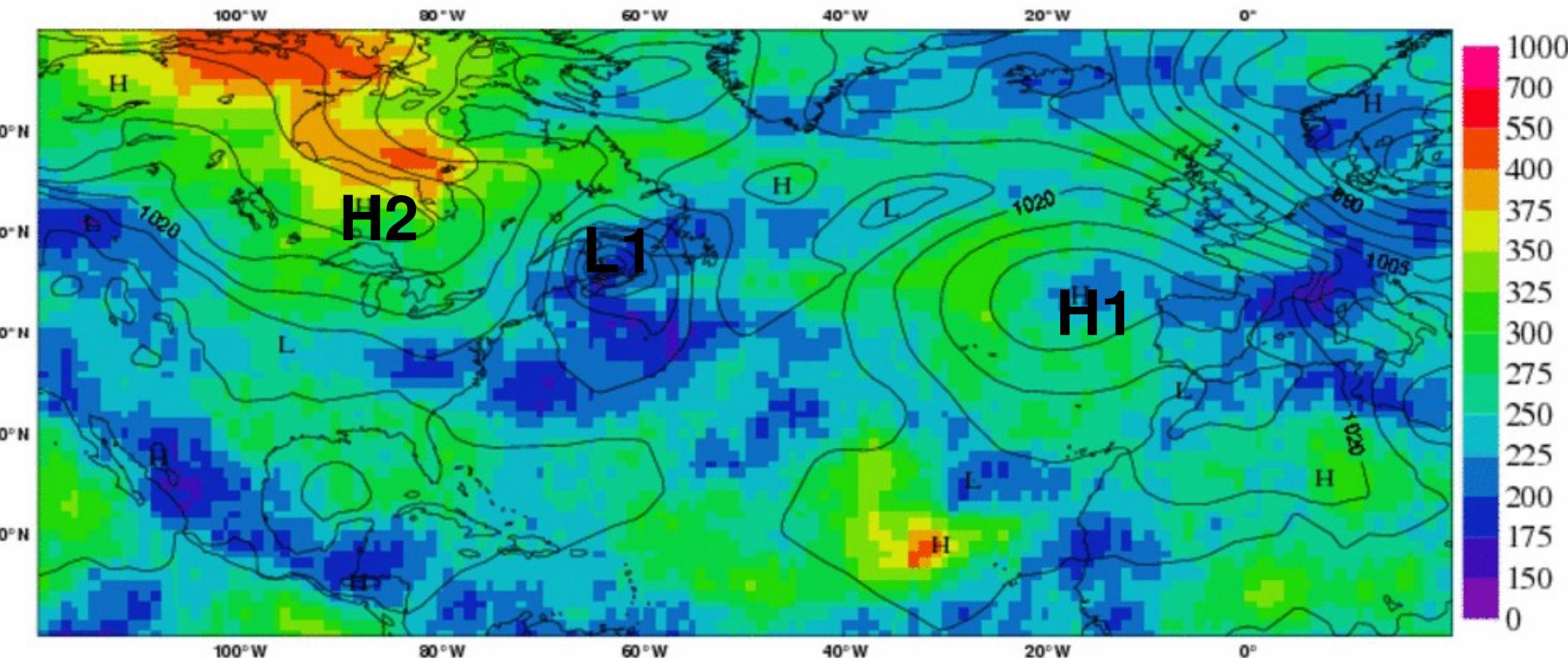
20/01/2005 12UTC ( 2/12)

# Length-scales of the day



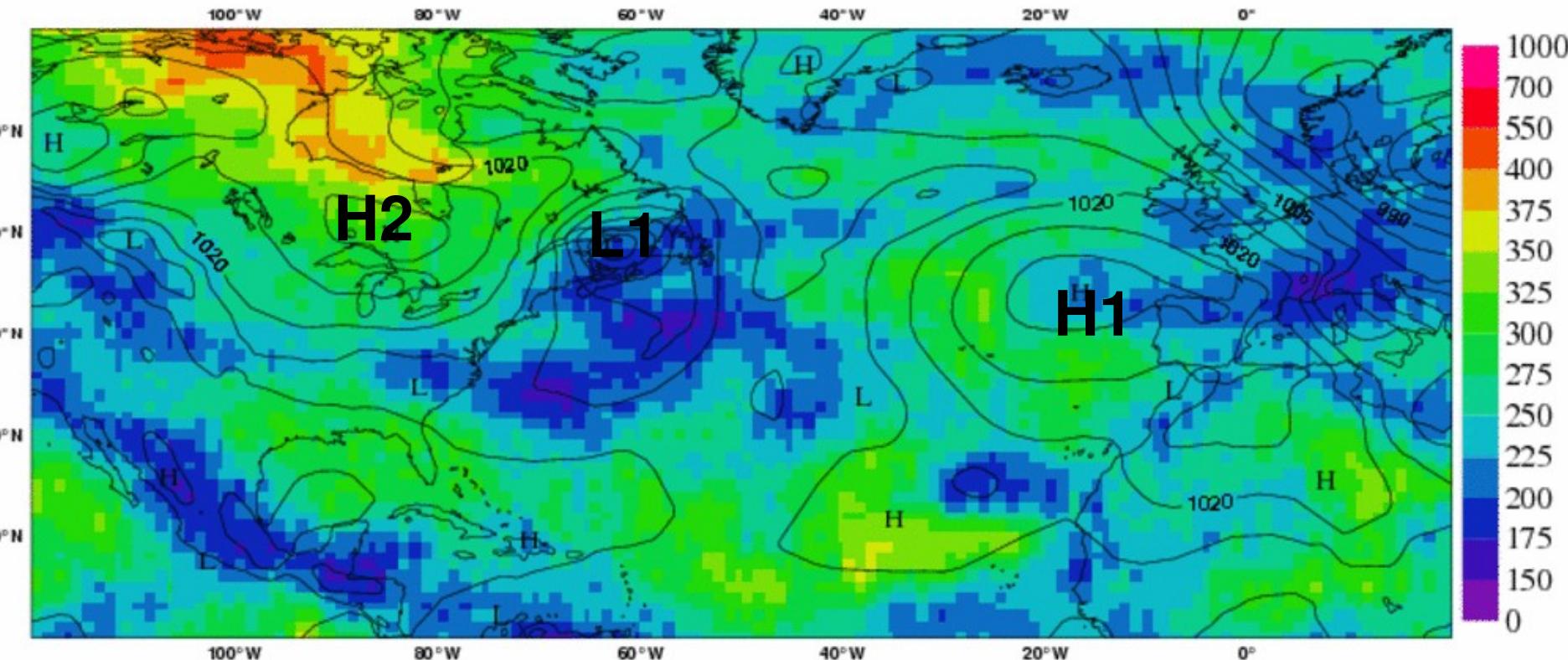
20/01/2005 18UTC ( 3/12)

# Length-scales of the day



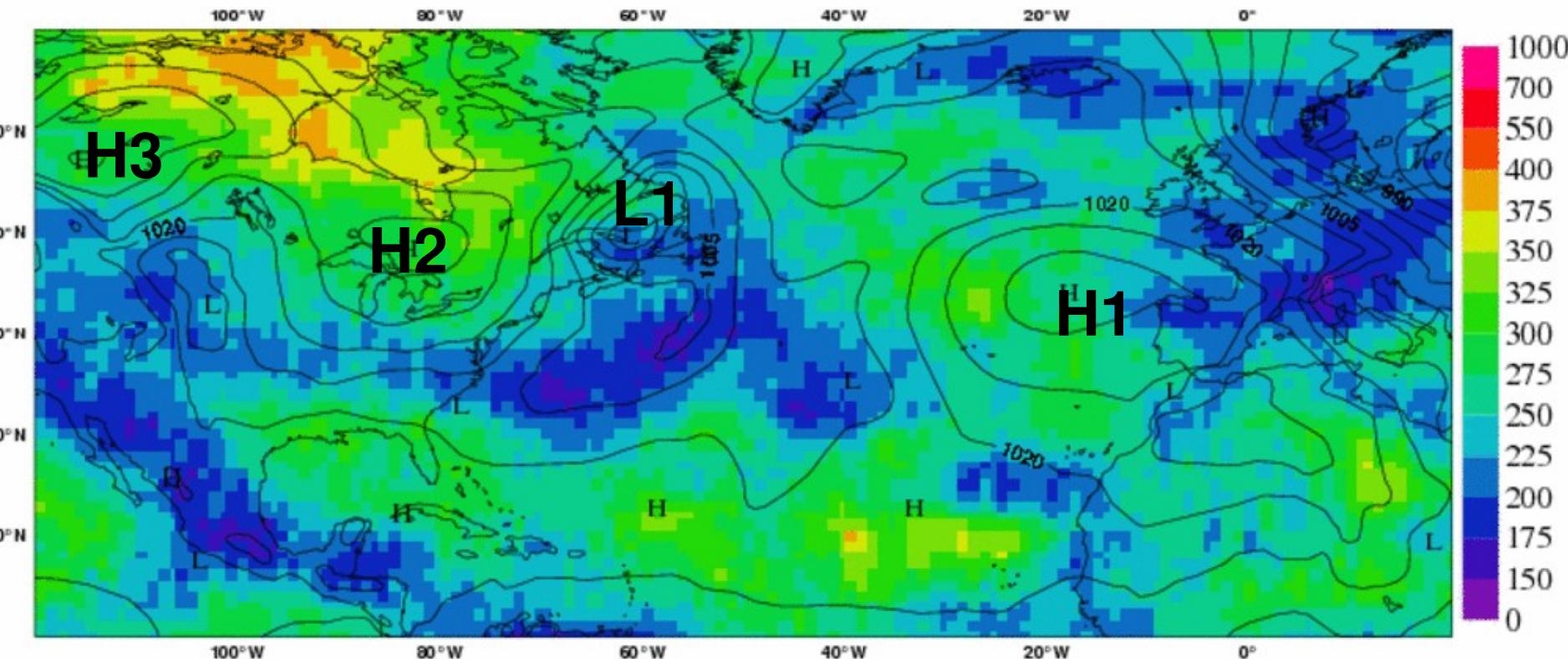
21/01/2005 00UTC ( 4/12)

# Length-scales of the day



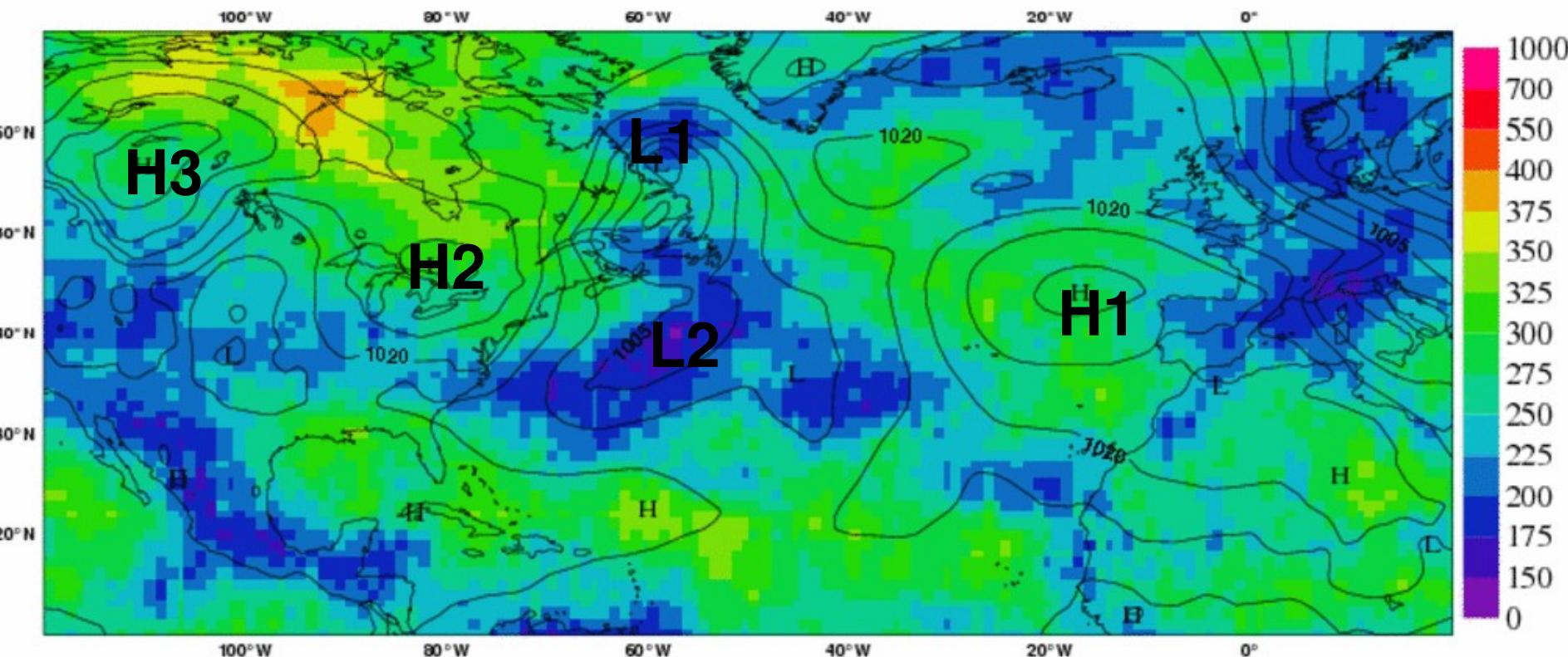
21/01/2005 06UTC ( 5/12)

# Length-scales of the day



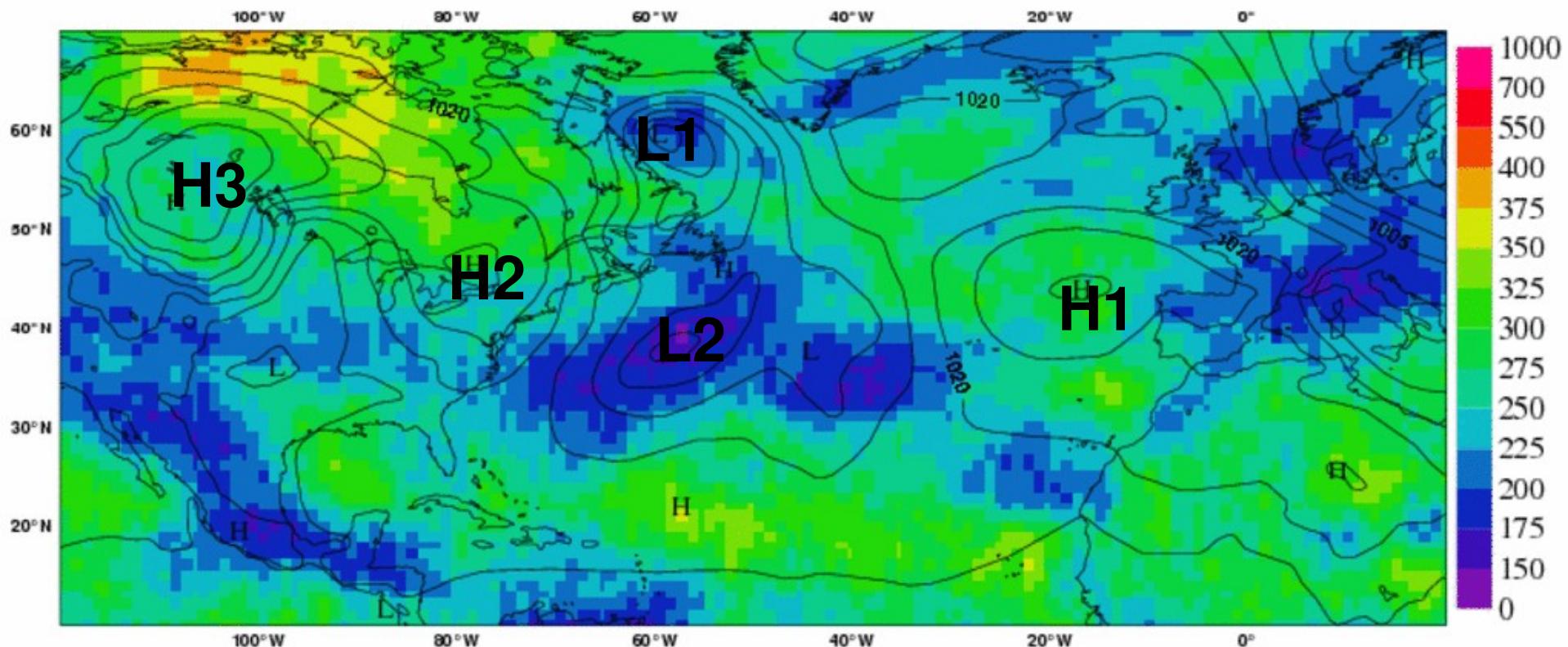
21/01/2005 12UTC ( 6/12)

# Length-scales of the day



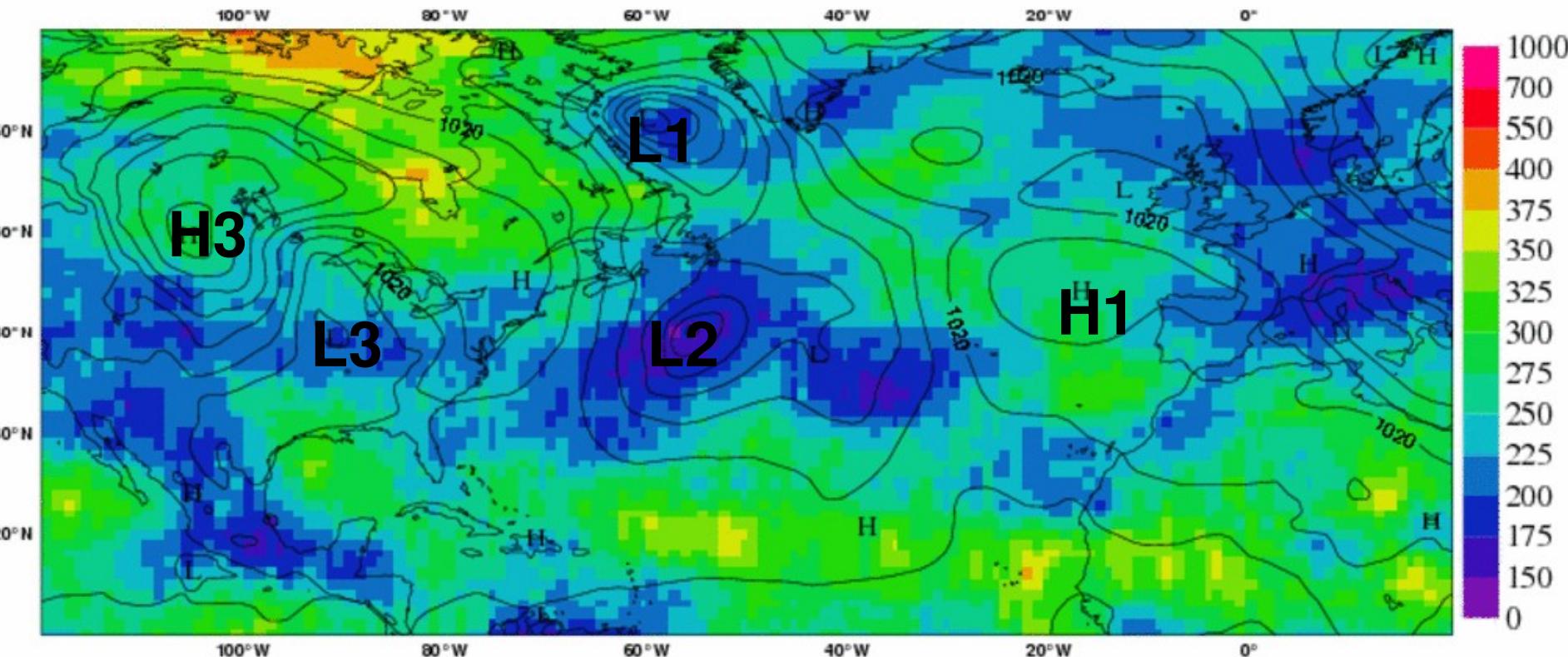
21/01/2005 18UTC ( 7/12)

# Length-scales of the day



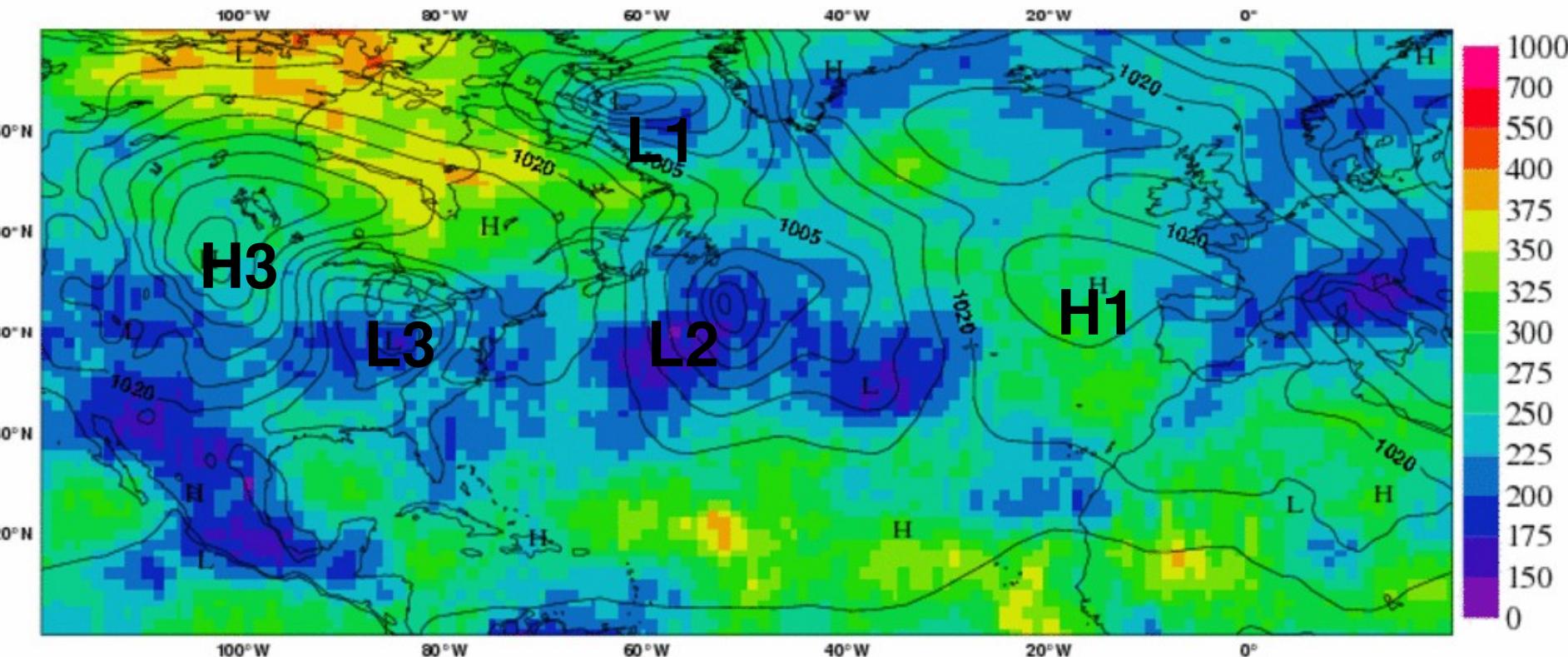
22/01/2005 00UTC ( 8/12)

# Length-scales of the day



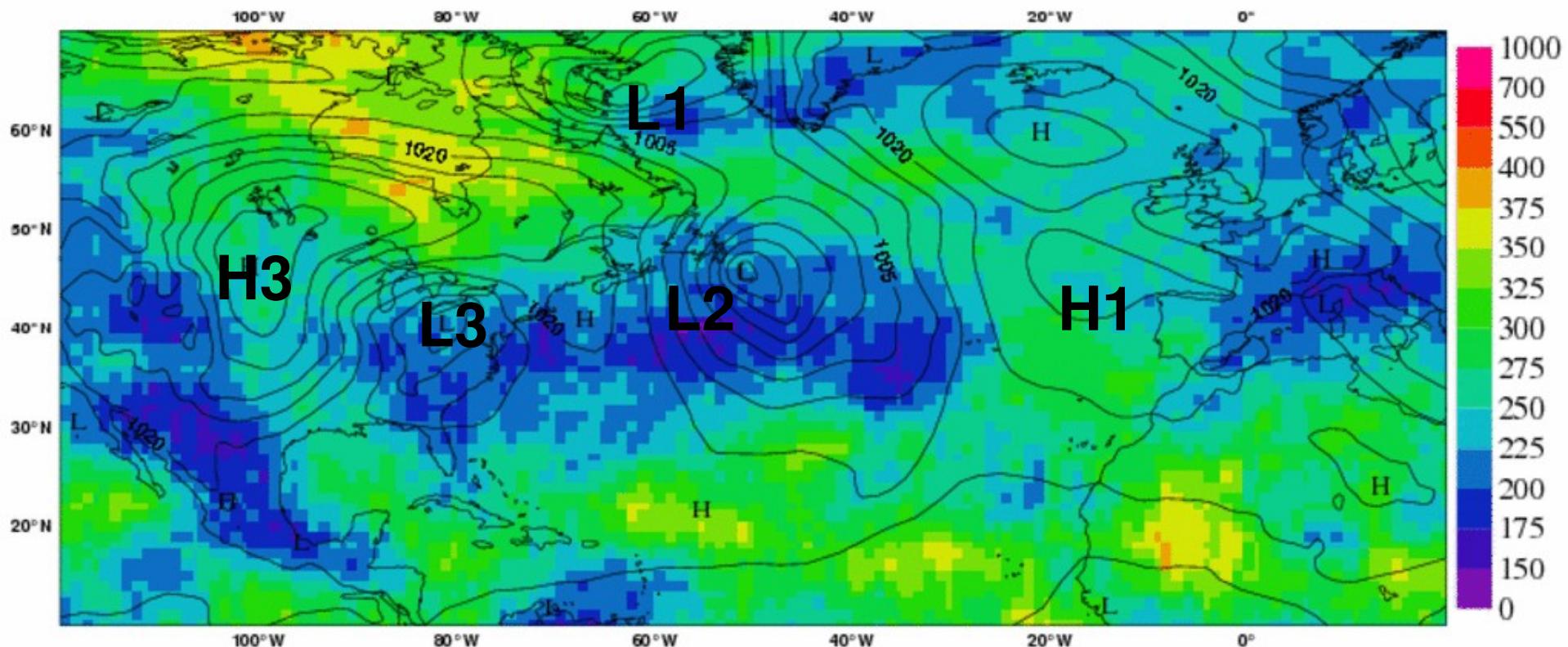
22/01/2005 06UTC ( 9/12)

# Length-scales of the day



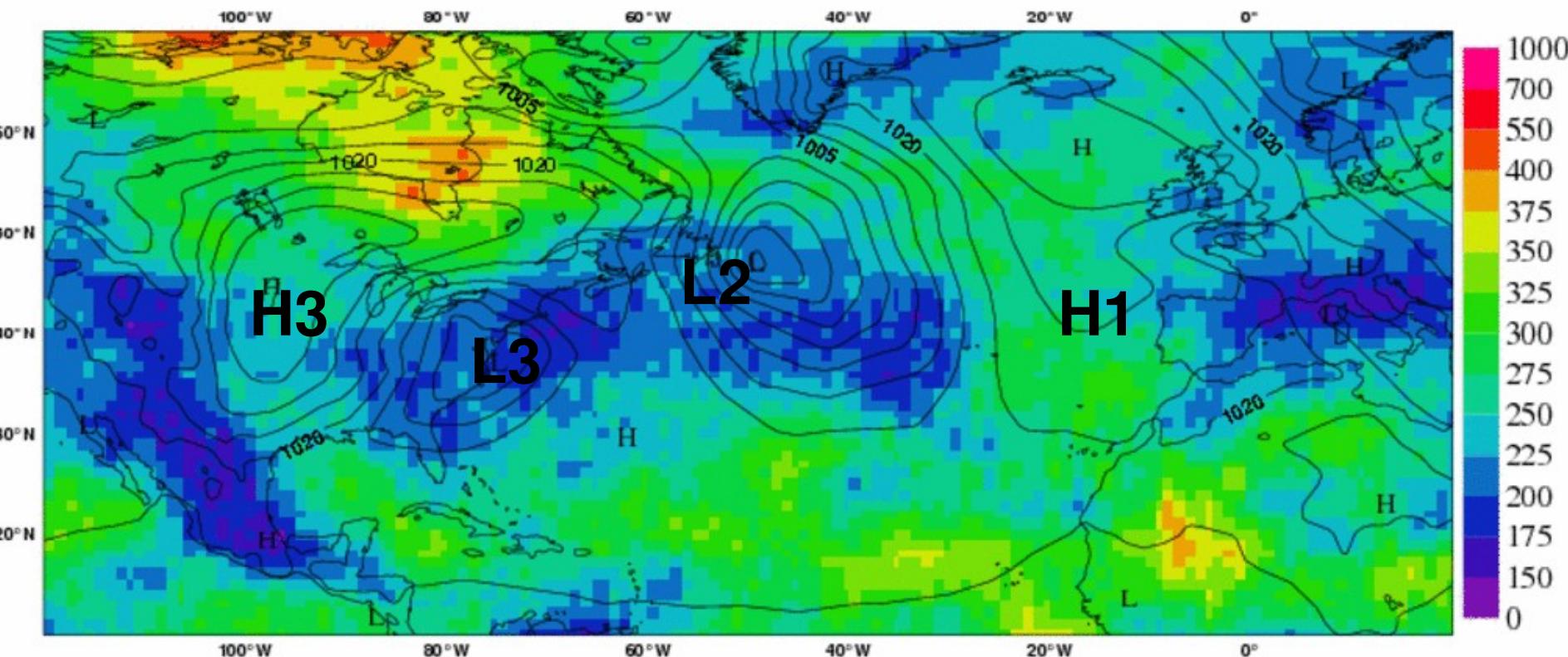
22/01/2005 12UTC (10/12)

# Length-scales of the day



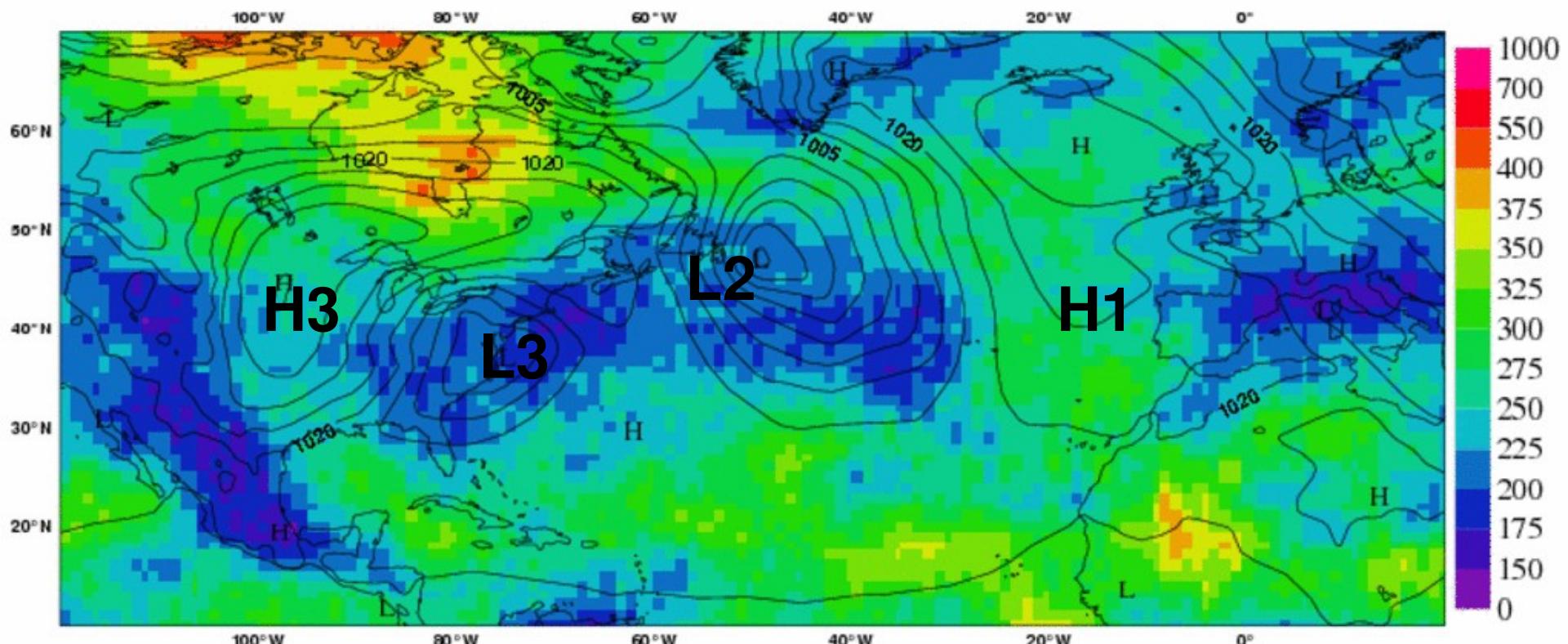
22/01/2005 18UTC (11/12)

# Length-scales of the day



23/01/2005 00UTC (12/12)

# Discussion



## Conclusions and perspectives

- Using an assimilation ensemble and spatial filtering is a promising way to obtain flow-dependent covariances (+ balances) (in a more realistic way than with a simplified background state dependence)
- The spatial filtering is justified by the small scale structure of sampling noise, and it can be optimized objectively.
- The local spatial averaging allows the sample size to be much increased, the ensemble size being MULTIPLIED by a 2D spatial sample size.

# Conclusions and perspectives

- The spatial filtering is costless: it may help to make the ensemble size and cost reasonable.
- First impact experiments and comparisons with innovation diagnostics are encouraging. => operational in 2007-2008 ?
- Applications for assimilation diagnostics and ensemble prediction too.