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Storm Prediction over Europe using the ECMWF Ensemble Prediction System

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Abstract

Three severe storms caused great damage in Europe in December 1999. The first storm hit Denmark and Germany on the 3rd and the 4th of December, and the other two storms crossed France and Germany on the 26th and the 28th of December.

Firstly, the performance of the Ensemble Prediction System (EPS) operational at the European Centre for Medium-Range Weather Forecast (ECMWF) in predicting these intense storms is investigated. Results indicate that the EPS gave early indications of possible severe storm occurrence, and was especially useful when the deterministic TL319L60 forecasts issued on successive days were highly inconsistent. These results indicate that the EPS is a valuable tool for assessing quantitatively the risk of severe weather and issuing early warnings of possible disruptions.

Secondly, the impact of an increase of the ensemble system horizontal resolution (T L255 integration from a TL511 analysis instead of the operational T L159 integration from a TL319 analysis) on the system performance is also investigated. Results show that the resolution increase enhances the ensemble performance in predicting the position and the intensity of intense storms.

1. INTRODUCTION

Human activities have become increasingly more vulnerable to severe weather (*Kunkel et al.* 1999, *Easterling et al.* 1999) and there is an increasing demand that numerical weather prediction centers provide reliable forecasts of such severe events. Early indications of severe weather events are necessary to improve the quality of systems designed to issue early warnings of potentially severe damages. In the United States, average costs of \$16 billion are incurred annually for weather-related damages (*Pielke* 1997).

Severe events are often associated with very energetic phenomena such as flooding, strong winds and extreme temperatures. In forecasting such events small errors in the initial conditions may grow very quickly and affect the forecast accuracy. Furthermore, model uncertainties due to the discrete representation of the system equations may increase the forecast error growth. As a consequence, forecasting systems based on single deterministic forecasts may not be reliable.

Since 1992, ensemble prediction systems based on multiple integrations of model equations have become part of the operational numerical weather prediction practice (*Palmer et al.* 1993, *Toth & Kalnay* 1993, *Houtekamer et al.* 1996). Ensemble prediction provides a tool for quantifying the risk of severe weather.

At the European Centre for Medium-Range Weather Forecasts (ECMWF), the Ensemble Prediction System (*Molteni et al.* 1996) has been designed to simulate both initial and model uncertainties. The initial uncertainties are simulated by starting the multiple integrations from perturbed initial conditions (*Buizza & Palmer* 1995). Model uncertainties due to the parameterized physical processes are simulated by stochastically perturbing the model equations (*Buizza et al.* 1999).

Two main issues are discussed in this work. First, the performance of the ECMWF forecasting system during the three severe storms that caused great damage in Europe in December 1999 is discussed. At the time of the events, the deterministic high-resolution model had horizontal spectral triangular truncation T319 with



linear grid and 60 vertical levels ($T_L319L60$) and the EPS had resolution $T_L159L40$ and 51 members, with initial conditions defined from the $T_L319L60$ analysis. The first storm hit Denmark and Germany on the 3^{rd} and the 4^{th} of December, and the other two storms crossed France and Germany on the 26^{th} and the 28^{th} of December. Strong winds associated with intense fast-moving cyclones caused serious disruptions, several deaths and billion of dollars (\$US) of damages (*Bell et al.* 2000). Numerous buildings and vast areas of forests were destroyed by the winds, while transport and power outages affected large areas for several days.

Then, the impact of an increase of the ensemble system horizontal resolution is investigated. EPS forecasts are compared with forecasts from a higher resolution experimental ensemble system (HEPS) based on 51 members as the EPS but with higher horizontal resolution (T_L159 instead of T_L255) and with initial conditions defined from a higher-resolution T_L511 analyses (by contrast, the EPS initial conditions were defined using operational T_L319 analyses). This high-resolution configuration became operational at ECMWF on the 21st of November 2000. The performance of the HEPS and the EPS are compared.

2. The ECMWF Ensemble Prediction System

Since December 1996, the ECMWF EPS has been based on 51 members at $T_L159L31$ resolution (spectral triangular truncation T159 with linear grid, *Buizza et al.* 1998). In October 1998, a scheme to simulate model uncertainties due to random model error in the parameterized physical processes was introduced (*Buizza et al.* 1999), and in October 1999 the number of vertical levels of the EPS was been increased to 40, with the extra levels in the planetary boundary layer (*Teixeira* 1999).

Schematically, the current EPS can be described as follows. Each EPS forecast e_j is generated by integrating the perturbed model equations

$$\frac{\partial e_j}{\partial t} = A(e_j, t) + P'_j(e_j, t) \tag{1}$$

starting from perturbed initial conditions

$$e_{j}(t=0) = e_{0}(t=0) + \delta e_{j}(t=0)$$
⁽²⁾

A and P' identify the contribution to the full equation tendency of the non-parameterized and parameterized physical processes. For each grid point $\mathbf{x} = (\lambda \phi, \sigma)$ (identified by its latitude, longitude and vertical hybrid coordinate), the perturbed parameterized tendency P' (of each state vector component) is defined as

$$P'_{j}(e_{j},t) = [1 + \langle r_{j}(\lambda,\phi,t) \rangle_{D,T}]P(e_{j},t)$$
(3)

where *P* is the unperturbed diabatic tendency, and $<...>_{D,T}$ indicates that the same random number r_j has been used for all grid points inside a *DxD* degree box and over *T* time steps. The random numbers are currently sampled uniformly in the interval *[-0.5,0.5]*, the same random number is used inside 10 ° degrees boxes (*D*=10), and the set of random numbers is updated every 6 hours (*T*=6) (note that random numbers do not vary with the vertical coordinate).



 $e_0(t=0)$ in Equation (0 is the operational analysis at t=0, while δe_j denotes the j-th initial perturbation. For each initial day *d*, the initial perturbations are defined using the singular vectors growing in the forecast range between day *d* and day d+2 at initial time, and the singular vectors that had grown in the past between day *d*-2 and day *d* at final time

$$\delta e_{j}(t=0) = \sum_{i=1}^{25} [\alpha_{i,j} v_{i}^{d,d+2}(t=0) + \beta_{i,j} v_{i}^{d-2,d}(t=48h)]$$
(4)

where $v_i^{d,d+2}(t=0)$ is the *i*-th singular vector growing between day d and d+2 at time t=0 (*Barkmeijer et al.* 1999). The coefficients $\alpha_{i,j}$ and $\beta_{i,j}$ set the initial amplitude of the ensemble perturbations, and are defined by comparing the singular vectors with estimates of analysis errors (*Molteni et al.* 1996).

At the time of the events under investigation the ensemble forecasts were post-processed and saved only every 12-hours (since March 2000 ensemble surface variables are post-processed and saved every 6 hours). As a consequence and since the initial time for the ECMWF operational ensemble is 12 UTC, verification can only be performed either at 00 or at 12 UTC.

3. Measures of forecast accuracy

Forecast verification is focused on mean-sea-level-pressure (MSLP), with forecasts started on subsequent days are verified at the same forecast time inside regions centered on the observed storms. The quality of the single deterministic and ensemble prediction is assessed by computing the error in the prediction of the intensity (Intensity Error, IE) and of the position (Position Error, PE) of the MSLP minimum value. Local minimum values are searched inside a verification region centered on the observed storm, and if found the position and the intensity of the MSLP minimum value is computed (this software was kindly provided by *Martin Leutbecher*). The intensity error IE (in hPa) is the absolute difference between the forecast and analysis pressure minimum and the position error PE is the distance (in km) between the forecast and the analyzed position. The root-mean-square error (RMSE) inside a verification area centered on the storm observed position is also computed, but the RMSE should be used with care when considering the prediction of fields characterized by a strong gradient such as deep lows. In this cases, in fact, a smooth forecast without any deep low could have a smaller RMSE than a forecast with a misplaced deep low, which maybe more informative than the previous one. The intensity and position error should be preferred in this case.

4. The Danish/German storm (3-4 December 1999)

This storm affected Denmark, Germany and other Baltic countries on the 3^{rd} and the 4^{th} of December 1999 (Fig. 1). A low-pressure system located northwest of Ireland at 00UTC on the 3^{rd} of December (Fig. 1a) deepened from 996hPa to 961hPa during the following 12 hours (Fig. 1b) while moving eastward. In the next 12 hours the cyclone continued eastward into the Baltic sea while MSLP dropped from 961hPa to 957hPa (Fig. 1c), and then continued to move eastward while weakening its intensity (Fig. 1d). Since forecasts issued at short forecast ranges (say up to t+72h) were rather accurate (see discussion below), attention will be focused mainly on the t+132h and the t+84h forecast ranges.



Forecasts are verified at 00UTC on the 4th of December when the cyclone reached its strongest intensity and was located northeast of Denmark (Fig. 1c). The verification area used to compute the RMSEs has longitude between 0 and 25°E and latitude between 48°N and 62°N. Consideration of other verification times would have led to qualitatively similar conclusions.

4.1 Performance of the ECMWF deterministic T_L319L60 model

Table 1a lists the IE/PE errors of the $T_L319L60$ forecasts issued from the 26th of November (t+180h) to the 2nd of December (t+36h). Figure 2 shows the analysis of 00UTC on the 4th of December and the deterministic $T_L319L60$ forecast started on the 28th of November (t+132h). Figure 3 shows the corresponding forecasts started on the 30th of November (t+84h). The $T_L319L60$ forecasts issued between the 26th (t+180h) and the 30th (t+84h) of November were very inconsistent, with forecasts with low IE/PE alternated by forecasts with large errors (Table 1a). Only the $T_L319L60$ forecasts issued on the 1st (t+60h) and 2nd (t+36h) of December had IE/PE smaller than 10hPa/300km.

4.2 Performance of the operational and of the high-resolution EPS

The EPS control performed similarly to the $T_L319L60$ for forecast ranges longer than 60 hours while the $T_L319L60$ forecast performed better for shorter forecast times. The ensemble-mean, which is the most immediate product that can be constructed using the EPS, had an RMSE higher than the EPS control forecast for all forecast ranges (not shown). This should not surprise since the ensemble-mean, even if it is a smoother field than any single forecasts, cannot be expected to have a smaller RMSE when only one single case of a prediction of a deep low is considered. Table 1a lists the intensity and position errors of the EPS control and the $T_L319L60$ forecasts.

The EPS started on the 26th and the 27th of November (t+180h and t+156h, not shown) had only one member predicting the storm with IE<10hPa and 300km<PE<600km. Figure 2 shows the EPS control, the ensemblemean and five selected EPS members started on the 28th of November (t+132h). The selected members are the two EPS members with the smallest RMSE and the three members with the smallest IE. Figure 2 shows that the ensemble-mean forecast did not provide any indication of the possibility of a storm affecting the verification area. Figure 3 shows the EPS control, the ensemble-mean and five EPS selected members issued of the 30th of November (t+84h). These forecasts were more accurate than the forecasts issued two days before (Fig. 2), with fifteen EPS members characterized by IE/PE smaller than 20hPa/600km (Table 2, top-left gray-shaded area). Again, note that the ensemble-mean forecast did not give any indication of the possibility of a storm affecting the verification area.

Figure 4 shows the high-resolution ensemble (HEPS) t+132h forecasts corresponding to the EPS forecasts shown in Fig. 2. Compared to the EPS (Fig. 2), the HEPS forecasts predicted more correctly both the storm intensity and its position. HEPS member 2, which had the lowest RMSE of all forecasts (3.0hPa), had intensity/position errors of 5hPa/120km. HEPS member 3, ranked in second position according to RMSE (7.2hPa) and characterized by the smallest IE, had intensity/position errors of 0.4hPa/207km (for this forecast range, the $T_L319L60$ forecast had an RMSE of 7.6hPa and intensity/position errors of 13.1hPa/149km). Figure 5 shows the t+84h HEPS forecasts. The t+84h HEPS forecasts had much smaller intensity errors than the corresponding EPS forecasts (Fig. 3). This is summarized in Table 2, which lists the



impact the horizontal resolution increase on the IE/PE of the t+132h and the t+84h forecasts. The HEPS not only had a larger number of good forecasts (top-left gray-shaded area in Tables 2a,b) but it also had a lower number of poor forecasts (bottom-right gray-shaded area in Tables 1a,b), especially for the t+84h forecast range.

Figure 6 shows some IE/PE and the RMSE statistics of the EPS and HEPS. Results indicate that the number of EPS and HEPS members with small errors had been consistently increasing during subsequent days while approaching the verification time, and that the HEPS forecasts had smaller intensity and position errors, especially at short forecast ranges (t+36h and t+60h).

5. The French/German storms (26-28 December 1999)

During the days after Christmas 1999 Western Europe was hit by a sequence of intense storms. The first storm crossed French in the early hours of the 26th of December (Fig. 7a,b), causing severe damage. The second storm hit southwestern France on the 27th of December and the alpine region on the 28th of December (Fig. 7d-f). These two storms originated in the western Atlantic and moved very rapidly eastward in the very strong zonal flow. The two storms were very different in scale: while the first storm was a very small-scale vortex moving extremely rapidly (it crossed France in less than 12 hours), a larger scale characterized the second storm.

The atmospheric flow during this period was very complex, with small-scale vortices developing and interacting while moving very rapidly in the strong zonal flow. At one time, three of these intense vortices were positioned very closely, affecting France, the UK and the Eastern Atlantic. The fact that the flow was difficult to predict is confirmed by the strong inconsistency of $T_L319L60$ forecasts issued on successive days. Since long and medium range forecasts were rather poor up to t+60h especially for the first storm (see discussion below), verification will focus on the t+48h forecast range for the first storm and the t+60h forecast range for the second storm.

Forecasts for the first storm are verified at 12UTC on the 26th of December (Fig. 7b) and forecasts for the second storm are verified at 00UTC on the 28th of December (Fig. 7e). Two different verification areas are used to compute the RMSE at the two verification times, each of them centered on the observed position. The first area has longitude between 5°W and 20°E and latitude between 40°N and 57°N, while the second area has longitude between 10°W and 20°E and latitude between 40°N and 57°N. Verification at other times would have drawn qualitatively similar conclusions.

5.1 Performance of the ECMWF deterministic T_L319L60 model

5.1.1 First storm (verification time 12UTC on the 26th of December)

The top two panels of Fig. 8 shows the analysis and the $T_L319L60$ forecast issued the 24th of December (t+48h). At the 48h forecast range, the $T_L319L60$ forecast almost correctly positioned the large-scale trough but failed to predict the storm intensity and position. Table 1b lists the IE/PE of the $T_L319L60$ forecast issued from the 19th (t+168h) to the 25th (t+24h) of December. The $T_L319L60$ forecasts issued on the 19th (t+168h) and on the 20th of December (t+144h) were rather accurate in describing the large-scale flow and had an RMSE of about 8hPa, but had very large IE/PE (Table 1b). The $T_L319L60$ forecast issued on the 21st



of December (t+120h) wrongly predicted a zonal flow instead of the deep trough. The $T_L319L60$ forecasts issued the following days were very inconsistent, with forecasts with either large IE or large PE (the t+96h issued the 22^{nd} and the t+48h issued the 24^{th}) alternated by more accurate forecasts (the t+72h issued the 23^{rd} and the t+24h issued the 25^{th}).

5.1.2 Second storm (verification time 00UTC on the 28th of December)

The top two panels of Fig. 9 shows the analysis and the $T_L319L60$ forecast issued the 25^{th} of December (t+60h). At this forecast range, the $T_L319L60$ forecast missed the prediction of the storm. Table 1c lists the IE/PE of the $T_L319L60$ forecast issued from the 20^{th} (t+180h) to the 26^{th} (t+36h) of December. Table 1c indicates that the $T_L319L60$ forecast issued the 21^{st} of December (t+156h) was the only forecast with small IE/PE (4.3hPa/169km), preceded and followed by forecasts characterized by large IE/PE (Table 1c).

5.2 Performance of the operational and the high-resolution EPS

5.2.1 *First storm (verification time 12UTC on the 26th of December)*

The EPS control performed similarly to the $T_L319L60$ forecast (the $T_L319L60$ was better than the EPS control at the 168h and 96h forecast ranges, while the EPS control was better for the other forecast ranges). Table 1b shows that in terms of IE/PE the EPS control was worse than the $T_L319L60$ forecast for forecast ranges up to 96h, but it was better for shorter forecast ranges.

Figure 8 shows the EPS control, the ensemble-mean and five selected EPS forecasts started on the 24^{th} of December (t+48h). Eleven EPS members had an RMSE smaller than the T_L319L60 forecast and six EPS members had intensity/position errors smaller than 10hPa/600km. Figure 10 shows the corresponding HEPS t+48h forecasts. Compared to the EPS (Fig. 8), the HEPS members were better able to predict the small-scale vortex. HEPS member 49 had the lowest RMSE (2.7hPa) and HEPS member 44 had the lowest IE (0.2hPa) of all forecasts.

Figure 11a shows some IE/PE statistics for all forecast issued from the 19th (t+168h) to the 25th (t+24h) of December. None of the EPS members predicted the storm with IE/PE smaller than 10hPa/300km and at most 9 members predicted the storm with IE/PE smaller than 20hPa/600km. Figure 11a shows that for all forecast ranges, HEPS forecasts were characterized by smaller IE/PE. Figure 11b shows RMSE statistics for both the EPS and the HEPS forecasts. Only up to two EPS members had a RMSE smaller than 5hPa up to the 96h forecast range, while this number steadily increased for shorter forecast ranges. Figure 11b shows that the HEPS had more members than the EPS with an RMSE smaller than 10hPa but has less members with RMSE smaller than 5hPa.

Table 3 highlights in more details the impact of horizontal resolution on the 120h and 48h forecasts. At both these forecast ranges, the HEPS had more forecasts with IE/PE smaller than 10hPa/300km (three compare to zero at t+132h and one compared to zero at t+60h), but the HEPS has also more members with large errors.

5.2.2 Second storm (verification time 00UTC on the 28th of December)

The EPS control performed on average again similarly to the $T_L319L60$ forecast. In terms of IE/PE (Table 1c) the $T_L319L60$ forecast and the EPS control had comparable errors for all but the t+156 forecast range, for which the $T_L319L60$ forecast was more accurate.



Figure 9 shows the EPS control, the ensemble-mean and five selected EPS members started on the 25^{th} of December (t+60h). Twenty-eight EPS members had an RMSE smaller than the T_L319L60 model, and thirtysix had an IE smaller than the T_L319L60 model. EPS member 1, best in terms of RMSE, had IE=3.8hPa and PE=138km. The two EPS members with the lowest IE, members 11 and 35, are ranked in 45^{th} and 14^{th} position according to RMSE. EPS members 34, ranked in 2^{nd} position according to RMSE, is ranked in 24^{th} position in terms of IE, with IE/PE of 17.2hPa/183km. These differences between the ranking based on IE or RMSE confirm that RMSE may not be the most appropriate measure of forecast accuracy for fields characterized by strong gradients.

Figure 12 shows the HEPS forecast started on the 25^{th} of December (t+60h). For this forecast range, HEPS member 45 had the lowest RMSE and the second lowest IE (0.6Pa/38km, compared with 23hPa/904km for the T_L319L60 forecast, see Table 1c).

Figures 13 shows the IE/PE and the RMSE statistics for all EPS and HEPS forecasts started from the 19^{th} (t+180h) to the 25^{th} (t+36h) of December. Figure 13a shows that for forecast ranges longer than 96h none of the EPS members had IE/PE smaller than 10hPa/300km and that only at most eight members had intensity/position errors smaller than 20hPa/600km. These numbers were higher for shorter forecast ranges up to t+60h but they decreased for the t+36h forecast. A possible reason for this poor 36-hour prediction is that the EPS initial perturbations are optimized to generate the proper spread among the ensemble members after 2 days of integration (see section 1). Figure 13b shows the number of EPS members with RMSE smaller than 5 and 10hPa for all forecast issued from the 20^{th} (t+180h) to the 26^{th} (t+36h) of December. The number of EPS members with RMSE smaller than 10hPa steadily increased with forecast time, but only up to six EPS members had an RMSE smaller than 5hPa (note that the RMSE of the T_L319L60 model was lower than 5hPa only for the 156h forecast range, and that the RMSE of the EPS control was always larger than 5hPa). The HEPS had a slightly larger number of ensemble members with low intensity/position errors (Fig. 13a), but it had fewer members with low RMSE (Fig. 13b).

Table 4 lists in more details the number of EPS and HEPS forecasts issued on the 22^{nd} (t+132h) and on the 25^{th} (t+60h) of December with IE/PE within predefined intervals. Table 4 shows that the number of EPS members with IE/PE smaller than 10hPa/300km increases from zero to three between the t+132h and the t+60h. At both these ranges, the HEPS and the EPS had a similar number of forecasts with low IE/PE.

6. Conclusion

From December 1992 to December 1996, the European Centre for Medium-Range Weather Forecasts (ECMWF) had been running operationally the Ensemble Prediction System (EPS) with a 33 members with spectral triangular truncation T63 and 19 vertical levels (T63L19). In December 1996, the EPS resolution was enhanced to $T_L159L31$ (the subscript 'L' stands for linear grid) and the ensemble size to 51 members. In October 1999 the number of vertical levels was enhanced to 40. The EPS resolution was further increased to $T_L255L40$ on 21^{st} of November 2000, with initial conditions generated from a high-resolution analysis ($T_L511L60$), has been tested at ECMWF.



This work discussed the performance of the operational EPS and of the high-resolution HEPS during two periods of December 1999 characterized by intense storms over Europe. Forecast verification focused on mean-sea-level-pressure (MSLP). The quality of single deterministic forecasts has been assessed by computing the intensity and position error in the prediction of the MSLP minimum value and by computing the root-mean-square error (RMSE) inside a verification area centered on the cyclone position. Ensemble performance had been assessed by statistics based on the number of members with low intensity, position and root-mean-square error. Due to the limited number of cases investigated, the verification of probabilistic products had not been considered. A proper evaluation of the impact of resolution on ensemble probabilistic forecasts for a 3-month period is under way and will be the subject of a separate paper.

The EPS proved to be particularly helpful in cases of large inconsistency between deterministic $T_L319L60$ forecasts issued on successive days. In fact, EPS forecasts started on successive days confirmed and refined earlier ensemble forecasts in a more consistent way than successive deterministic $T_L319L60$ forecasts.

The EPS performed differently during the three cases. It was very successful in predicting the Danish storm, with EPS forecasts started on subsequent days consistently increasing the probability of occurrence and with many EPS members correctly predicting the intensity and the position of the storm. For this case characterized by a large-scale cyclone, the EPS gave some indications of the possibility of a severe storm affecting Denmark 132-hours before the event. The prediction was less accurate during the two French storms, with fewer EPS members correctly predicting the intensity and the position of the MSLP minimum value. This was particularly true for the first storm, which was characterized by a very small-scale vortex moving very rapidly across Europe. During the two French storms, the EPS provided forecasters with some indications of the chance of an intense storm 72- to 48-hours before the event. By contrast, the ECMWF deterministic T_L 319L60 model did not give any useful indications especially in the case of the second French storm.

The impact of horizontal resolution on the ensemble performance was also discussed. Results indicated that the high-resolution ensemble HEPS, based on $T_L255L40$ integration with initial conditions defined from the unperturbed $T_L511L60$ analysis, was better capable to correctly predict the intensity of severe storms. This positive impact was evident in the case of the Danish storm, was still positive but less detectable in the case of the first French storm but was neutral in the case of the second French storm. Although strong and statistically significant conclusions on the impact of resolution on ensemble performance cannot be drawn from these results, the indications were that high resolution is required to simulate small-scale features. The overall performance of the EPS and the HEPS system on a larger data set and using a larger set of verification measure will be the subject of a future study.

One of the difficult aspects of ensemble prediction is how to summarize the forecast information contained in the ensemble without oversimplifying it. Results have indicated that the ensemble-mean, which can be considered as the most immediate way to condense the ensemble of forecasts, may not be a useful forecast product in cases of extreme events. By contrast, MSLP stamp-maps showing all EPS members can provide the forecasters with indications of possible extreme weather events.



Longer advance warnings of severe weather events are increasingly requested to improve public safety and reduce economic damages (*Anthes et al* 2001). The ECMWF Ensemble Prediction System is a practical tool designed to assist users to issue weather predictions. The latest increase in resolution of the EPS implemented in November 2001 is part of the ECMWF continuous efforts to improve forecast quality and to develop a forecasting system of severe weather events such as the winter storms that caused casualties and huge damages to some European Countries in December 1999.

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Figure 1. Danish storm. (a) MSLP analysis at 00 UTC on the 3^{rd} of December 1999. (b) as (a) but at 12 UTC on the 3^{rd} . (c) as (a) but at 00 UTC on the 4^{th} . (d) as (a) but at 12 UTC on the 4^{th} . Contour interval is 5hPa, with shading for values below 980hPa.





Figure 2. Danish storm. (a) MSLP analysis at 00 UTC on the 4th of December 1999 and (b-I) t+132h T_L319L60 and EPS forecasts started at 12 UTC on the 28th of November. (b) T_L319L60 forecast; (c) EPS control forecast; (d) EPS ensemblemean forecast; (e-f) the two EPS members with the lowest RMSE; (g-i) the three EPS members with the smallest IE. In panels (b) and (c), *nor* and *noi* in the title indicate the number of EPS perturbed members with RMSE smaller than the T_L319L60 and the EPS control forecast. For all single forecast, the RMSE, IE and PE is reported in the panel title; for each ensemble perturbed member, the ranking position with respect to RMSE (*irms*) and IE (*iie*) (1 is given to the forecast with the smallest error) is also reported. Contour interval is 5hPa, with shading for values below 980hPa.







Figure 3. Danish storm. As Fig. 2 but showing t+84h T_L 319L60 and EPS forecasts started at 12 UTC on the 30th of November.





Figure 4. Danish storm. As Fig. 2 but showing HEPS forecasts.







Figure 5. Danish storm. As Fig. 3 but showing HEPS forecasts.



Danish storm (ver. 00 UTC on 4 Dec 99)

Figure 6. Danish storm, MSLP forecasts verified at 00 UTC on the 4th of December 1999. (a) Number of EPS perturbed members with IE/PE \leq 10hPa/300km (dashed line with diamonds) and with IE/PE \leq 20hPa/600km (dotted line with squares), number of HEPS perturbed members with IE/PE \leq 10hPa/300km (dotted line with triangles) and with IE/PE \leq 20hPa/600km (solid line with crosses). (b) Number of EPS perturbed members with RMSE \leq 15hPa (dashed line with diamonds) and RMSE \leq 20hPa (dotted line with squares) and number of HEPS with RMSE \leq 15hPa (dotted line with triangles) and RMSE \leq 20hPa (solid line with crosses).





Figure 7. First French storm. (a) MSLP analysis at 00 UTC on the 26^{th} of December 1999, (b) as (a) but at 12 UTC on the 26^{th} , (c) as (a) but at 00 UTC on the 27^{th} , (d) as (a) but at 12 UTC on the 27^{th} , (e): as (a) but at 00 UTC on the 28^{th} , (f) as (a) but at 12 UTC on the 28^{th} . Contour interval is 5hPa, with shading for values below 980hPa.





Figure 8. First French storm. (a) MSLP analysis at 12 UTC on the 26th of December 1999 and (b-i) t+48h T_L319L60 and EPS forecasts started at 12 UTC on the 24th of December. (b) T_L319L60 forecast; (c) EPS control forecast; (d) EPS ensemble-mean forecast; (e-f) the two EPS members with the lowest RMSE; (g-i) the three EPS members with the smallest IE. In panels (b) and (c), *nor* and *noi* in the title indicate the number of EPS perturbed members with RMSE smaller than the T_L319L60 and the EPS control forecast. For all single forecast, the RMSE, IE and PE is reported in the panel title. For all single forecast, the RMSE, IE and PE is reported in the panel title; for each ensemble perturbed member, the ranking position with respect to RMSE (*irms*) and IE (*iie*) (1 is given to the forecast with the smallest error) is also reported. Contour interval is 5hPa, with shading for values below 980hPa.





Figure 9. Second French storm. (a) MSLP analysis at 00 UTC on the 28^{th} of December 1999 and (b-i) t+60h T_L319L60 and EPS forecasts started at 12 UTC on the 25^{th} of December. (b) T_L319L60 forecast; (c) EPS control forecast; (d) EPS ensemble-mean forecast; (e-f) the two EPS members with the lowest RMSE; (g-i) the three EPS members with the smallest IE. In panels (b) and (c), *nor* and *noi* in the title indicate the number of EPS perturbed members with RMSE smaller than the T_L319L60 and the EPS control forecast. For all single forecast, the RMSE, IE and PE is reported in the panel title. For all single forecast, the RMSE, IE and PE is reported in the panel title. For all single forecast, the RMSE, IE and PE is reported in the panel title; for each ensemble perturbed member, the ranking position with respect to RMSE (*irms*) and IE (*iie*) (1 is given to the forecast with the smallest error) is also reported. Contour interval is 5hPa, with shading for values below 980hPa.





Figure 10. First French storm. As Fig. 8 but showing HEPS forecasts.





French storm 1 (ver. 12 UTC on 26 Dec 99)

Figure 11. First French storm forecasts verified at 12 UTC on the 26th of December 1999. (a) Number of EPS perturbed members with IE/PE \leq 10hPa/300km (dashed line with diamonds) and with IE/PE \leq 20hPa/600km (dotted line with squares), number of HEPS perturbed members with IE/PE \leq 10hPa/300km (dotted line with triangles) and with IE/PE \leq 20hPa/600km (solid line with crosses). (b) Number of EPS perturbed members with RMSE \leq 15hPa (dashed line with diamonds) and number of HEPS with RMSE \leq 15hPa (dotted line with triangles) and RMSE \leq 20hPa (solid line with crosses).





Figure 12. Second French storm verified at 00 UTC on the 28th of December 1999. As Fig. 9 but showing the HEPS forecasts.





French storm 2 (ver. 00 UTC on 28 Dec 99)

Figure 13. Second French storm forecasts verified at 00 UTC on the 28th of December. As Fig. 11.



Danish Storm (ver. 00 UTC on 4 December 1999)							
Initial date	Forecast time (h)	Intensity e T∟319L60	error (hPa) EPS control	Position e T∟319L60	error (km) EPS control		
26 Nov	T+180h	24.7	15.8	133	348		
27 Nov	T+156h	70.3	30.1	1169	739		
28 Nov	T+132h	13.1	33.1	149	249		
29 Nov	T+108h	36.1	35.6	394	140		
30 Nov	T+84h	28.4	26.7	292	107		
1 Dec	T+60h	4.6	9.3	141	111		
2 Dec	T+36h	1.3	4.0	81	251		

Table 1a.

French Storm (ver. 12 UTC on 26 December 1999)							
Initial date	Forecast time	Intensity e	error (hPa)	Position e	Position error (km)		
	(h)	T ₁ 319L60	EPS control	T ₁ 319L60	EPS control		
19 Dec	T+168h	25.9	35.3	825	231		
20 Dec	T+144h	43.7		636			
21 Dec	T+120h						
22 Dec	T+96h	19.1	5.1	225	507		
23 Dec	T+72h	1.3	2.0	366	81		
24 Dec	T+48h	13.5	11.1	406	77		
25 Dec	T+24h	2.4	3.6	175	128		

Table 1b.

	French Storm 2 (ver. 00 UTC on 28 December 1999)						
Initial date	Forecast time	Intensity e	error (hPa)	Position e	error (km)		
	(h)	T _L 319L60	EPS control	T _L 319L60	EPS control		
20 Dec	T+180h	28.3	25.0	1151	751		
21 Dec	T+156h	4.3	33.0	169	654		
22 Dec	T+132h	14.7	11.8	666	833		
23 Dec	T+108h	15.1	18.5	472	134		
24 Dec	T+84h	32.2	29.5	471	795		
25 Dec	T+60h	22.7	23.0	904	596		
26 Dec	T+36h	22.8	23.3	526	623		

Table 1c.

Table 1. IE/PE of the $T_L319L60$ and the EPS $T_L159L40$ control forecasts for (a) the Danish storm verified at 00UTC on the 4th of December, (b) the French storm verified at 12 UTC on the 26th of December and (c) the French storm 2 verified at 00 UTC on the 28th of December 1999.



Danish Storm (ver. 00 UTC on 4 December 1999)						
28 Nov t+132h PE 0-300km PE 300-600km PE 600-900km PE > 900km						
IE 0-10hPa	0 (2)	0 (3)	0 (2)	0 (2)		
IE 10-20hPa	0 (0)	2 (1)	1 (3)	0 (0)		
IE 20-30hPa	0 (0)	6 (4)	3 (3)	4 (1)		
IE > 30hPa	4 (1)	11 (13)	5 (3)	5 (5)		

Table 2a

Danish Storm (ver. 00 UTC on 4 December 1999)						
30 Nov t+84h PE 0-300km PE 300-600km PE 600-900km PE > 900km						
IE 0-10hPa	1 (0)	2 (4)	1 (6)	0 (0)		
IE 10-20hPa	5 (5)	7 (9)	3 (0)	3 (0)		
IE 20-30hPa	1 (4)	5 (3)	3 (2)	1 (0)		
IE > 30hPa	1 (2)	12 (14)	5 (1)	0 (0)		

Table 2b.

Table 2. Danish storm. Number of EPS and HEPS (in brackets) perturbed members with IE and PE included in defined interval, for (a) ensembles started on the 28^{th} of November (t+132h) and (b) on the 30^{th} of November (t+84h).

French Storm (ver. 12UTC on 26 December 1999)						
21 Dec t+120h PE 0-300km PE 300-600km PE 600-900km PE > 900km						
IE 0-10hPa	0 (3)	2 (2)	6 (2)	2 (7)		
IE 10-20hPa	0 (1)	1 (1)	2 (1)	5 (6)		
IE 20-30hPa	0 (0)	1 (1)	0 (2)	0 (1)		
IE > 30hPa	0 (0)	0 (1)	19 (14)	0 (4)		

Table 3a

French Storm (ver. 12 UTC on 26 December 1999)						
24 Dec t+48h PE 0-300km PE 300-600km PE 600-900km PE > 900km						
IE 0-10hPa	0 (1)	6 (6)	16 (5)	3 (2)		
IE 10-20hPa	0 (1)	3 (5)	3 (1)	0 (2)		
IE 20-30hPa	0 (0)	2 (6)	9 (8)	0 (5)		
IE > 30hPa	0 (0)	0 (0)	2 (7)	1 (1)		

Table 3b.

Table 3. First French storm. Number of EPS and HEPS (in brackets) perturbed members with IE and PE included in defined interval, for ensembles started (a) on the 21^{st} of December (t+120h) and (b) on the 24^{th} of December (t+48h).



French Storm 2 (ver. 00 UTC on 28 December 1999)						
22 Dec t+132h PE 0-300km PE 300-600km PE 600-900km PE > 900km						
IE 0-10hPa	0 (1)	0 (1)	3 (1)	4 (3)		
IE 10-20hPa	4 (0)	4 (7)	7 (5)	5 (1)		
IE 20-30hPa	0 (0)	1 (11)	8 (9)	2 (2)		
IE > 30hPa	0 (0)	4 (2)	5 (3)	1 (3)		

Table 4a

French Storm 2 (ver. 00 UTC on 28 December 1999)						
25 Dec t+60h PE 0-300km PE 300-600km PE 600-900km PE > 900km						
IE 0-10hPa	3 (4)	5 (4)	0 (0)	1 (1)		
IE 10-20hPa	6 (1)	6 (4)	8 (1)	3 (3)		
IE 20-30hPa	1 (1)	8 (8)	4 (7)	0 (3)		
IE > 30hPa	0 (1)	0 (10)	5 (3)	1 (0)		

Table 4b.

Table 4. Second French storm. Number of EPS and HEPS (in brackets) perturbed members with IE and PE included in defined interval, for ensembles started (a) on the 22^{nd} of December (t+132h) and (b) on the 25^{th} of December (t+60h).