

Representing model error in the Met Office convection permitting ensemble prediction system

Anne McCabe, Richard Swinbank, Warren Tennant and Adrian Lock

ECMWF/WWRP Workshop Model Uncertainty April 2016



### Outline

- MOGREPS-UK
- Representing model uncertainty at the convective scale
- Improved Random Parameter Scheme
- Fog case studies
- Verification statistics from month long trials
- Future work



# MOGREPS-UK set-up from 2013 to early 2016



- Straight downscaler of the MOGREPS-G forecast
- Initial & boundary conditions from global forecast.
- Model physics as 1.5km UKV
- 4 cycles per day, 12 members to T+36.

Operational MOGREPS-UK is now centred around the UKV analysis (March 2016)

# Met Office Model uncertainty in a convective Scale ensemble prediction system

Need to represent model uncertainty to accurately represent forecast probabilities

Use experience of modelling uncertainty at the synoptic scales

Different physical processes dominate at the convective-scale

> Adapt stochastic physics schemes to specifically target areas of model uncertainty relevant for convective scale

What are the relevant areas of model uncertainty?

Use experience of forecasters and parametrization modellers to identify key areas in the model that are either inherently uncertain or known to be inadequately represented



# Which stochastic physics scheme?

Schemes to target missing physical processes:

**SKEB** – based on synoptic scale arguments; would need reviewing to apply at the convective scale

#### **BL perturbations** –

backscatter the effect of unresolved processes

Pragmatic approaches to target missing aspects of model uncertainty:

**RP scheme** – represents knowledge uncertainty in parametrizations

**SPPT** – perturbation to total tendencies; independent of physics parametrizations

#### **Start with RP scheme and BL perturbations**



Basic<br/>Idea:choose a subset of parameters from relevant<br/>parametrization schemes and vary them<br/>stochastically throughout the forecast

Advantages:

Addresses knowledge uncertainty in physics parametrizations Physically realistic tendencies

Conceptually simple and computationally cheap to implement

#### Difficulties:

Needs to be regularly reviewed / revised as parametrizations changeChoice of parameters and ranges can be subjectiveModest impact on spread and skillQuestion of best time evolution of parameter values



### Improved RP algorithm

#### Slower, more smoothly varying parameter path

Original

Improved





Parameters are chosen to target uncertainty at the small-scales





# RP scheme increases variability in fog forecasts

#### Number of points with visibility < 1km, for each member





### RP scheme reduces overconfident fog forecasts

#### Probability of fog. Winter case study. 11<sup>th</sup> – 12<sup>th</sup> December. T+19





## RP ensemble captures observed fog missed by control forecast

#### Probability of fog. Winter case study. 15<sup>th</sup> – 16<sup>th</sup> January. T+8



## RP scheme increases spread in Met Office surface wind and temperature

## Increase in spread is small and the ensemble remains underspread



<sup>68.26%</sup> error bars calculated using standard normal distribution

Surface (10m) Wind (m/s), Area 517, Meaned between 20130101 01:00 and 20130131 23:00,

Surface (1.5m) Temperature (deg K), Area 517,

<sup>68.26%</sup> error bars calculated using standard normal distribution

Ranked Probability Score (Ensemble FC(j) (Excluding Control)), Area 517, Meaned between 20130101 01:00 and 20130131 23:00, Surface Obs



Surface (1.5m) Visibility (< 1000.0), Brier Score (Ensemble FC(j) (Excluding Control)), Area 517, Meaned between 20130101 01:00 and 20130131 23:00, Surface Obs



RP ensemble gives improved verification scores over month long trial for visibility and cloud base height

### Plots compare RP and control ensembles

Ranked Probability Score (Ensemble FC(j) (Excluding Control)), Area 517, Meaned between 20130101 01:00 and 20130131 23:00, Surface Obs





### Summary

- Improved RP scheme applied to convective scale ensemble prediction system
- Practical method to tackle known areas of model uncertainty
- Shown to be effective at increasing variability in fog forecasts in a physically realistic way
- Limited effect on verification scores MOGREPS-UK remains underspread



### **Ongoing & future work**

**Verification of fog forecasts** – replace month long trials with a series of interesting fog case studies

**Extensions of RP work:** 

- uncertainty in the land-surface
- **RP3** for global ensemble see Warren Tennant's poster

#### **Refinements to BL perturbations** – Adrian Lock (Met Office), Peter Clark (Reading University) and Carol Haliwell (Met Office)



# Thank you for listening

