

### Observations and their importance in the verification process: view of the Joint Working Group on Forecast Verification Research (JWGFVR)

#### Anna Ghelli

Thanks to: Simon Mason, Laurie Wilson, Barbara Casati, Barbara Brown, Beth Ebert, Joel Stein, Pertti Nurmi

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12 MOS Workshop, ECMWF, November 2009



#### Vision:

To promote best practices and understanding of verification methods

#### **Activities:**

- Verification guidance and support for WMO Forecast **Demonstration Projects**
- Participation in activities of other WMO groups
- Documentation of recommended methods for specific application
- Education

#### Who are we?

Barbara Brown (NCAR) Beth Ebert (BOM) Anna Ghelli (ECMWF) Marion Mittermaier (UK MetOffice) Pertti Nurmi (FMI) Joel **Stein** (Meteo France) Clive **Wilson** (UK MetOffice)

Barbara **Casati** (Ouranos) Harold **Brooks** (NOAA) Martin Goeber (DWD) David Stephenson (Uni. Exeter) Laurie **Wilson** (Env. Canada)

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#### International Verification Methods Workshop June 4 – 10, 2009 To be held at FMI, Helsinki, Finland

utorial Session: June 4-6 Scientific Workshop: June 8-10



#### Where in WMO?

#### http://www.wmo.int/pages/prog/arep/wwrp/new/Forecast Verification.html



GE



#### History and achievements:

2002 Birth

2002 1st workshop (Boulder, Colorado, USA)

2004 2nd workshop (Montreal, Canada)

- 2007 3rd workshop (ECMWF, Reading, UK) the workshop included for the first time tutorials
- **2008** Special issue of Meteorological Applications vol. 15 no. 1 with papers from the 3rd international workshop.
- **2009** Publication WMO/TD-No. 1485 "Recommendations for verification of QPF"
- 2009 4th workshop (FMI, Helsinki, Finland), tutorials were run as integral part of the workshop

12 MOS Workshop, ECMWF, November 2009

**3rd International Workshop on** Verification Methods, ECMWF, Reading, January 2007







#### outline

- Quality control
- Observation uncertainty: how to account for it
- Observation dataset independency
- The role of analyses in verification
- Conclusions







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### **Quality control**

#### **Quality control**

- Remove gross errors
- Remove instruments and reporting errors
- Remove biases

#### **Properties**

- Standardized procedures
- Model independent





(P. Lopez, ECMWF, Tech. Memo. 569, 2008)

#### Mean differences OPERA–dataset (mm day<sup>-1</sup>) Period: 10 April – 8 June 2008 (60 days)







-- Comparisons with other datasets -- Common procedures

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(P. Lopez, ECMWF, Tech. Memo. 569, 2008)

OPERA-dataset mean correlation vs OPERA–dataset mean difference (various domains) Period: 10 April – 8 June 2008 (60 days)







#### **Quality control in Data Assimilation**

#### Comparing two norms: Huber (red) Gaussian (blue)

- More weight in the middle of the distribution
- More weight on the edges of the distribution
- More influence of data with large departures

-Weights: 0 – 25%



(Lars Isaksen and Cristina Tavolato, ECMWF)

FCMWF



#### **French Storm**



## WGFVR French Storm

#### 1362: VarQC-rejections: Flag1 (green), Flag2 (orange), Flag3 (red), MSL analysis (black) 066 57 50°N 50°N 0 57 57 32<sup>51</sup> 000 VarQC weight = 50-75% VarQC weight = 25-50% VarQC weight = 0-25% 00 **ECMWF**

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-- not model independent



### **Uncertainty in observations**

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#### **Sources of Uncertainty**

- Observation error
- "Under-sampling" of station data
- Interpolation (time and space)
- Analysis errors

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How can we cope with observational uncertainty?





# Verification using RADAR and rain gauges

- QPF in pre-specified area  $\rightarrow$  River / Lake catchment
- Three independent components addressing the quality

Structure	- S -	-2	0	+2
		object too small or too peaked	Perfect	objects too large or too flat
Amplitude	- A -	-2	0	+2
		Averaged QPF under- estimated	Perfect	Averaged QPF over- estimated
Location	- L -	-2	0	+2
For a perfect forecast: S = A = L = 0			Perfect	wrong location of Total Center of Mass (TCM) and / or of objects relative to TCM

Wernli, Paulat, Hagen, Frei, 2008 (MWR, 136, 4470-4487)

ECMWF



### Medium-size catchment

17 August 2008;24 hour accumulated precipitation



ECMWF ~ 25 km HIR\_RCR ~ 16 km HIR\_MB71 ~ 7.5 km MET\_Edit ~ 15 km S: 0.76 S: 0.48 S: 0.06 S: 1.13 A: 0.50 A: -0.42 A: 0.15 A: -0.64 L: 0.17 L: 0.15 L: 0.22 L: 0.15

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# Medium-size catchment

17 August 200824 hour accumulated precipitation





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#### Largest/flattest precip objects ref. winter/spring

Amplitude strongly overestimated Amplitude somewhat overestimated 0.66 2 0.50 0.27 ∢ 0 ∢ -1 -2 ⊾ -2 -2 -2 -1 0 2 1 -1 2 0 S **ECMWF** vs GAUGES **ECMWF vs RADAR** Pertti Nurmi, FMI Slide 16 12 MOS Workshop, ECMWF, November 2009

-- Which is the truth? -- Observation uncertainty

Too large/flat precip objects, on average



# Direct approaches for coping with observational uncertainty

Compare forecast error to known observation error

- If forecast error is smaller, then
  - A good forecast
- If forecast error is larger, then
  - A bad forecast

•Bowler (2008)

-Methods for reconstructing contingency table statistics, taking into account errors in classification of observations

•Ciach and Krajewski (1999)

-Decomposition of RMSE into components due to "true" forecast errors and observation errors







# Direct approaches for taking uncertainty into account

- Candille and Talagrand (2008)
  - Treat observations as probabilities (new Brier score decomposition)
- Briggs et al. (2005)
  - Incorporating mis-classification errors using a "gold standard"
- Casati (2008)
  - Wavelet reconstruction
- Roberts and Lean (2008)
  - Perturb pixels in the observed field to obtain error bars
- Hamill (2001)
  - Rank histogram perturbations
- Mittermaier (2008)
  - Incorporation of uncertainty in radar-rainfall estimates





Approaches:

### The matching game: Strive for an independent dataset

- Model to observations → model output is manipulated to become comparable to observations
- Observations to model → observations are manipulated to become comparable to model output





### The matching game

**VOCALS field experiment off Chile** 

#### GOES12 10.8µm GOES12IR10.8 20081018 18 UTC

#### ECMWF 10.8µm





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# The role of the analysis in verification

#### Analyses are model dependent

- Allows to use a number of different type of sensors to provide a coherent analysis for the model 
  this out-weight the drawback of model contamination
- Good if used for specific purposes e.g. when performance needs to be assessed for scales that the model can resolve and for comparison of same model (operational vs. experimental suite)
- Multi-analysis against observations scores better than single analysis
- Use of randomly drawn analyses for comparative verification of multiple models.





#### What do we need for verification purposes?



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