# The European Flood Forecasting system



HEPEX Workshop, 08-10 March 2004





## The EFFS: the facts

- Project EFFS was sponsored by the 5th Framework Programme of the European Commission.
- Duration 01/03/2000 31/09/2003 (42 months).
- EC financial contribution: 1.8 M€ over 3,5 years.
  11 institues + 8 NAS institutes= 19 partners in total.





### **EFFS Project Objectives**

- EFFS aims at developing a <u>prototype</u> of a flood forecasting system for the European countries for up to 10 days ahead.
- The main emphasis is on the <u>medium-range lead</u> time, i.e 4 to 10 days.
- The prototype is designed at providing pre-warning to local water and flood forecasting authorities across Europe.
- The system should permit encapsulation of preexisting hydrological and river routing models already tested and used by local authorities.



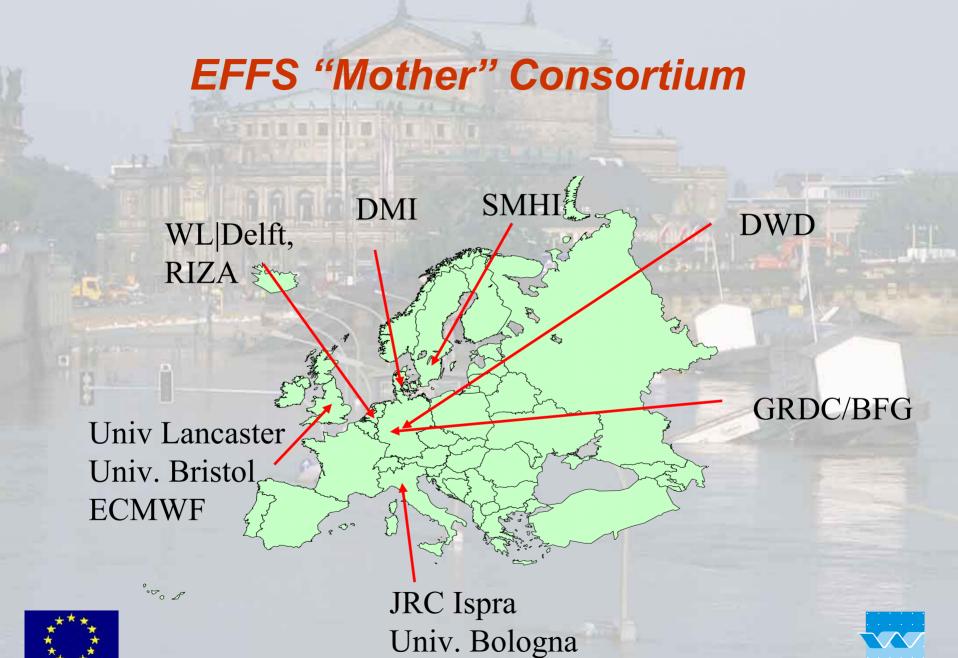


### **EFFS "Mother" Consortium**

- Original Consortium: 11 institutes
- 3 Weather services (DWD, DMI, ECMWF)
- 3 Universities (Lancaster, Bristol, Bologna)
- 2 Research Centres (Delft Hydraulics, JRC)
- 2 National Hydro-meteorological Services (SHMI, BAFG)
- 1 National Water Management Authority (RIZA)







### **EFFS NAS-1** amendment

- In June 2002 an EFFS <u>amendment</u> is approved to include 8 additional institutes from the Newly Associated States (NAS) in view of the enlargement of the EU.
- Amendment financed with ~ 4 k€ over 1 year
- New opportunities: Data from river systems in Eastern Europe are made available for sharing within the consortium.
- Results of hydrological and river routing models can be compared.





### **EFFS NAS-1 Partners**

GGI-LT

# IMWM-PL

### SHMU-SK Slovak UT-SK

°00 D



Uni Ljubljana-SI

250



Vituki Plc

NIMH-RO

NIMH-BG

### **EFFS Project Organigramm**



WP 1 Co-ordinator & interface with EC WL-Delft Hydraulics

WP 2 Meteorological data collection & supply DWD WP 3 Hydrological data collection GRDC WP 4: Building a geographical DB UNI Bristol

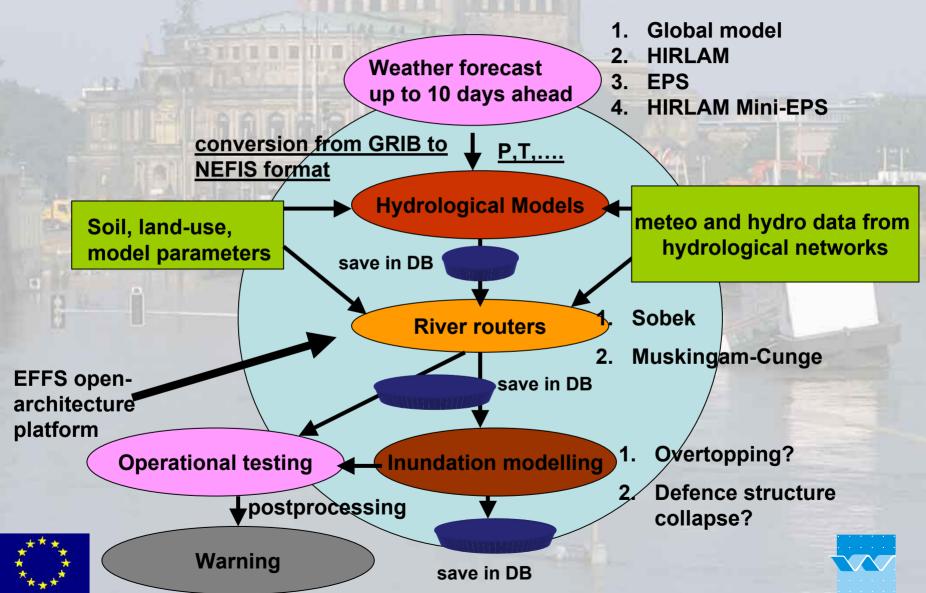
WP 5 Parameter and forecast uncertainty estimation Lancaster WP 6 Downscaling and validating meteorological forecasts DMI

WP 7 Development of the European-scale FF system JRC WP 8 Application, validation & comparison of watershed models Uni Bologna

WP 9 Set-up & testing of prototype system RIZA WP 10 Dissemination of forecasts & warnings SHMI



### **EFFS** structure



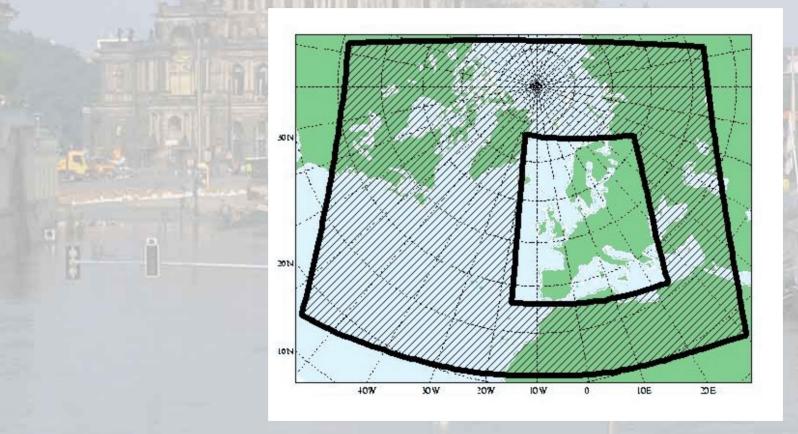
### **Numerical Weather forecasts**

- ECMWF supplies medium range meteorological data from their deterministic model and from their Ensemble Prediction System (EPS).
- DWD and DMI supply deterministic high resolution short range forecasts from their <u>High</u> <u>Resolution Local</u> <u>Area</u> <u>Model</u> (HIRLAM).
- HIRLAM is initialised through <u>Global</u> ECMWF model output
- The high-resolutions forecasts make it possible to estimate the impact of horizontal resolution of the atmospheric predictions on water level forecasts.
- In addition, DMI is experimenting with <u>mini ensembles</u> with the aim to investigate uncertainties in the precipitation forecasts.





### High Resolution Local Area Model nested domains



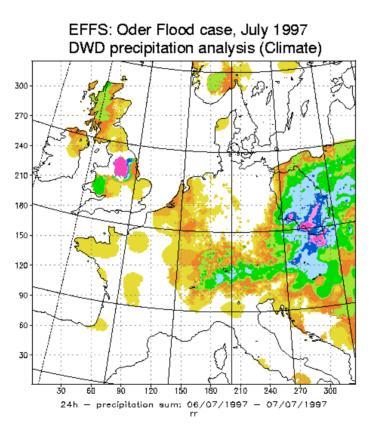
#### **Courtesy Danish Meteorological Institute**



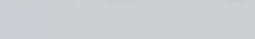


### **Precipitation hindcast**









### **Courtesy Deutscher Wetterdienst**



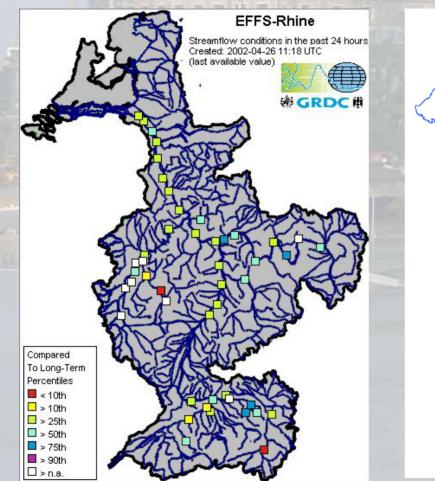
### Hydrological measuring networks in flood forecasting

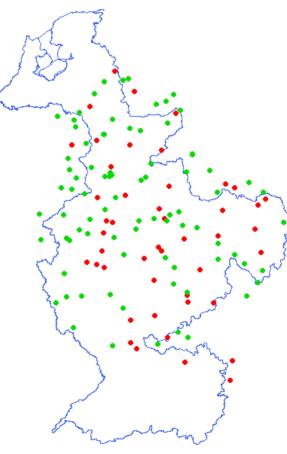
- The operation of a river basin-scale flood forecasting system, and in particular of a continental-scale system, as EFFS, requires regular update through measured data.
  - Which data are required?
- 1. Precipitation
- 2. Temperature
- 3. Synoptic weather data
- 4. Discharge data at critical locations
- 5. Water level data at critical locations





### Measuremement network for the Rhine Basin









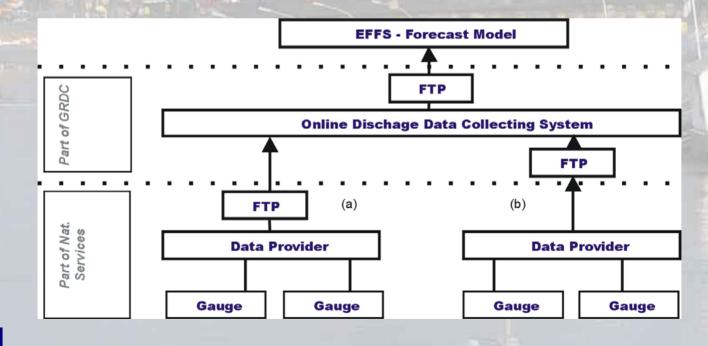
DWD meteorological stations



## **Data acquisition in EFFS**

•The following scheme shows the data-stream from measuring networks to the EFFS is performed.

•The data acquisition was led by the GRDC in Work-Package 3.

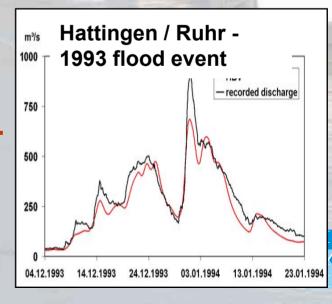


**Courtesy GRDC** 



# Utilisation of measured data in the flood forecasting system

- The regularly update measurement form the hydrological networks are used for the following purpose:
- In now-casting (extremely short lead-time, max 24 hrs) directly measured precipitation data form gauges and radar are used to drive models.
- in EFFS (mdium-range lead-time) hydrological and hydraulic models are updated (data assimilation) through data measured over the 2 weeks precedent the begin of the forecast.
- The data are transferred from the loggers over FTP into the database of the flood forecasting system.





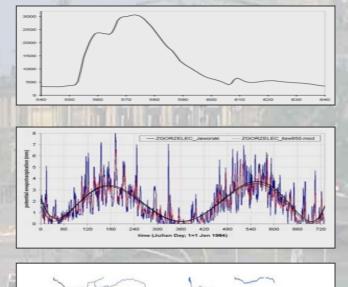
### Hydrological modelling

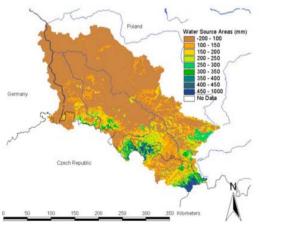
- Different hydrological models are used within the EFFS system:
- 1. HBV (SHMI) semi-distributed model the entire Rhine Basin (calibrated at the BFG, Koblenz) representing the Rhine Basin up to Switzerland through 134 sub-basins.
- 2. LISFLOOD (JRC) raster-based model for simulation of continental river basins at 5 sqkm resolution. Used in particular for Rhine, Odra, Danube.
- 3. TopKapi (Uni Bologna) for simulation of the Po river basin
- N.B.: The system is however conceived as "<u>open</u>" allowing any other model to be incorporated through an appropriate <u>model-adapter.</u>

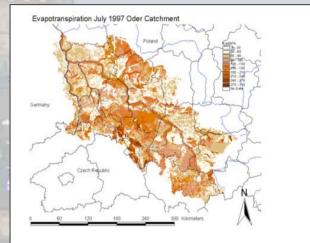


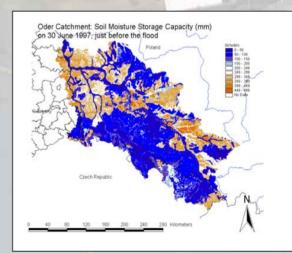


LISFLOOD model









### **Courtesy Joint Research Centre**





### **River routing**

- Lateral inflows into the main river system are calculated by the hydrological model (e.g. HBV).
- The water is subsequently routed along the main river system (e.g. Rhine).
- Within the EFFS river routing is performed with the WL | Delft Hydraulics Saint-Venant model SOBEK.

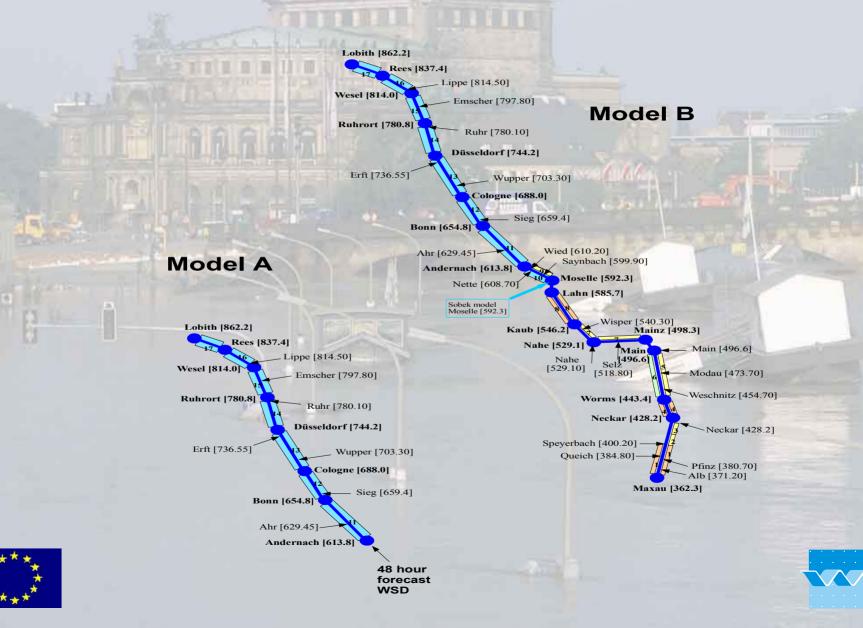
Discharge Q and water level height H at critical sections are calculated.

 Effects of engineering structures such as weirs, locks and bridges are included in the schematisation.





# **River routing**



### **Floodplain inundation modelling**

- Once water overtops a dyke and invades lowlands (e.g. polders), 2-D flood-wave propagation modelling is needed to forecast the extent of the inundation.
  - Inundation modelling within EFFS can be performed by two different models:
  - 1. The 2D inundation of the University of Bristol and JRC (LISFLOOD-FP.
  - 2. The Delft 2D inundation model.



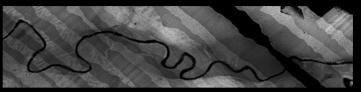


### Inundation Modeling River Severn (UK)

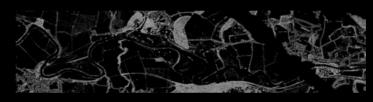
Raw LiDAR data (6 x 3 km domain)

Topography map

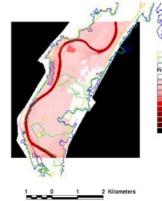
Vegetation height map







Inundation modelling results



Air photo shoreline SAR shoreline (raske algorithm) SAR shoreline (threshold algorith decked water dept(m) 0.01 1.4 1.4 - 2.75 2.79 - 4.18 4.18 - 5.65 5.87 - 6.37

### **Courtesy University of Bristol**

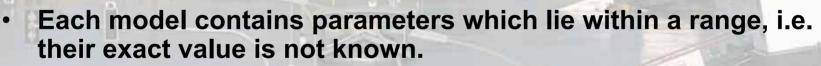




### **Uncertainty**

- Flood forecasting cannot be separated form the problem of the <u>uncertainty</u> inherent to the input, model structure and parameter values.
- Any flood forecasting system is made up by a cascade of models, usually :





Routing

 In addition the inputs (e.g. rainfall) as well as the initial conditions are affected by uncertainty.

Hydrology

 Subsequently the predictions lead to a bandwidth of forecasted values, which may over- or underestimate the actual water levels.





Inundation

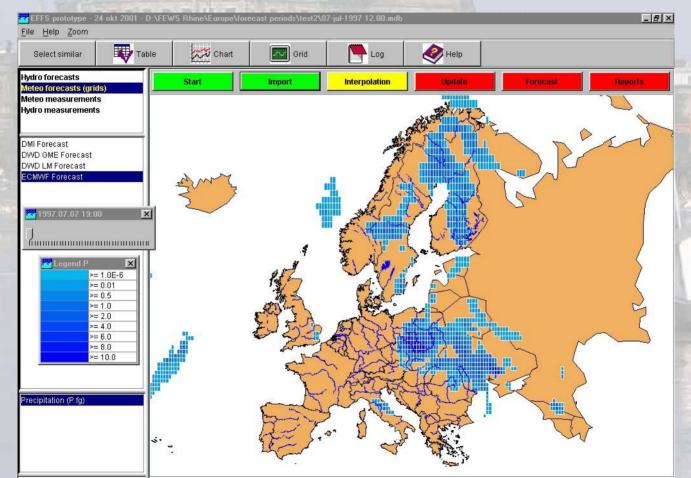
### Model integration: prototype FEWS

- The modeling steps needed in a flood forecasting system are integrated through an integration platform (shell-tool).
- The shell-tool is designed as open and re-usable software system.
- The system is adaptable to different hydrological and hydraulic models through <u>model-adapters</u>.
- The platform is linked to a data-base system.
- Results of various model runs are saved and retrieved subsequently from the DB.
- Within the shell-tool model runs, analysis of results and postprocessing are facilitated.





### **The Open-Architecture Platform**



start forecast 07-07-1997 12:00 simulation period 29-06-1997 14:00 to 17-07-1997 12:00





## Testing of the prototype

- The EFFS is being tested within the frame of the project in a semi-operational fashion by the Dutch institute RIZA on the river Rhine.
- Several hundreds of forecasts have been carried out though direct access to DWD weather forecast data and subsequent running of the model cascades.
- The predicted water levels are compared directly with the ones measured at the German-Dutch border flow measuring station.
- Results of these test-runs will be presented later on in the conference.





## Flood Warning & dissemination

- Once a high water is forecast by the system, decision need to be made if evacuation is necessary.
- False alarms can be as damaging as not issuing a warning at the right moment.
- Decisions stay ultimately with the forecaster and need use of historical records for verification and uncertainty reduction.
- A systematic approach to address this issue is matter of ongoing research.





### Summary

- The outlined system components will be addressed by the project partners through dedicated sessions during this conference.
- Results and applications of various project
   applications will be presented.
- Systematic quantification and handling of the inherent uncertainties on forecast results are a complex issue which needs particular attention from a research point of view.





## **Contributions**

To this presentation have contributed the following people :

- Keith Beven
- Paul Bates
- Erdmann Heise
- Tony Hollingsworth
- Bo Holst
- Michael Hils

- Jaap Kwadijk
- Ad de Roo
- Kai Sattler
- Eric Sprokkereef
- Ezio Todini

The conference organisation would like to wish you a pleasant stay and is looking forward to fruitful discussion!

Thank you very much for your attention.



